Preliminary Design Specifications for the Windlite 10 kW DC Wind Turbine

SYSTEM

Type Configuration

Rotor Diameter

PERFORMANCE PARAMETERS

Rated Electrical Power Wind Speed

- cut-in
- Furling (high wind)

peak (survival)
 Calculated Annual Output
 @ 100 % availability

ROTOR

Type of Hub Rotor Diameter Swept Area Number of Blades Rotor Speed @ rated wind speed Location Relative to Tower Rotation

BLADE

Length Material

Airfoil (type) Twist Root Chord Tip Chord Over speed Device Hub Attachment

GENERATOR

Type Min. Ambient Temp. Voltage (V) kW @ Rated Wind Speed kW @ Peak Continuous Speed RPM (nominal) Winding Configuration Insulation Enclosure Frame Size Mounting

<u>YAW SYSTEM</u> Normal

Normai

59.5 m/s 24,093 kWh (25m) 27,878 kWh (37m)

Rigid 7.0 m 38.5 m² 3 230 rpm Upwind CW When Looking Downwind

Stand Alone Battery Charger

Furling Tail

@hub height

9.7 kW @10.5 m/s

7.0 m

4.0 m/s

18 m/s

Direct Drive, Horizontal Axis, Upwind

3.4 m
Resin Transfer Molded or
Wood Epoxy
NREL 822,823
10
500 mm
207 mm
Horizontal Furling
Partially Imbedded Root Bolts

Permanent Magnet -40°c 100-300 VRMS Variable Rectified to 120 V DC 9.7 kW 10.5 kW 230 @ Rated Power Ungrounded Wye Stator Class F Totally Enclosed Air Over (TEAO) Custom Direct mount to Yaw Tube

Free, rotates 360 degrees

DRIVE TRAIN TOWER INTERFACE

Structural Electrical Turntable Bearing & Plate Adapter Slip Ring Assembly

TOWER

Туре

Tower Height Options

Options 18.3 FOUNDATION

Туре

CONTROL SYSTEM

Type Enclosures Galvanized Guyed, Tubular or Self

Self Supporting Lattice 25 m (82 ft) 18.3 m (60 ft), 30.5 m (100 ft), 37 m (121 ft)

Concrete or special pad

Digital Signal Processor (DSP) Based NEMA 1, NEMA 4 (optional)

PROTECTION FEATURES

- Field Current Limiting
- Power Converter Output Protection
- DC Bus Current Limiting
- DC Bus Over Voltage Protection
- Battery Voltage Regulation
- Power Converter Overload Protection
- Power Switches Thermal Cutout
- Stator Current Limit
- Stator Imbalance
- Generator Ground Fault
- Generator Thermal Cutout
- Failed Rectifier Diodes Detection

ROTOR SPEED CONTROL

Passive	Rotor yaw angle increases with increased wind
	velocity
Normal Start up	Aerodynamic, electrical boost if necessary
Furling / Over Speed Control	Drive Train offset rotates rotor out of wind-
	Furling

APPROXIMATE SYSTEM DESIGN WEIGHTS Tower 825 kgs

Tower825 kgsRotor & Drive Train300 kgs

DESIGN LIFE: 20 Years

DESIGN STANDARDS: Applicable Standards, AWEA, EIA and IEC **DOCUMENTATION:** Installation Guide and Operation & Maintenance Manual

SCHEDULED MAINTENANCE: Annual or after severe events.



<u>NOTE 1</u>: Atlantic Orient Corporation, Windlite Corporation, and their affiliates are constantly working to improve their products, therefore, product specifications are subject to change without notice.

NOTE 2: Power curves show typical power available at the controller based on a combination of measured and calculated data. Annual energy is calculated using power curves and a Rayleigh wind speed distribution. Energy production may be greater or lesser dependent upon actual wind resources and site conditions, and will vary with wind turbine maintenance, altitude, temperature, topography and the proximity to other structures including wind turbines.

REV. March 2000