

# Example: Spherical Coordinates

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$$\vec{r} = r \hat{r} \Rightarrow d\vec{r} = dr \hat{r} + r d\hat{r}$$

But  $d\vec{r} = dr \hat{r} + r d\theta \hat{\theta} + r \sin\theta d\phi \hat{\phi}$

$$\Rightarrow d\hat{r} = d\theta \hat{\theta} + \sin\theta d\phi \hat{\phi}$$

Furthermore,

$$d\hat{\theta} \cdot \hat{r} = -d\hat{r} \cdot \hat{\theta} = -d\theta$$

$$d\hat{\phi} \cdot \hat{r} = -d\hat{r} \cdot \hat{\phi} = -\sin\theta d\phi$$

$$d\hat{\theta} \cdot \hat{\phi} = -d\hat{\theta} \cdot \hat{\phi} =: -\alpha$$

$$\therefore \begin{aligned} d\hat{\theta} &= -d\theta \hat{r} + \alpha \hat{\phi} \\ d\hat{\phi} &= -\sin\theta d\phi \hat{r} - \alpha \hat{\theta} \end{aligned}$$

To find  $\alpha$ , need  $d^2 \vec{r} = \vec{0}$ :

$$\begin{aligned} d(d\vec{r}) &= -dr \wedge d\hat{r} + dr \wedge d\theta \hat{\theta} - r d\theta \wedge d\hat{\theta} \\ &\quad + \sin\theta dr \wedge d\phi \hat{\phi} + r \cos\theta d\theta \wedge d\phi \hat{\phi} \\ &\quad - r \sin\theta d\phi \wedge d\hat{\theta} \end{aligned}$$

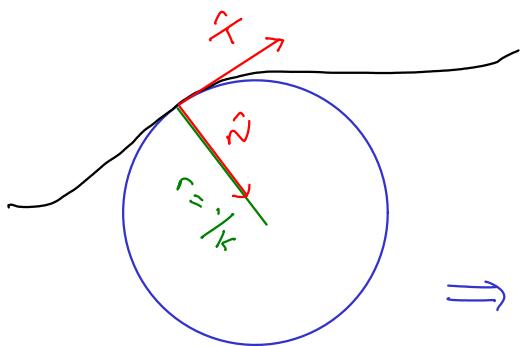
$$\begin{aligned} &= -dr \wedge d\theta \hat{\theta} + dr \wedge d\phi \hat{\phi} - \cancel{\sin\theta dr \wedge d\phi \hat{\phi}} \\ &\quad - r d\theta \wedge \alpha \hat{\phi} + \cancel{\sin\theta dr \wedge d\theta \hat{\theta}} \\ &\quad + r \cos\theta d\theta \wedge d\phi \hat{\phi} + r \sin\theta d\phi \wedge \alpha \hat{\theta} \end{aligned}$$

$$\begin{aligned} &= 0 \Rightarrow d\phi \wedge \alpha = 0 \\ &\quad d\theta \wedge \alpha = \cos\theta d\theta \wedge d\phi \end{aligned}$$

$$\Rightarrow \alpha = \cos\theta d\phi$$

# Curvature of a Curve

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$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{ds}{dt} \hat{T} = v \hat{T}$$

$$\Rightarrow d\vec{r} = ds \hat{T} = v dt \hat{T}$$

$$\text{But } \hat{T} \cdot \hat{T} = 1$$

$$\Rightarrow d\hat{T} \cdot \hat{T} = 0$$

$$\Rightarrow d\hat{T} = k ds \hat{N} = kv dt \hat{N}$$

principal unit  
normal

$$\begin{aligned}\therefore d\vec{v} &= dv \hat{T} + v d\hat{T} \\ &= dv \hat{T} + kv ds \hat{N} \\ &= dv \hat{T} + kv^2 dt \hat{N}\end{aligned}$$

↑                              ↑                              ↑  
 linear                      centripetal              acceleration  
 acceleration      is      is      is  
 is       $\frac{dv}{dt}$        $k v^2$        $\frac{v^2}{r}$   
 $\underline{k = \text{curvature}}$

$$\begin{aligned}\therefore k ds &= d\hat{T} \cdot \hat{N} \\ &= -d\hat{N} \cdot \hat{T}\end{aligned}$$

# Curvature of Surfaces

SWBQ: Give me a surface

A surface in  $\mathbb{R}^3$  is  $\{f = \text{const}\}$

↑  
use as  $x^3$

∴ choose orthonormal basis  $\{\hat{e}_1, \hat{e}_2, \hat{n}\}$

∴ curvature in  $\hat{e}_3$  direction is  $\hat{e}_3$

$$\begin{aligned} k ds &= -d\hat{n} \cdot \hat{e}_3 \\ &= -d\hat{e}_3 \cdot \hat{e}_3 \\ &= +\omega_{3i} \end{aligned}$$

On surface  $\Rightarrow x^3 = \text{const}$

$$\Rightarrow dx^3 = 0 \Rightarrow \Gamma^3 = 0$$

$$\therefore d\cancel{\Gamma^3} + \omega^3_1 \wedge \Gamma^1 + \omega^3_2 \wedge \Gamma^2 = 0$$

$$\text{But } \omega^3_{ij} = \Gamma^3_{ij}, \Gamma^3 = \Gamma^3_{11} \Gamma^1 + \Gamma^3_{12} \Gamma^2 + \Gamma^3_{13} \cancel{\Gamma^3}$$

$$\Rightarrow \Gamma^3_{12} \Gamma^2 \wedge \Gamma^1 + \Gamma^3_{21} \Gamma^1 \wedge \Gamma^2 = 0$$

$$\Rightarrow \Gamma^3_{12} = \Gamma^3_{21}$$

∴  $S = (-\Gamma^3_{ij})$  is symmetric

shape  
operator

eigenvalues = principal curvatures  
(max & min)

trace = mean curvature

determinant = Gauss curvature