

Octonions and the exceptional Lie algebras (and particle physics)

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Division Algebras

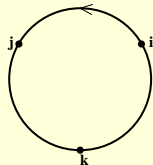
Real Numbers

$$\mathbb{R}$$

Quaternions

$$\mathbb{H} = \mathbb{C} \oplus \mathbb{C}j$$

$$q = (x + yi) + (r + si)j$$



Complex Numbers

$$\mathbb{C} = \mathbb{R} \oplus \mathbb{R}i$$

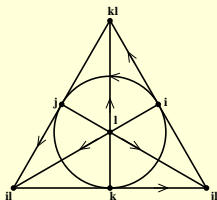
$$z = x + yi$$

Octonions

$$\mathbb{O} = \mathbb{H} \oplus \mathbb{H}l$$

Split Octonions

$$\mathbb{O}' = \mathbb{H} \oplus \mathbb{H}L$$



$$I^2 = J^2 = -U, L^2 = +U$$

Split Division Algebras

$$I^2 = J^2 = -U, L^2 = +U$$

Signature (4, 4):

$$x = x_1 U + x_2 I + x_3 J + x_4 K + x_5 KL + x_6 JL + x_7 IL + x_8 L \implies$$

$$|x|^2 = x\bar{x} = (x_1^2 + x_2^2 + x_3^2 + x_4^2) - (x_5^2 + x_6^2 + x_7^2 + x_8^2)$$

Null elements:

$$|U \pm L|^2 = 0$$

Projections:

$$\left(\frac{U \pm L}{2}\right)^2 = \frac{U \pm L}{2}$$

$$(U + L)(U - L) = 0$$

Definition

A *Lie Group* G is a group that is also a smooth manifold, and on which the group operations are smooth:

$$\begin{aligned} G \times G &\longrightarrow G \\ (X, Y) &\longmapsto X^{-1}Y \end{aligned}$$

Example

$$\begin{aligned} \mathrm{SO}(2) &= \{M \in \mathbb{R}^{2 \times 2} \mid MM^T = I, \det M = 1\} \\ &= \left\{ \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \mid \theta \in \mathbb{R}/2\pi\mathbb{Z} \right\} \cong \mathbb{S}^1 \end{aligned}$$

continuous symmetry groups (rotations)

$$|G| = \# \text{ of parameters}$$

Definition

A *Lie algebra* is a vector space \mathfrak{g} together with a binary operation

$$\begin{aligned}\mathfrak{g} \times \mathfrak{g} &\longrightarrow \mathfrak{g} \\ (x, y) &\longmapsto [x, y]\end{aligned}$$

which is *bilinear* and satisfies

$$\begin{aligned}[x, y] &= -[y, x] \\ [x, [y, z]] + [y, [z, x]] + [z, [x, y]] &= 0\end{aligned}$$

Example

$$\begin{aligned}\mathfrak{so}(3) &= \{A \in \mathbb{R}^{3 \times 3} \mid A^t = -A, \operatorname{tr}(A) = 0\} \\ &= \langle r_x, r_y, r_z \rangle\end{aligned}$$

$$r_z = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \left. \frac{d}{d\theta} \right|_{\theta=0} \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$[r_x, r_y] = r_z$$

infinitesimal symmetries ($\mathfrak{g} = TG|_e$)

(WARNING: physicists use $-i \frac{d}{d\theta}$ to get Hermitian operators.)

$$|\mathfrak{g}| = \dim \mathfrak{g} = \dim TG = |G|$$

Representations

Definition

A *representation of a Lie group* G on a vector space V is a (group) homomorphism $\Pi : G \mapsto GL(V)$.

Definition

A *representation of a Lie algebra* \mathfrak{g} on a vector space V is a (Lie algebra) homomorphism $\rho : \mathfrak{g} \mapsto \mathfrak{gl}(V)$.

(WARNING: The map ρ , the image matrices $\rho(\mathfrak{g})$, and the vector space V are all referred to as “representations of \mathfrak{g} ”, and similarly for G .)

Theorem

(Killing 1888–1890, Cartan 1894)

The (“simple”) Lie groups are the classical groups

A_n	$SU(n+1)$
B_n	$SO(2n+1)$
C_n	$Sp(n)$
D_n	$SO(2n)$

together with the exceptional groups G_2 , F_4 , E_6 , E_7 , and E_8 .

$$SU(n) \equiv SU(n, \mathbb{C})$$

$$SO(n) \equiv SU(n, \mathbb{R})$$

$$Sp(n) \equiv SU(n, \mathbb{H})$$

$$F_4 \equiv SU(3, \mathbb{O})$$

$$G_2 \equiv \text{Aut}(\mathbb{O})$$

$$E_6 \equiv SL(3, \mathbb{O})$$

$$E_7 \equiv Sp(6, \mathbb{O})$$

$$E_8 \equiv ??$$

The Freudenthal–Tits Magic Square

Freudenthal (1964), Tits (1966):

	\mathbb{R}	\mathbb{C}	\mathbb{H}	\mathbb{O}
\mathbb{R}	\mathfrak{a}_1	\mathfrak{a}_2	\mathfrak{c}_3	\mathfrak{f}_4
\mathbb{C}	\mathfrak{a}_2	$\mathfrak{a}_2 \oplus \mathfrak{a}_2$	\mathfrak{a}_5	\mathfrak{e}_6
\mathbb{H}	\mathfrak{c}_3	\mathfrak{a}_5	\mathfrak{d}_6	\mathfrak{e}_7
\mathbb{O}	\mathfrak{f}_4	\mathfrak{e}_6	\mathfrak{e}_7	\mathfrak{e}_8

Vinberg (1966):

$$\begin{aligned}
 & \mathfrak{sa}(3, \mathbb{A} \otimes \mathbb{B}) \oplus \mathfrak{der}(\mathbb{A}) \oplus \mathfrak{der}(\mathbb{B}) \\
 & \mathfrak{der}(\mathbb{H}) = \mathfrak{so}(3); \quad \mathfrak{der}(\mathbb{O}) = \mathfrak{g}_2
 \end{aligned}$$

Goal:

Description as symmetry groups

[Barton & Sudbery (2003), Wangberg (PhD 2007),
 Dray & Manogue (CMUC 2010), Wangberg & Dray (JMP 2013, JAA 2014),
 Dray, Manogue, & Wilson (CMUC 2014), Wilson, Dray, & Manogue (2022)]

The 2 × 2 Magic Square

Barton & Sudbery (2003):

	\mathbb{R}	\mathbb{C}	\mathbb{H}	\mathbb{O}
\mathbb{R}	\mathfrak{d}_1	\mathfrak{a}_1	\mathfrak{b}_2	\mathfrak{b}_4
\mathbb{C}	\mathfrak{a}_1	$\mathfrak{a}_1 \oplus \mathfrak{a}_1$	\mathfrak{d}_3	\mathfrak{d}_5
\mathbb{H}	\mathfrak{b}_2	\mathfrak{d}_3	\mathfrak{d}_4	\mathfrak{d}_6
\mathbb{O}	\mathfrak{b}_4	\mathfrak{d}_5	\mathfrak{d}_6	\mathfrak{d}_8

“Vinberg”:

$$\begin{aligned}
 & \mathfrak{sa}(2, \mathbb{A} \otimes \mathbb{B}) \oplus \mathfrak{so}(\text{Im } \mathbb{A}) \oplus \mathfrak{so}(\text{Im } \mathbb{B}) \\
 & \mathfrak{so}(\text{Im } \mathbb{H}) = \mathfrak{so}(3); \quad \mathfrak{so}(\text{Im } \mathbb{O}) = \mathfrak{so}(7)
 \end{aligned}$$

Unified Clifford algebra description using division algebras

[Kincaid (MS 2012), Kincaid and Dray (MPLA 2014),
Dray, Huerta, & Kincaid (LMP 2014)]

$\mathfrak{so}(3)$

$$P = \begin{pmatrix} z & x - iy \\ x + iy & -z \end{pmatrix}$$

$$= x\sigma_x + y\sigma_y + z\sigma_z$$

$$\implies \det P = -(x^2 + y^2 + z^2)$$

Preserved by $P \mapsto MPM^\dagger$ with $MM^\dagger = 1$. $SU(2)$!

Generated by $P \mapsto AP + PA^\dagger$ with $A + A^\dagger = 0$. $\mathfrak{su}(2)$!

(Weyl) spinor: $\theta \in \mathbb{C}^2$, $\theta \mapsto M\theta$.

$$s_x = -\frac{i}{2}\sigma_x \implies [s_x, s_y] = s_z \implies \mathfrak{su}(2) \cong \mathfrak{su}(3)$$

$$r_x^2 + r_y^2 + r_z^2 = -2I \text{ (spin 1), but } s_x^2 + s_y^2 + s_z^2 = -\frac{3}{4}I \text{ (spin } \frac{1}{2}\text{)}.$$

$\mathfrak{so}(3, 1)$

$$P = \begin{pmatrix} t + z & x - iy \\ x + iy & t - z \end{pmatrix}$$

$$= t\sigma_t + x\sigma_x + y\sigma_y + z\sigma_z$$

group: $P \mapsto MPM^\dagger$ algebra: $P \mapsto AP + PA^\dagger$

$\mathfrak{so}(3, 1)$

$$P = \begin{pmatrix} t + z & x - iy \\ x + iy & t - z \end{pmatrix} \\ = t\sigma_t + x\sigma_x + y\sigma_y + z\sigma_z$$

Rotations (antihermitian!): $(\mathfrak{so} P \mapsto [A, P])$

$$A = i\sigma_x, i\sigma_y, i\sigma_z$$

Boosts (hermitian!): $(\mathfrak{so} P \mapsto \{A, P\})$

$$A = \sigma_x, \sigma_y, \sigma_z$$

$\mathfrak{so}(3, 1)$

Vector in $\mathbb{C}' \oplus \mathbb{C}$

$$P = \begin{pmatrix} Lt + Uz & 1x - iy \\ 1x + iy & Lt - Uz \end{pmatrix}$$
$$= Lt \sigma_t + 1x \sigma_x + iy (-i\sigma_y) + Uz \sigma_z$$

Rotations (antihermitian!): (so $P \mapsto [A, P]$)

$$A = i\sigma_x, i\sigma_y, i\sigma_z$$

Boosts (antihermitian!): (so $P \mapsto [A, P]$)

$$X_L = L\sigma_x, \quad X_{iL} = L\sigma_y, \quad D_L = L\sigma_z$$

$$\mathfrak{so}(3, 1) \cong \mathfrak{sl}(2, \mathbb{C}) \cong \mathfrak{su}(2, \mathbb{C}' \otimes \mathbb{C})$$

Guiding Principle #1

Lie algebras are real!

(signature matters)

$\mathfrak{so}(3, 1)$ has boosts and rotations

	\mathbb{R}	\mathbb{C}	\mathbb{H}	\mathbb{O}
\mathbb{R}'	$\mathfrak{so}(2)$	$\mathfrak{so}(3)$	$\mathfrak{so}(5)$	$\mathfrak{so}(9)$
\mathbb{C}'	$\mathfrak{so}(2, 1)$	$\mathfrak{so}(3, 1)$	$\mathfrak{so}(5, 1)$	$\mathfrak{so}(9, 1)$
\mathbb{H}'	$\mathfrak{so}(3, 2)$	$\mathfrak{so}(4, 2)$	$\mathfrak{so}(6, 2)$	$\mathfrak{so}(10, 2)$
\mathbb{O}'	$\mathfrak{so}(5, 4)$	$\mathfrak{so}(6, 4)$	$\mathfrak{so}(8, 4)$	$\mathfrak{so}(12, 4)$

$$d = 3, 4, 6, 10$$

(1980s: Corrigan, Evans, Fairlie, Manogue, Sudbery)

(1990s: Manogue & Schray)

Summary: 2 × 2 Magic Square

- The algebras in the 2 × 2 magic square are $\mathfrak{su}(2, \mathbb{K}' \otimes \mathbb{K})$.
- Each algebra is generated by the 2 × 2 matrices below, with $p \in \mathbb{K}' \otimes \mathbb{K}$ and $q \in \text{Im}\mathbb{K} + \text{Im}\mathbb{K}'$.

$$D_q = \begin{pmatrix} q & 0 \\ 0 & -q \end{pmatrix}, \quad X_p = \begin{pmatrix} 0 & p \\ -\bar{p} & 0 \end{pmatrix}$$

Idea: rotations/boosts acting on $\mathbb{K}' \oplus \mathbb{K}$:

$$D_i = D_{1i}; D_L = D_{UL}; X_i = X_{iU}; X_L = X_{1L}$$

- The remaining basis elements are of the form

$$D_{i,j} = \begin{pmatrix} i \circ j & 0 \\ 0 & i \circ j \end{pmatrix} = \frac{1}{2} [D_i, D_j]$$

where $i \circ j \doteq k$ over \mathbb{H} , but stands for nesting over \mathbb{O} .

The 3 × 3 Magic Square

	\mathbb{R}	\mathbb{C}	\mathbb{H}	\mathbb{O}
\mathbb{R}'	$\mathfrak{su}(3, \mathbb{R})$	$\mathfrak{su}(3, \mathbb{C})$	$\mathfrak{su}(3, \mathbb{H})$	$\mathfrak{su}(3, \mathbb{O})$
\mathbb{C}'	$\mathfrak{sl}(3, \mathbb{R})$	$\mathfrak{sl}(3, \mathbb{C})$	$\mathfrak{sl}(3, \mathbb{H})$	$\mathfrak{sl}(3, \mathbb{O})$
\mathbb{H}'	$\mathfrak{sp}(6, \mathbb{R})$	$\mathfrak{sp}(6, \mathbb{C})$	$\mathfrak{sp}(6, \mathbb{H})$	$\mathfrak{sp}(6, \mathbb{O})$
\mathbb{O}'	??	??	??	??

Dray & Manogue (2010):

$F_4 \cong SU(3, \mathbb{O})$, $E_{6(-26)} \cong SL(3, \mathbb{O})$ using $SL(2, \mathbb{O}) \cong Spin(9, 1)$

Dray, Manogue, & Wilson (2014): $E_7 \cong Sp(6, \mathbb{O})$

Minimal representation of \mathfrak{e}_8 is adjoint!

Guiding Principle #2

The 3 × 3 structure is broken to 2 × 2.

$$\mathcal{P} = \begin{pmatrix} P & \theta \\ \theta^\dagger & n \end{pmatrix} \quad \mathcal{M} = \begin{pmatrix} M & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{aligned} \mathcal{P} \mapsto \mathcal{M}\mathcal{P}\mathcal{M}^\dagger &\implies P \mapsto MPM^\dagger, \theta \mapsto M\theta \\ \mathcal{P} \mapsto [A, \mathcal{P}] &\implies P \mapsto [A, P], \theta \mapsto A\theta \end{aligned}$$

Idea: 2 × 2 vector and spinor actions at same time!

Example: $\mathcal{M} \in E_6$, $\mathcal{A} \in \mathfrak{e}_6$, $\mathcal{P} \in H_3(\mathbb{O})$

Guiding Principle #2

The 3 × 3 structure is broken to 2 × 2.

$$\mathcal{P} = \begin{pmatrix} P & \theta \\ -\theta^\dagger & n \end{pmatrix} \quad \mathcal{M} = \begin{pmatrix} M & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{aligned} \mathcal{P} \mapsto \mathcal{M}\mathcal{P}\mathcal{M}^{-1} &\implies P \mapsto MPM^{-1}, \theta \mapsto M\theta \\ \mathcal{P} \mapsto [A, \mathcal{P}] &\implies P \mapsto [A, P], \theta \mapsto A\theta \end{aligned}$$

Idea: 2 × 2 adjoint and spinor actions at same time!

Example: $\mathcal{M} \in E_6$, $\mathcal{A} \in \mathfrak{e}_6$, $\mathcal{P} \in \mathfrak{e}_6$ (3 × 3 adjoint action!)

Summary: 3 × 3 Magic Square

- The algebras in the 3 × 3 magic square are $\mathfrak{su}(3, \mathbb{K}' \otimes \mathbb{K})$.
- Each algebra is generated by the 3 × 3 matrices below, with $p \in \mathbb{K}' \otimes \mathbb{K}$ and $q \in \text{Im}\mathbb{K} + \text{Im}\mathbb{K}'$.

$$D_q = \begin{pmatrix} q & 0 & 0 \\ 0 & -q & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad S_q = \begin{pmatrix} q & 0 & 0 \\ 0 & q & 0 \\ 0 & 0 & -2q \end{pmatrix}, \quad X_p = \begin{pmatrix} 0 & p & 0 \\ -\bar{p} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$Y_p = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & p \\ 0 & -\bar{p} & 0 \end{pmatrix}, \quad Z_p = \begin{pmatrix} 0 & 0 & -\bar{p} \\ 0 & 0 & 0 \\ p & 0 & 0 \end{pmatrix}$$

- The remaining basis elements can be chosen to be of the form

$$D_{i,j} = \begin{pmatrix} i \circ j & 0 & 0 \\ 0 & i \circ j & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

where $i \circ j \doteq k$ over \mathbb{H} , but stands for nesting over \mathbb{O} . **TRIALITY!**

Subalgebras

- All algebras in both magic squares are subalgebras of \mathfrak{e}_8 !
- $\mathfrak{e}_{8(-24)} = \mathfrak{so}(12, 4) + \mathbf{128}$.
- The **128** is a Majorana–Weyl spinor rep of $\mathfrak{so}(12, 4)$.
- The **128** contains spinor reps of each 2×2 algebra.

Particle Physics

Fundamental particles (leptons and quarks) are Lorentz ($\mathfrak{so}(3,1)$) *spinors*, and carry representations of electromagnetism (“charge”; $\mathfrak{u}(1)$), the weak interaction ($\mathfrak{su}(2)_L$), and the strong interaction (“color”; $\mathfrak{su}(3)$).

Mediators (photons, vector bosons, gluons) are Lorentz *vectors*, and carry (adjoint?) representations of the interactions.

Want simultaneous representations of the Lorentz group $SO(3,1)$ and the Standard Model group $U(1) \times SU(2)_L \times SU(3)$.

Guiding Principle #3

All representations live in \mathfrak{e}_8 !

$$\mathfrak{e}_{8(-24)} = \mathfrak{so}(12, 4) + \text{spinors}$$

$$\mathfrak{so}(12, 4) \supset \mathfrak{so}(3, 1) + \mathfrak{so}(7, 3) + \mathfrak{so}(2)$$

$$\supset \mathfrak{so}(3, 1) + \mathfrak{so}(4) + \mathfrak{so}(3, 3) + \mathfrak{so}(2)$$

$$\supset \mathfrak{so}(3, 1) + \mathfrak{su}(2)_L + \mathfrak{su}(2)_R + \mathfrak{su}(3)_c + \mathfrak{u}(1) + \mathfrak{so}(2)$$

SUMMARY

Lie algebras are real!
The 3 × 3 structure is broken to 2 × 2.
All representations live in \mathfrak{e}_8 !

$$\mathfrak{e}_{8(-24)} = \mathfrak{so}(12, 4) + \text{spinors}$$

$$\mathfrak{so}(12, 4) \supset \mathfrak{so}(3, 1) \oplus \mathfrak{su}(3) \oplus \mathfrak{su}(2) \oplus \mathfrak{u}(1) \oplus \mathbb{C}$$

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