

If f, D, M are forms on N

Then:
$$F^*f = f \circ F$$

 $F^* \sigma (\vec{v}) = \sigma(F_* \vec{v})$
 $F^* \sigma (\vec{v}, \vec{\omega}) = \sigma(F_* \vec{v}, F_* \vec{\omega})$

"pull back"

.: in practice, "use what you know"

$$Ex: M = \{g = ronst\}$$

 $\Rightarrow dg = 0$

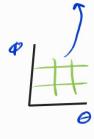
Example: (Stereographic Projection)

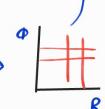
$$M = \mathcal{F}^{2}$$

$$M = \mathcal{S}^2$$
 $(\theta, \phi) \mapsto Q$
 $N = xy - plane$ $(R, \phi) \mapsto P$









In practice, just need relationship between R & O:

$$\frac{R}{\Gamma} = \frac{\Gamma \sin \theta}{\Gamma + \Gamma \cos \theta}$$

$$\Rightarrow R = \frac{\Gamma \sin \theta}{1 + \cos \theta} = \frac{2 \Gamma \sin \theta}{1 + (2 \cos^2 \theta - 1)} = \frac{1}{\Gamma \cos \theta}$$

$$\Rightarrow dR = \frac{\Gamma d\theta}{1 + \cos \theta}$$

Line Integrals

Idea: Just do it!

Theory :

$$\alpha': [0,2\pi] \to \mathbb{R}^{2}$$

$$\beta \mapsto (\Gamma(uS\Theta, \Gamma Sin\Theta))$$
Basis of TR is $\hat{e}:$

$$\hat{e}[f(\theta)] = \frac{df}{d\theta}$$

$$\Rightarrow \alpha_{*}(\hat{e}) = \frac{dG}{d\theta} = -\Gamma Sin\Theta \hat{x} + \Gamma(uS\Theta) = \Gamma \hat{\theta}$$

$$\Rightarrow \frac{dG}{d\theta}[g(x,y)] = \alpha_{*}\hat{e}[g]$$

$$= \frac{d}{d\theta}[g(x(\theta))] = \frac{\partial g}{\partial x} \frac{dx}{d\theta} + \frac{\partial g}{\partial y} \frac{dy}{d\theta}$$

$$= \frac{\partial g}{\partial x} \Gamma Sin\Theta + \frac{\partial g}{\partial y} \Gamma CuS\Theta$$

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