

# Integration

Recall:  $f \in \mathcal{A}^0(\mathbb{R}^3)$ ,  $F \in \mathcal{A}^1(\mathbb{R}^3)$

$$\begin{aligned} \Rightarrow \quad *f &= f dV & \nabla f &= df = \vec{\nabla} f \cdot d\vec{r} \\ F &= \vec{F} \cdot d\vec{r} & \nabla \times F &= *dF = \vec{\nabla} \times \vec{F} \cdot d\vec{r} \\ *F &= \vec{F} \cdot d\vec{A} & \nabla \cdot F &= \nabla \cdot \vec{F} \cdot dV \end{aligned}$$

$$\begin{aligned} \Rightarrow \quad df &= \vec{\nabla} f \cdot d\vec{r} \\ dF &= \vec{\nabla} \times \vec{F} \cdot d\vec{A} \\ d*F &= \vec{\nabla} \cdot \vec{F} dV \end{aligned}$$

FT for gradient:  $\int_C \vec{\nabla} f \cdot d\vec{r} = f|_A^B$

Stokes' Thm:  $\int_S \vec{\nabla} \times \vec{F} \cdot d\vec{A} = \oint_C \vec{F} \cdot d\vec{r}$

Divergence Thm:  $\int_V \vec{\nabla} \cdot \vec{F} dV = \oint_S \vec{F} \cdot d\vec{A}$

$$\int_C df = \int_C f \frac{\partial}{\partial x}$$

$$\int_S dF = \int_S F$$

$$\int_V d*F = \int_V *F$$

$$\therefore \int_R d\alpha = \int_{\partial R} \alpha$$

Stokes' Theorem

for any  $\alpha \in \mathcal{A}^p$

"outward" orientation of boundary is tricky if  $S \neq \emptyset$