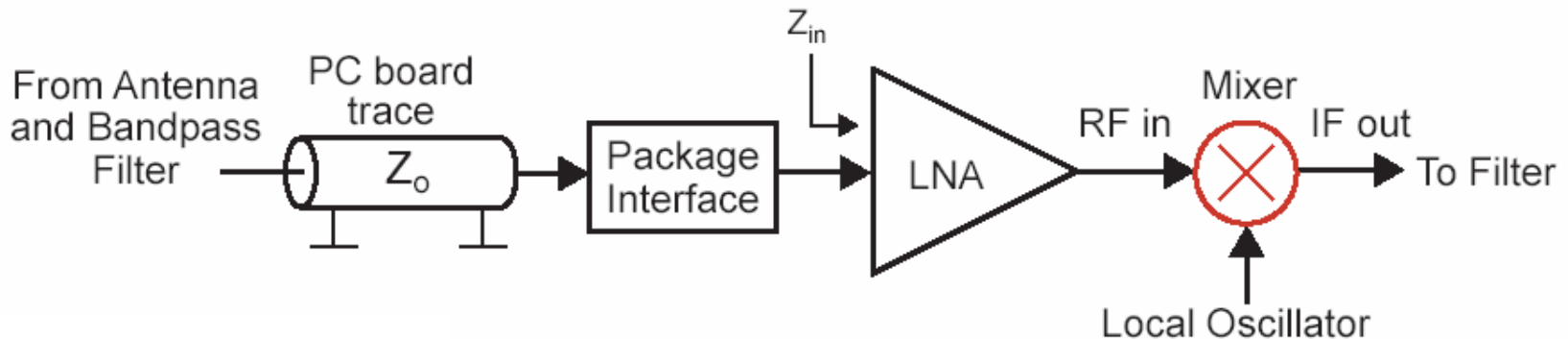


# Mixer Design Overview

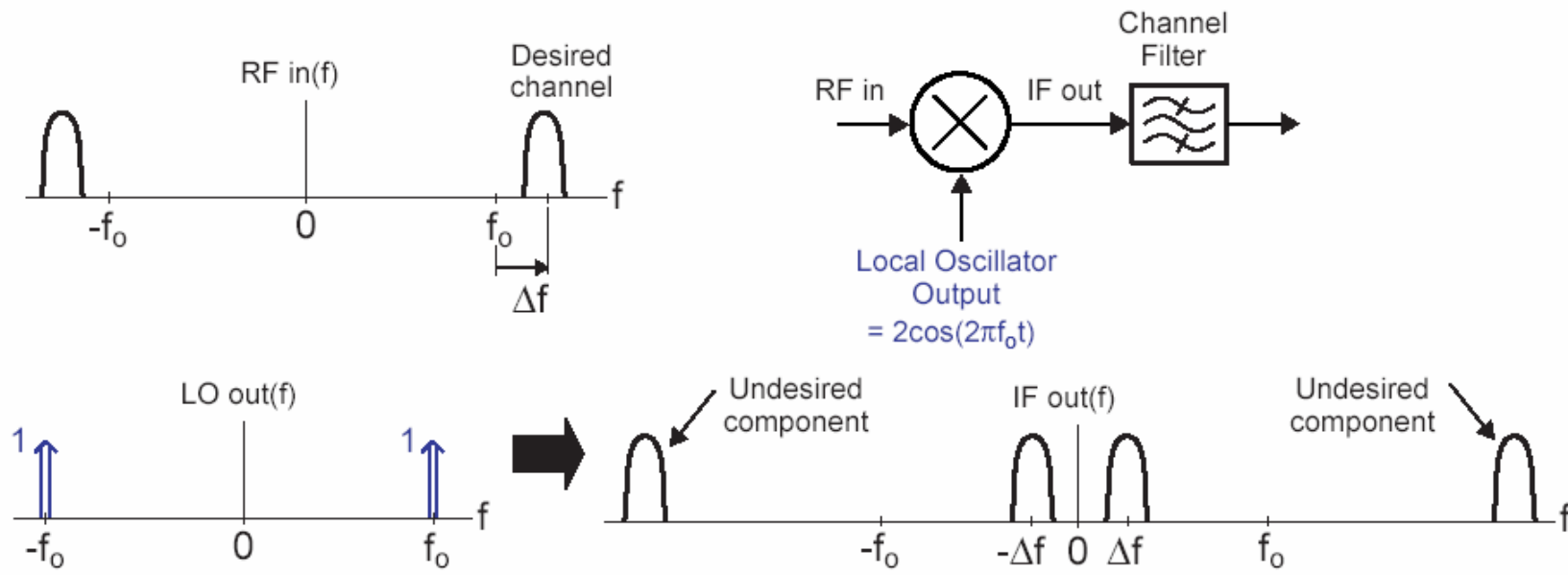


- ❑ **Noise Figure – impacts receiver sensitivity**
- ❑ **Linearity (IIP3) – impacts receiver blocking performance**
- ❑ **Conversion gain – lowers noise impact of following stages**
- ❑ **Power match – want maximize voltage gain rather than power match for integrated designs**
- ❑ **Power – want low power dissipation**
- ❑ **Isolation – want to minimize interaction between the RF, IF, and LO ports**
- ❑ **Sensitivity to process/temp variations – need to make it manufacturable in high volume**

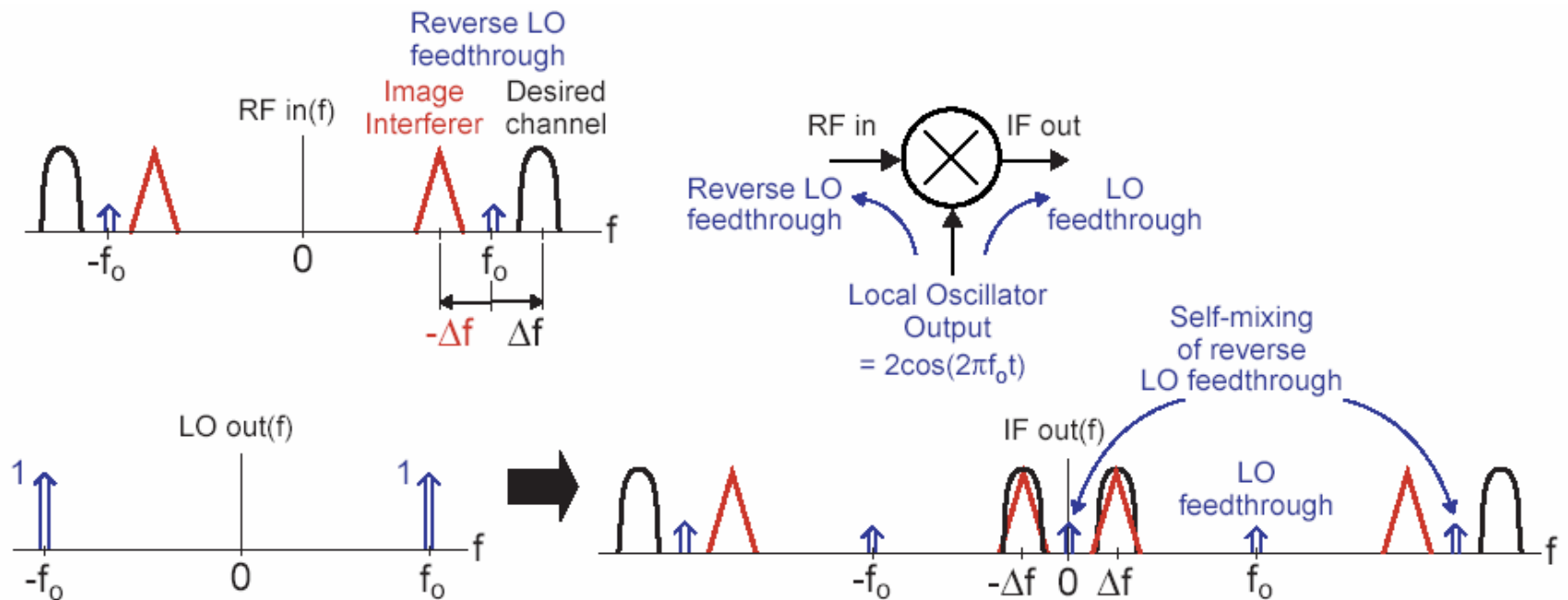
# Types of Mixer

- ❑ **Multiplication through device non-linearity**
- ❑ **Multiplication through switching**
  - **Active mixers**
  - **Passive mixers**

# Ideal Mixer Behavior

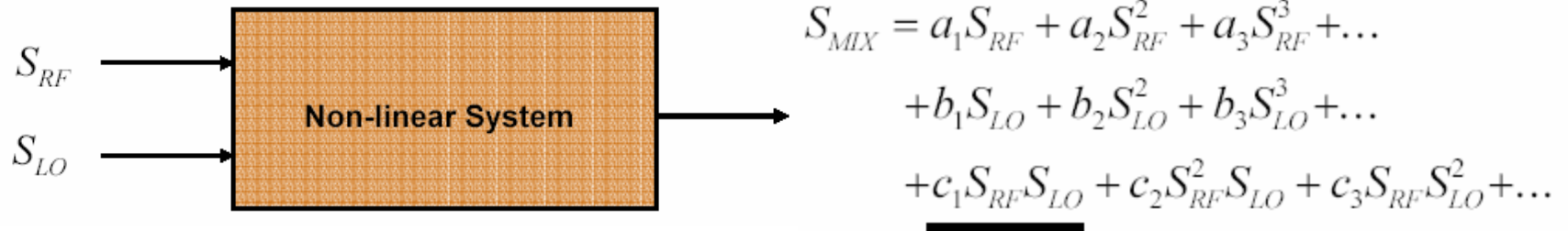


# Non-Ideality in Mixers



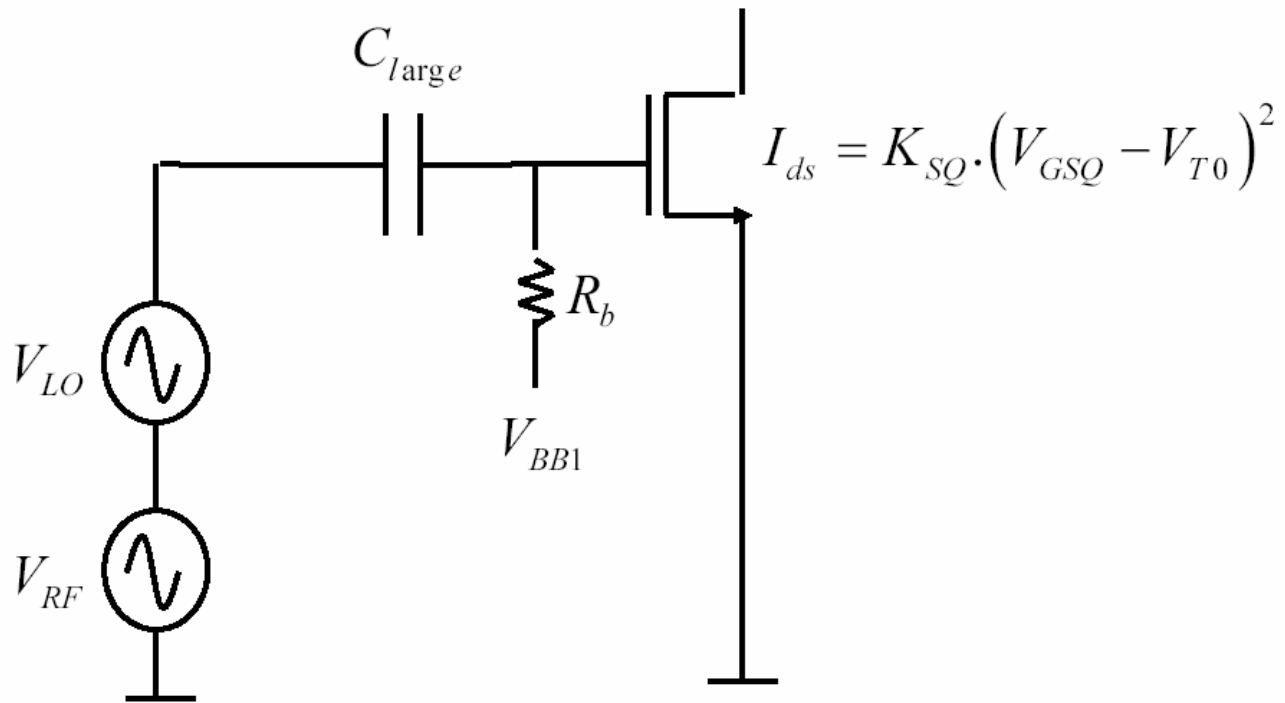
- ❑ Image problem
- ❑ LO feedthrough
- ❑ Self mixing due to reverse LO feedthrough

# Mixer Based on Non-Linearity



- ❑ Drain current of an MOSFET exhibits a square dependence on gate overdrive
- ❑ Collector current of an BJT exhibits an exponential dependence on base-emitter voltage drive

# Single-Device Mixer Using MOSFET (Square-Law Mixer)

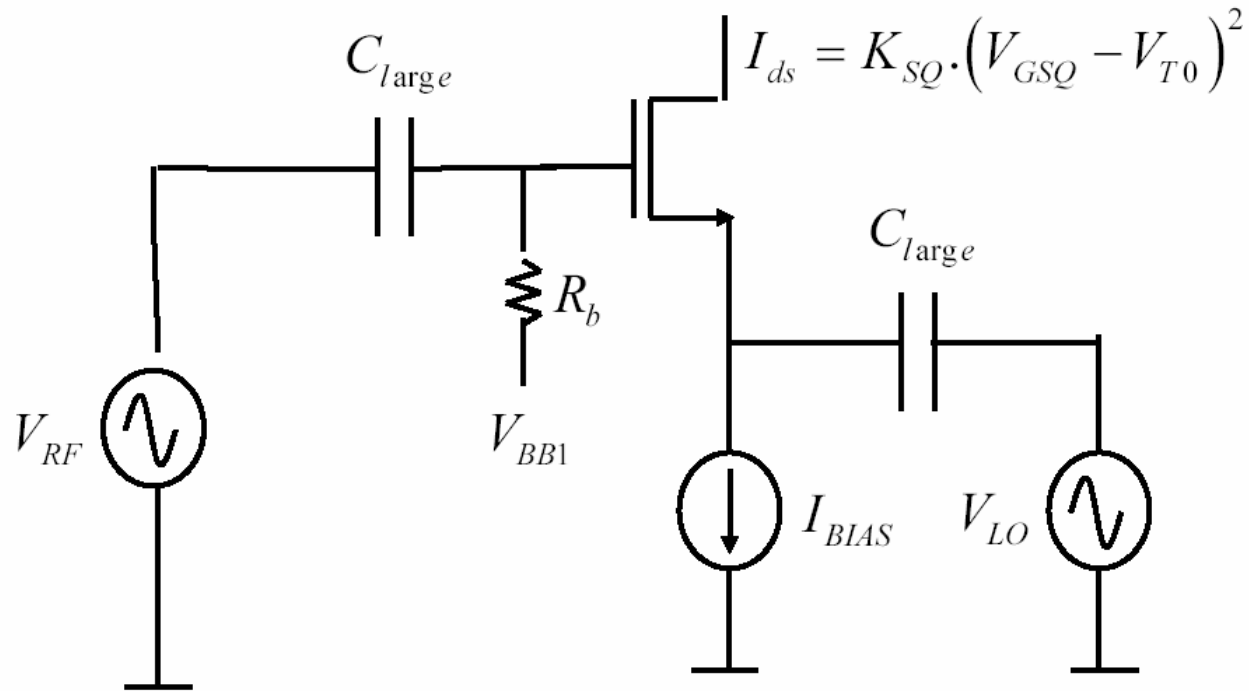


$$I_{ds} = K_{SQ} \cdot (V_{bias} + V_{RF} + V_{LO} - V_{T0})^2$$

$$= K_{SQ} \cdot \left\{ (V_{bias} - V_{T0})^2 + (V_{RF} + V_{LO})^2 + 2(V_{bias} - V_{T0}) \cdot (V_{RF} + V_{LO}) \right\}$$

$$i_{ds}(\omega_{LO} \pm \omega_{RF}) = K_{SQ} \cdot V_{RF} \cdot V_{LO} \left\{ \boxed{\text{Cos}(\omega_{LO} - \omega_{RF})t} + \text{Cos}(\omega_{LO} + \omega_{RF})t \right\}$$

# Practical Configuration for Single-Device Mixer

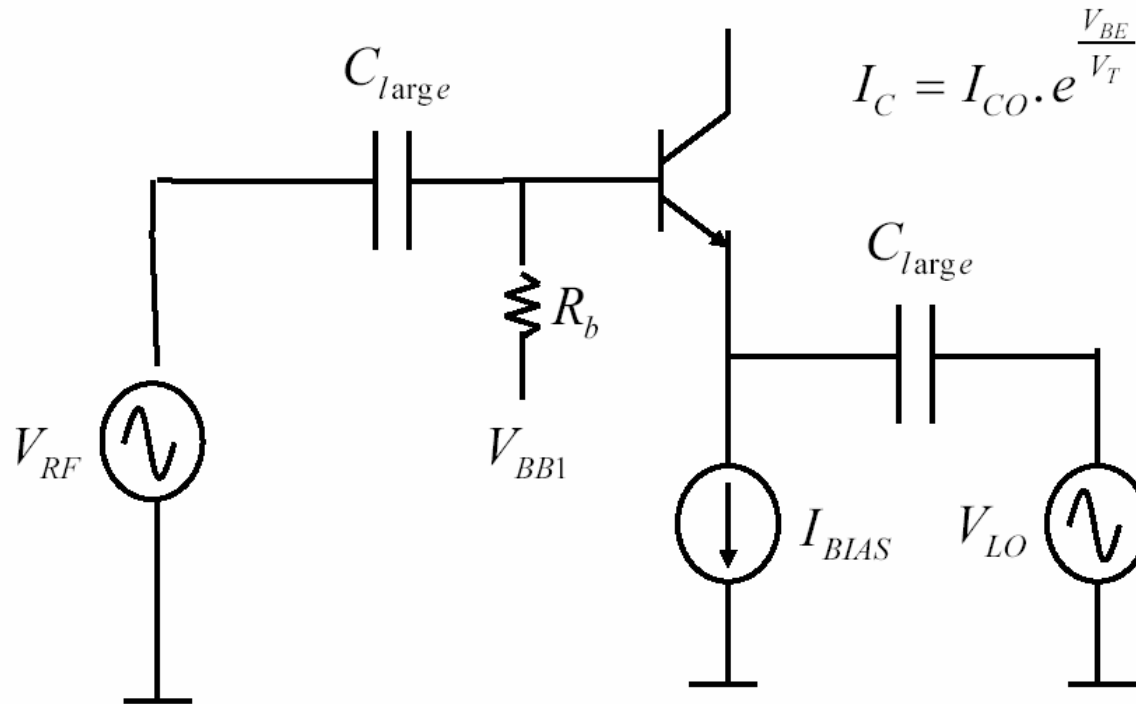


$$i_{ds}(\omega_{LO} - \omega_{RF}) = .K_{SQ} \cdot V_{RF} \cdot V_{LO} \cdot \text{Cos}(\omega_{LO} - \omega_{RF})t$$

$$\text{Transconductance - conversion - gain} = G_c = \frac{i_{ds}(\omega_{IF} = \omega_{LO} - \omega_{RF})}{V_{RF}(\omega_{RF})}$$

$$= K_{SQ} \cdot V_{LO} = \frac{\mu C_{ox} W}{2L} \cdot V_{LO}$$

# Single-Device Mixer Using BJT



$$I_C = I_{CQ} \cdot e^{\frac{V_{RF} - V_{LO}}{V_T}} = I_{CQ} \cdot \left\{ 1 + \left( \frac{V_{RF} - V_{LO}}{V_T} \right) + \left( \frac{V_{RF} - V_{LO}}{V_T} \right)^2 + \dots \right\}$$

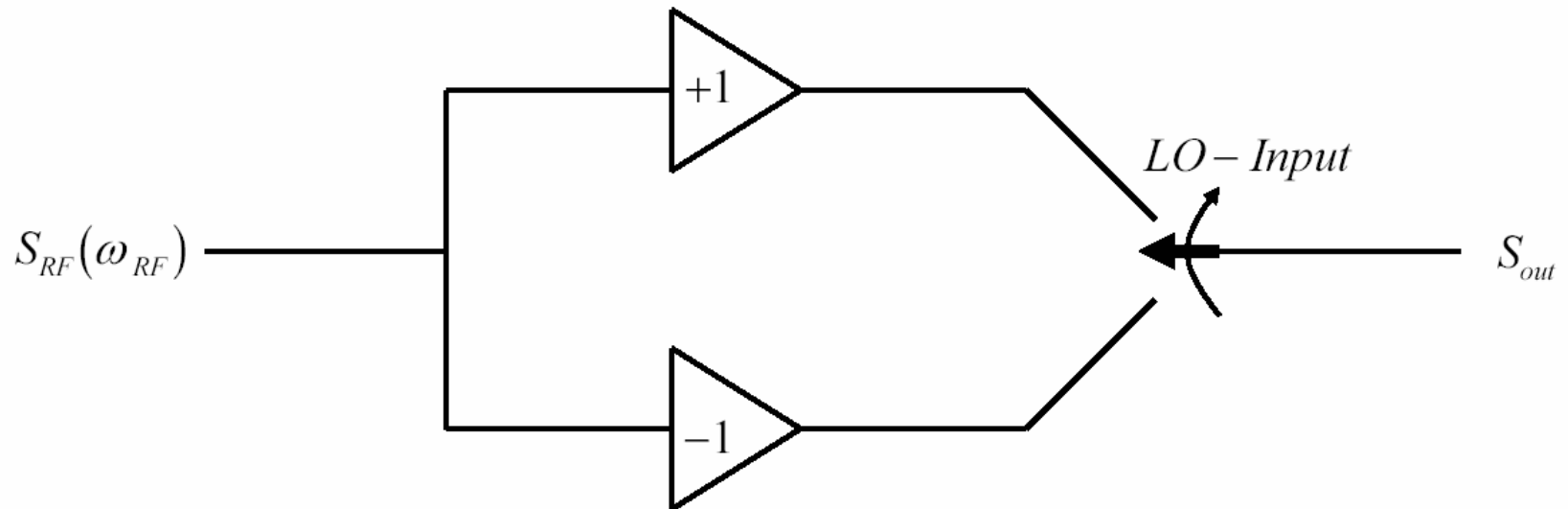
$$\text{Transconductance-conversion-gain} = G_c = \frac{i_c(\omega_{IF} = \omega_{LO} - \omega_{RF})}{V_{RF}(\omega_{RF})} = \frac{I_{CQ}}{V_T^2} \cdot V_{LO}$$



# Design Considerations for Mixer Based on Device Non-Linearity

- ❑ **Design simplicity**
- ❑ **Noise Figure**
  - The square law MOSFET mixer can be designed to have very low noise figure
- ❑ **Linearity**
  - By operating the square law MOSFET mixer in the square law region the linearity of the mixer can be improved considerably
  - BJT mixer is less linear as it produces a host of non-linear components due to the exponential nature of the BJT mixer
- ❑ **Power Dissipation**
  - Very low power dissipation due to single device operation
- ❑ **Power Gain**
  - Reasonable power gain can be achieved
- ❑ **Isolation**
  - Poor isolation from LO to RF port – by far the biggest short coming

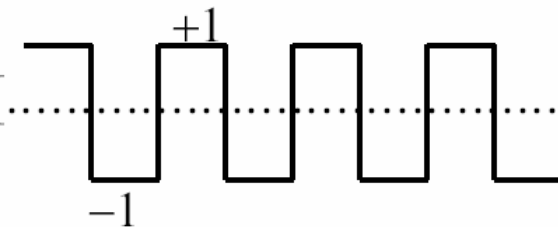
# Mixing Through Switching



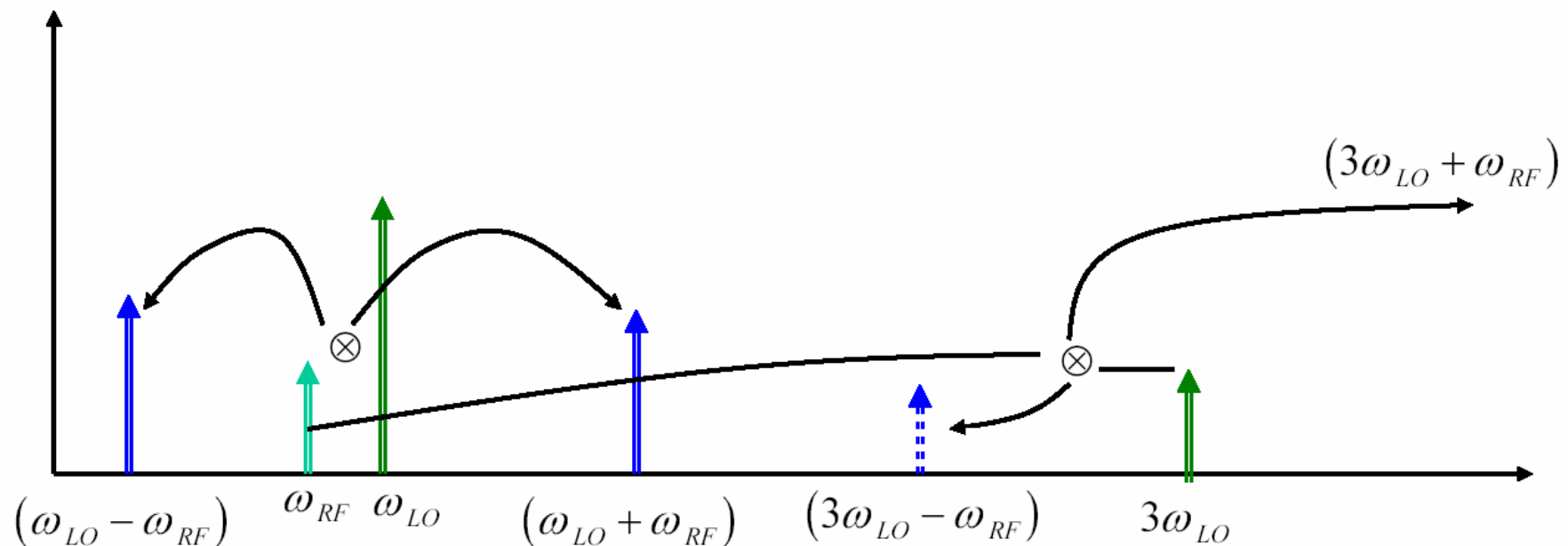
$$S_{out} = S_{RF} \cdot \text{Cos}(\omega_{RF}t) \otimes \left\{ \dots \begin{array}{c} +1 \\ \text{---} \\ -1 \end{array} \dots \right\}$$

$$S_{out} = S_{RF} \cdot \text{Cos}(\omega_{RF}t) \otimes \left\{ \frac{4}{\pi} \text{Cos}(\omega_{LO}t) - \frac{4}{3\pi} \text{Cos}(3\omega_{LO}t) + \frac{4}{5\pi} \text{Cos}(5\omega_{LO}t) - \dots \right\}$$

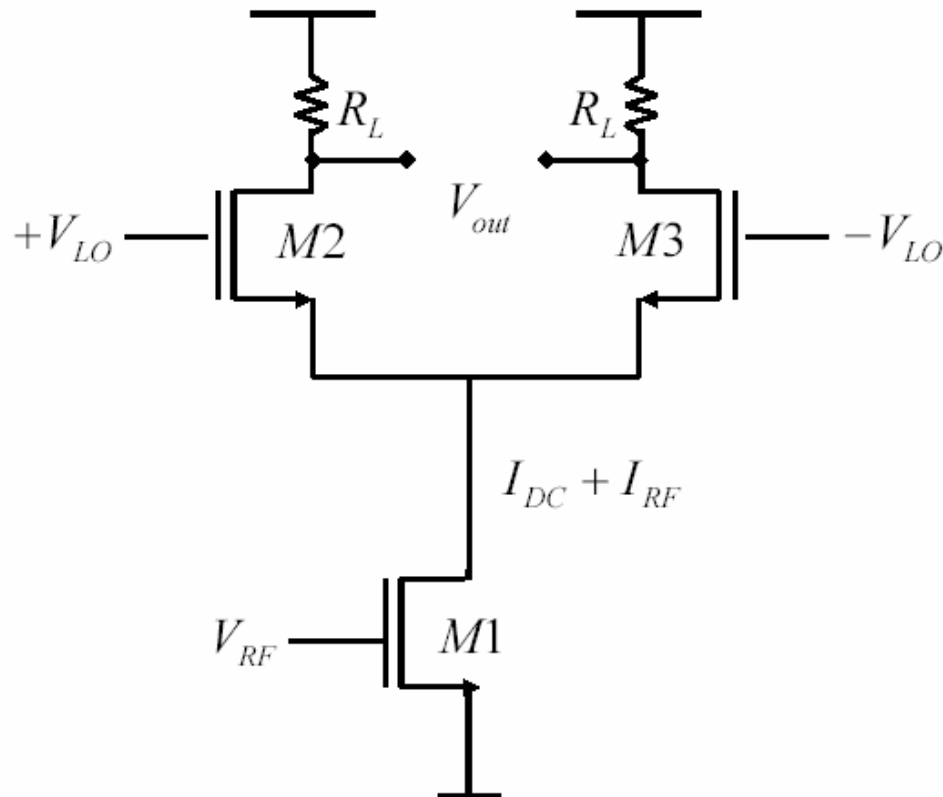
# Spectral Components Due to Mixing

$$S_{out} = S_{RF} \cdot \text{Cos}(\omega_{RF}t) \otimes \left\{ \dots \begin{array}{c} \text{+1} \\ \text{---} \\ \text{-1} \end{array} \dots \right\}$$


$$S_{out} = S_{RF} \cdot \text{Cos}(\omega_{RF}t) \otimes \left\{ \frac{4}{\pi} \text{Cos}(\omega_{LO}t) - \frac{4}{3\pi} \text{Cos}(3\omega_{LO}t) + \frac{4}{5\pi} \text{Cos}(5\omega_{LO}t) - \dots \right\}$$

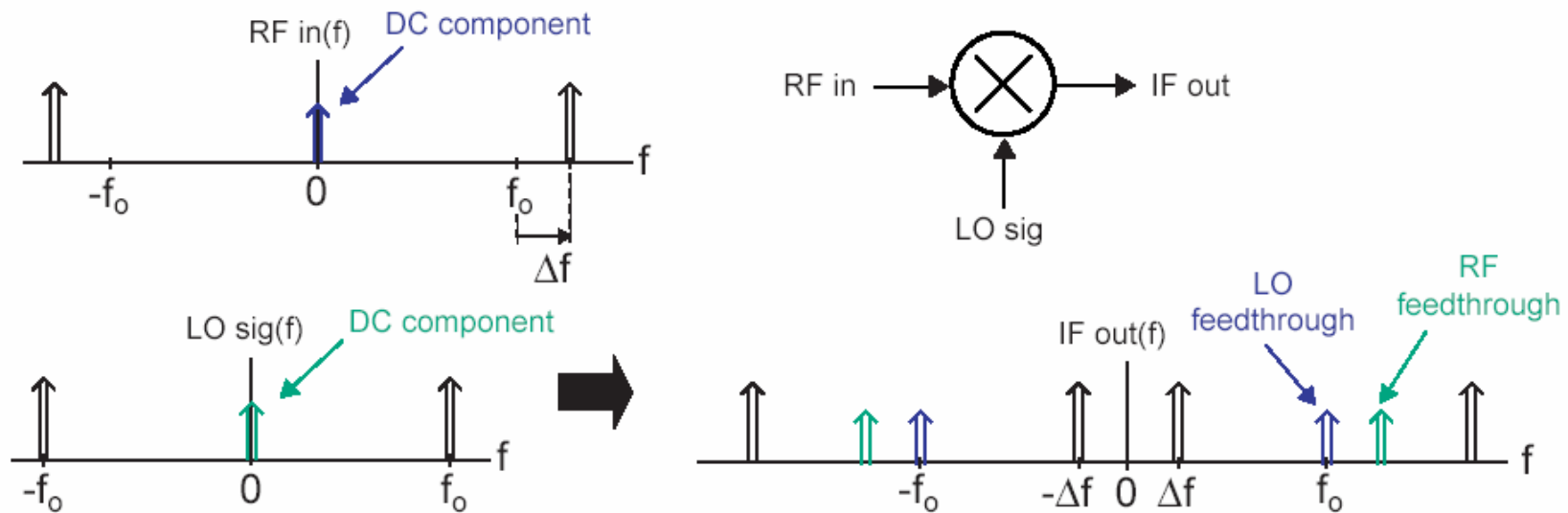


# Simple Switching Mixer (Single-Balanced Mixer)



- ❑  $M1$  acts as a transconductance to convert the RF voltage signal to a current
- ❑  $M2$  and  $M3$  commute the current between the two output branches.

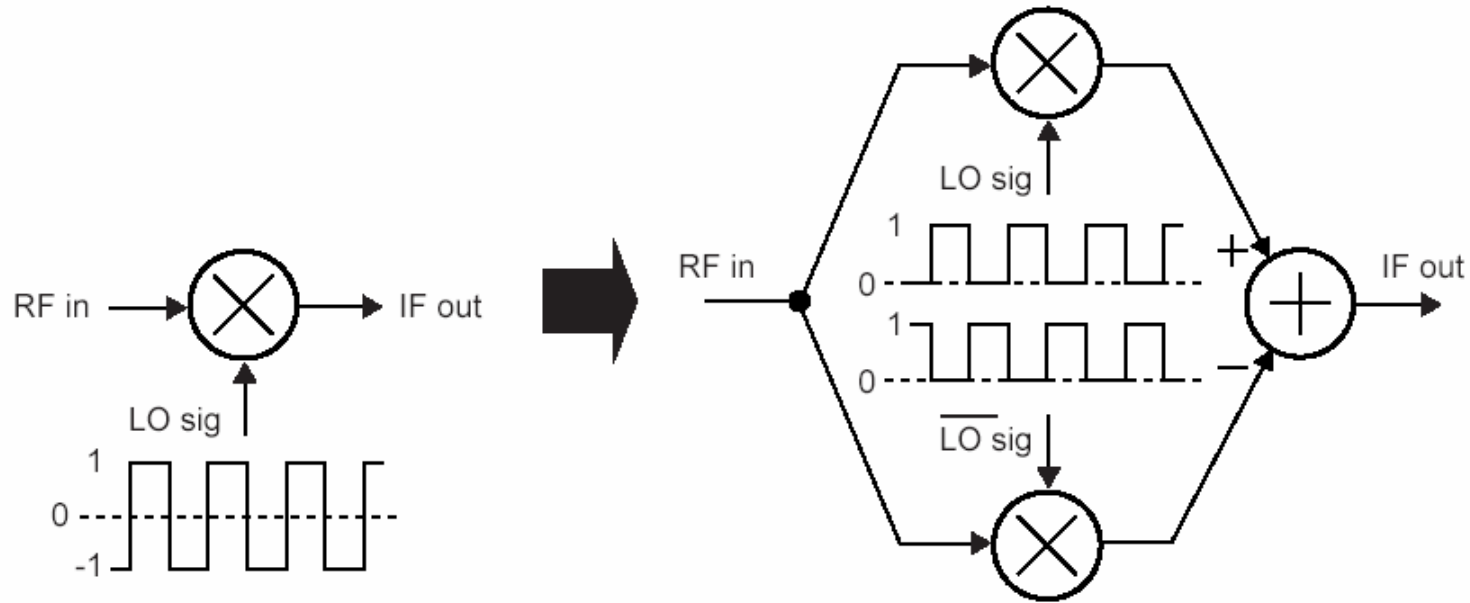
# The Issue of Balance in Mixers



- A balanced signal is defined to have a zero DC component
- Mixers have two signals of concern with respect to this issue – LO and RF signals
  - Unbalanced RF input causes LO feedthrough
  - Unbalanced LO signal causes RF feedthrough
- Issue – transistors require a DC bias

# Achieving Balanced LO Signal with DC Biasing

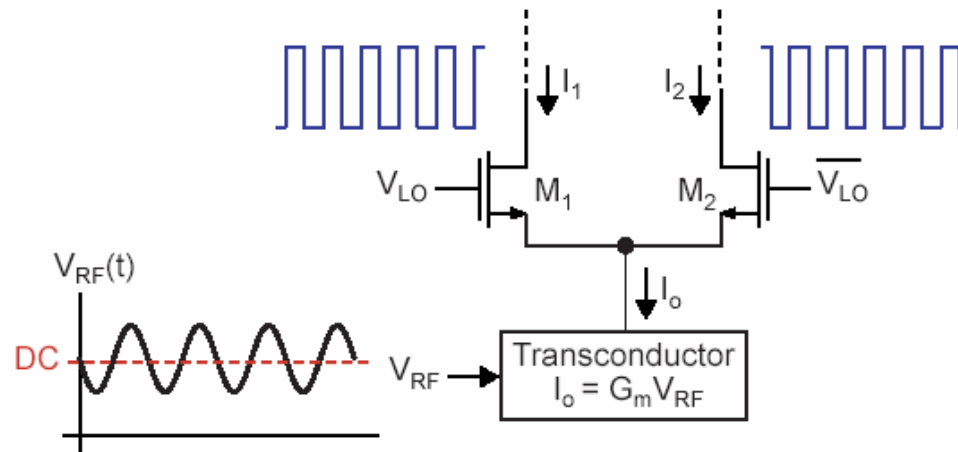
- Combine two mixer paths with LO signal 180 degrees out of phase between the paths



$$RF(t) \cdot [LO(t) - \overline{LO(t)}] = RF(t) \cdot LO(t) - RF(t) \cdot \overline{LO(t)}$$

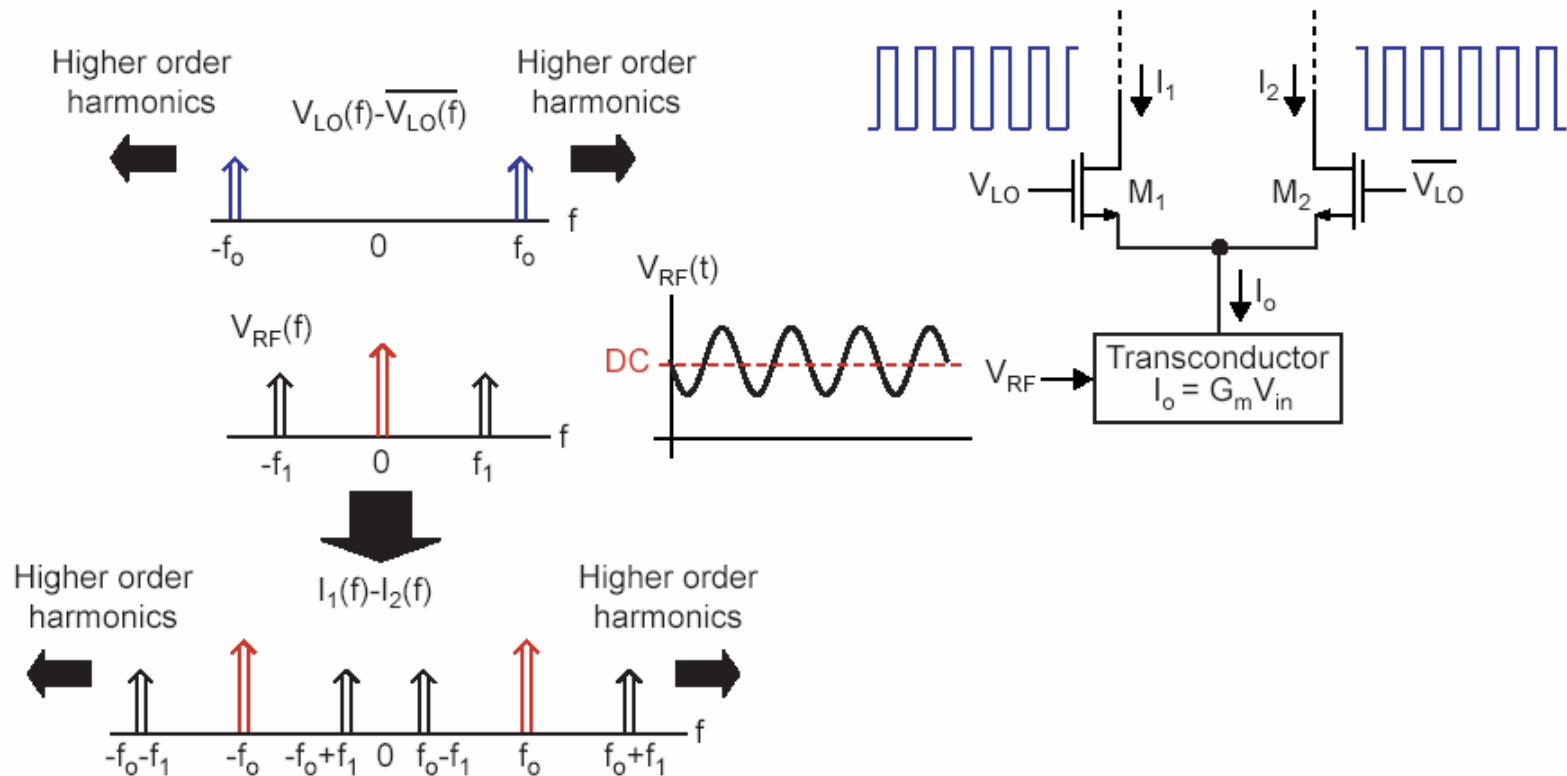
- DC component is cancelled

# Single-Balanced Mixer



- Works by converting RF input voltage to a current, then switching current between each side of differential pair
- Achieves LO balance using technique on previous slide
  - Subtraction between paths is inherent to differential output
- LO swing should be no larger than needed to fully turn on and off differential pair
  - Square wave is best to minimize noise from  $M_1$  and  $M_2$
- Transconductor designed for high linearity

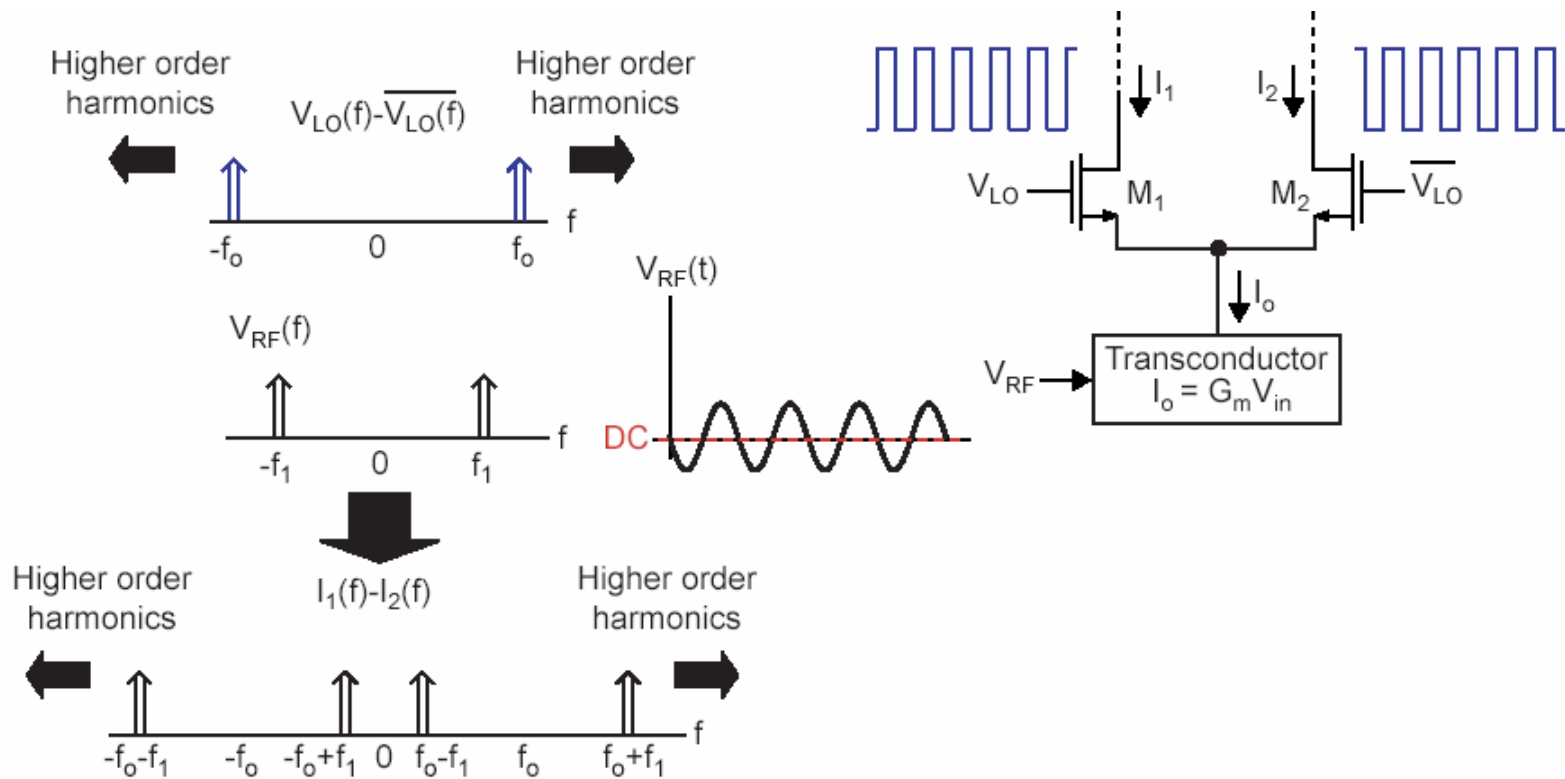
# LO Feedthrough in Single-Balanced Mixers



- DC component of RF input causes very large LO feedthrough
  - Can be removed by filtering, but can also be removed by achieving a zero DC value for RF input

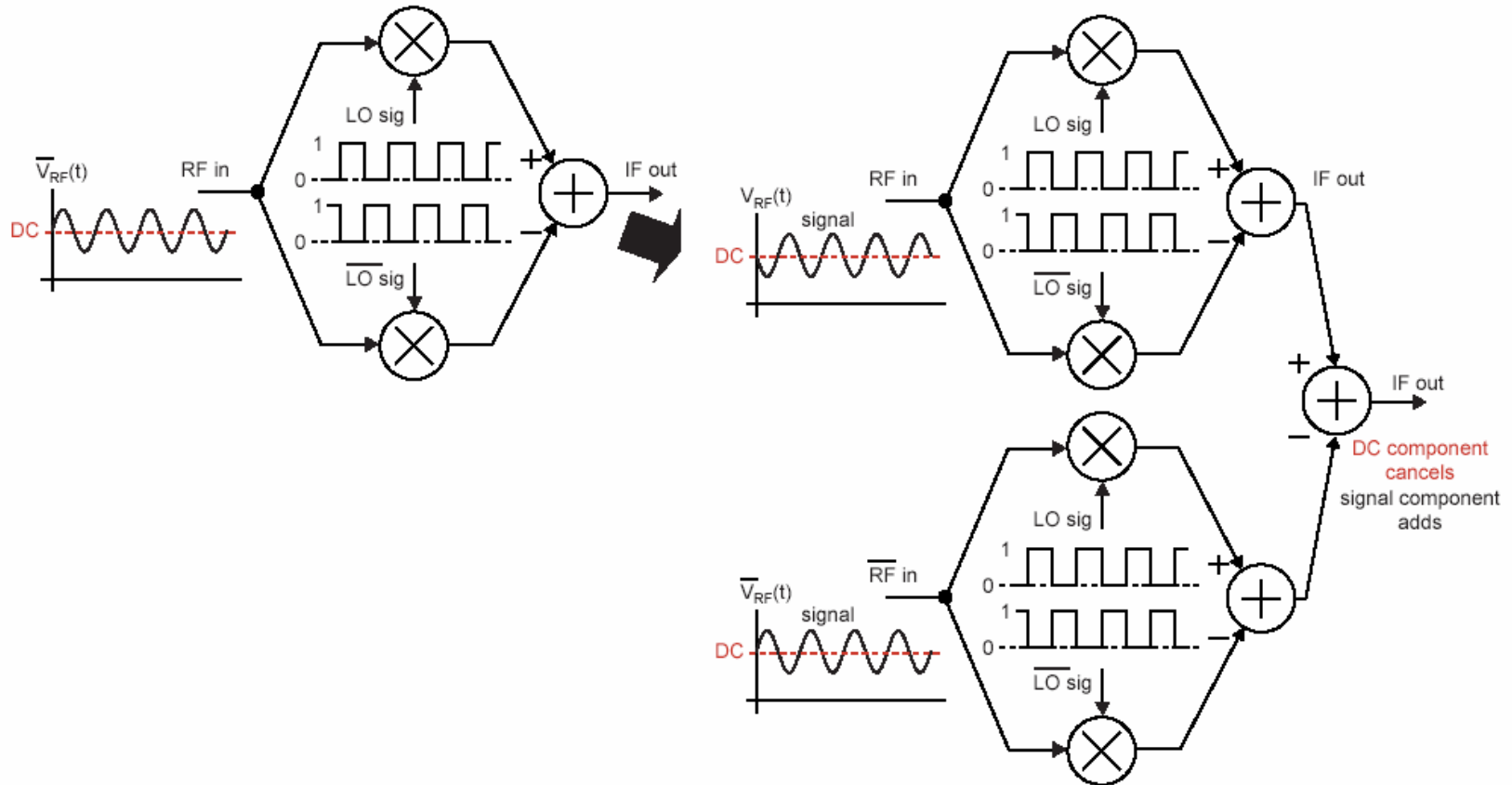


# Ideal Double-Balanced Mixer



- DC values of LO and RF signals are zero (balanced)
- LO feedthrough dramatically reduced!
- But, practical transconductor needs bias current

# Achieving Balanced RF Signal with Biasing

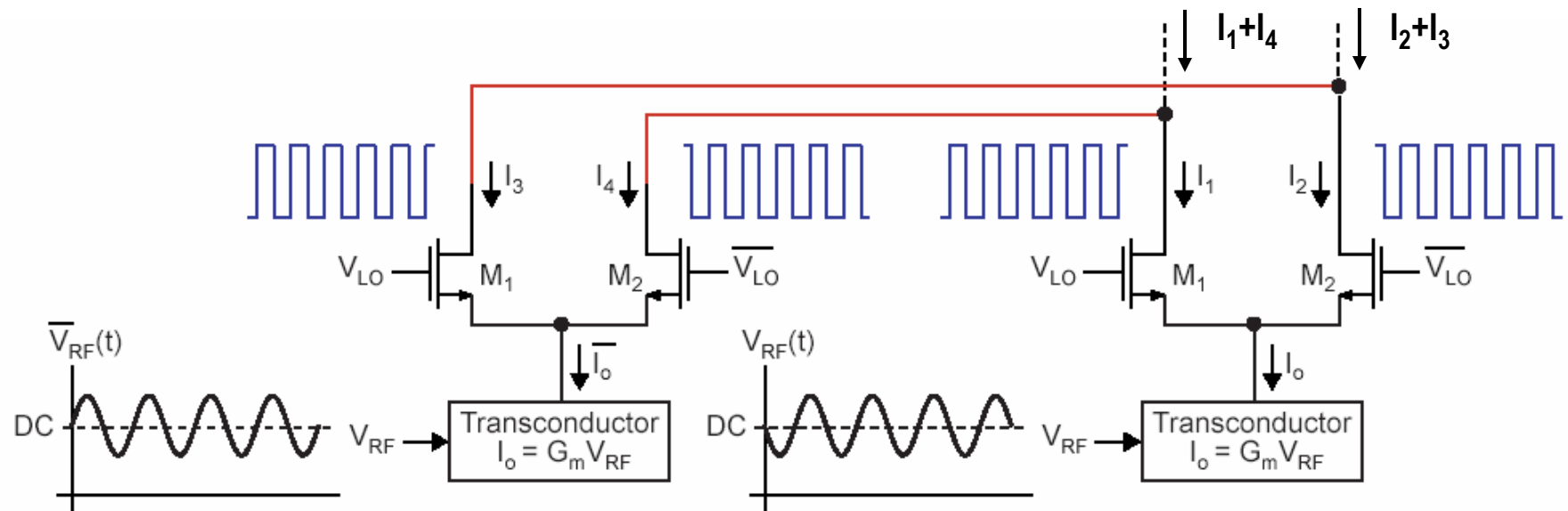


$$[RF(t) - \overline{RF(t)}] \cdot [LO(t) - \overline{LO(t)}]$$

$$\Downarrow RF(t) \cdot [LO(t) - \overline{LO(t)}] = RF(t) \cdot LO(t) - RF(t) \cdot \overline{LO(t)}$$

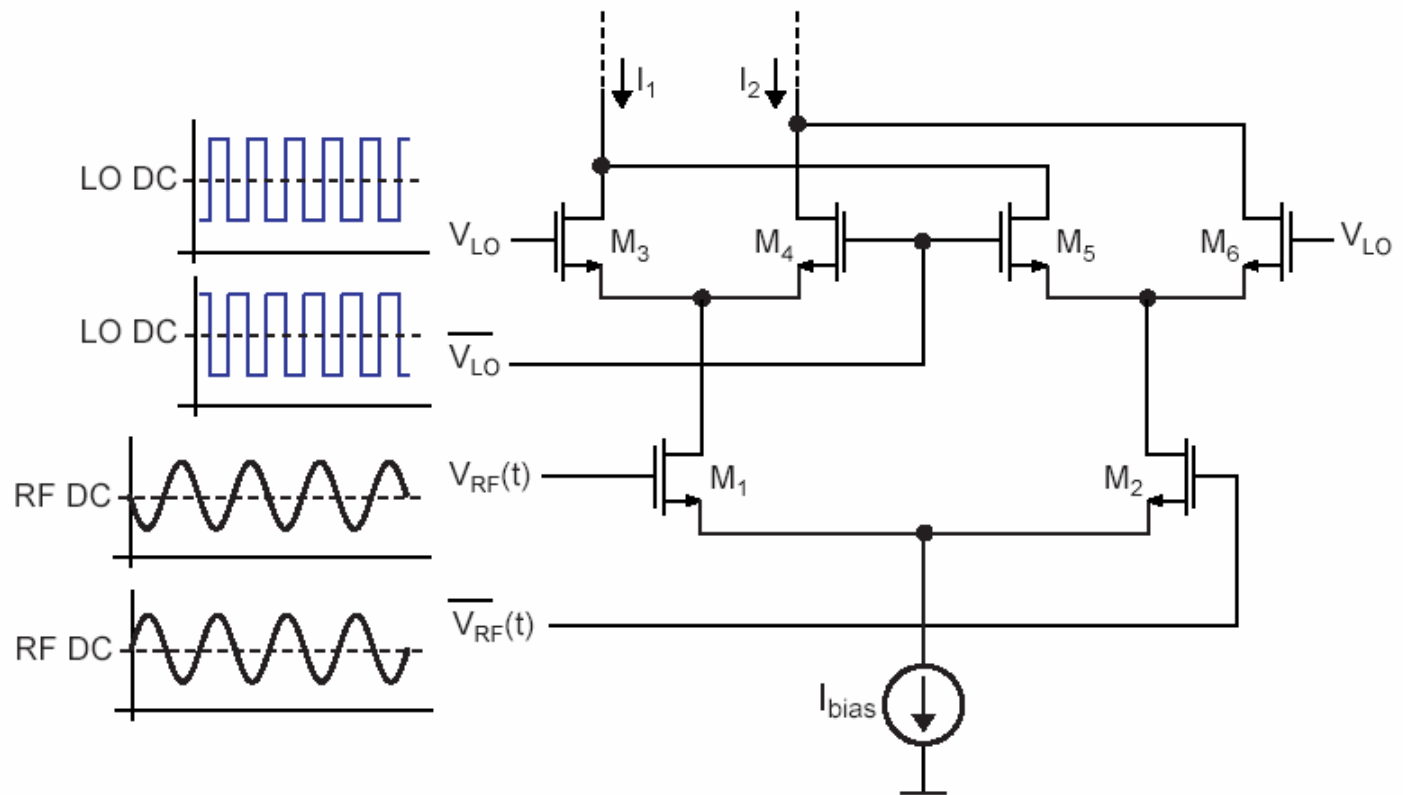
$$\Downarrow \overline{RF(t)} \cdot [LO(t) - \overline{LO(t)}] = \overline{RF(t)} \cdot LO(t) - \overline{RF(t)} \cdot \overline{LO(t)}$$

# Double-Balanced Mixer Implementation



- Applies technique from previous slide
  - Subtraction at the output achieved by cross-coupling the output current of each stage

# Gilbert Cell (Four Quadrant) Mixer

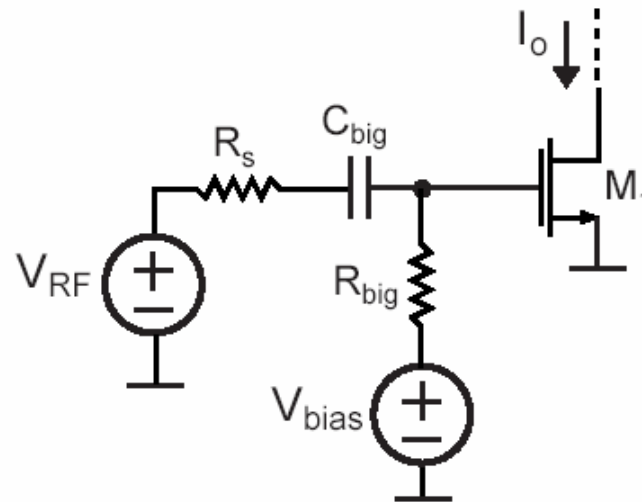


- Use a differential pair to achieve the transconductor implementation
- This is the preferred mixer implementation for most radio systems!

## Mixer Voltage Conversion Gain

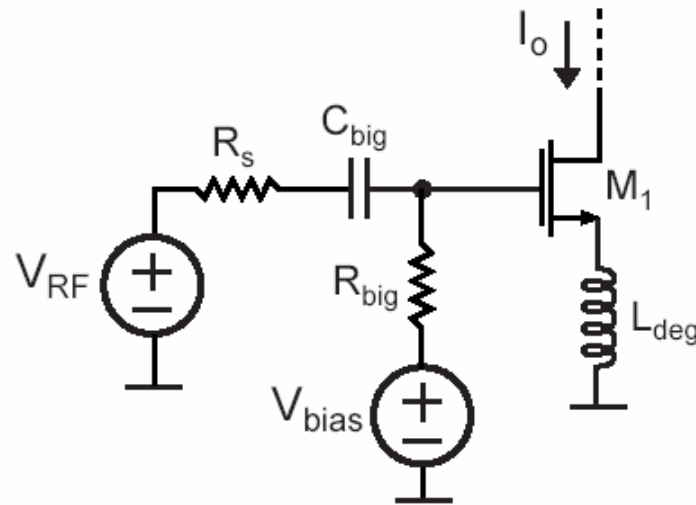
- ❑ **Voltage conversion gain of a mixer depends on several factors**
  - **Input transconductance**
  - **Multiplication factor**
  - **Load resistance**

# Common-Source Transconductance Stage in Mixer



- Apply RF signal to input of common source amp
  - Transistor assumed to be in saturation
  - Transconductance value is the same as that of the transistor
- High  $V_{bias}$  places device in velocity saturation
  - Allows high linearity to be achieved

# CS Transconductance Stage with Degeneration



- **Add degeneration to common source amplifier**
  - **Inductor better than resistor**
    - No DC voltage drop
    - Increased impedance at high frequencies helps filter out undesired high frequency components
  - **Don't generally resonate inductor with  $C_{gs}$** 
    - Power match usually not required for IC implementation due to proximity of LNA and mixer

# Transconductor Stage in Mixer

$$g_{m\_Effective} = \frac{1/j\omega C_{gs}}{Z_{in}} g_m = G_m$$

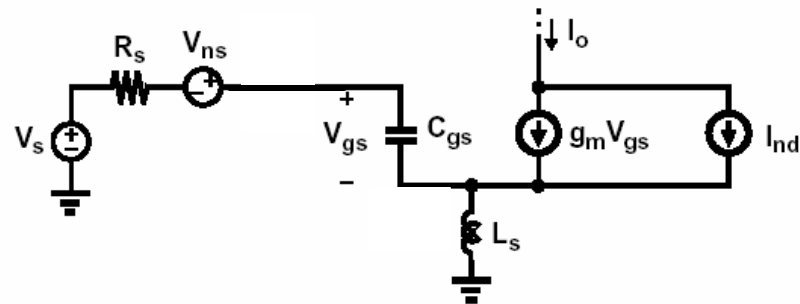
$$= Q_{in} g_m$$

$$= \frac{g_m}{\omega C_{gs} (R_s + \frac{g_m}{C_{gs}} L_s)}$$

$$= \frac{g_m}{\omega C_{gs} (R_s + \omega_T L_s)}$$

$$\gg \frac{1}{\omega_T L_s}$$

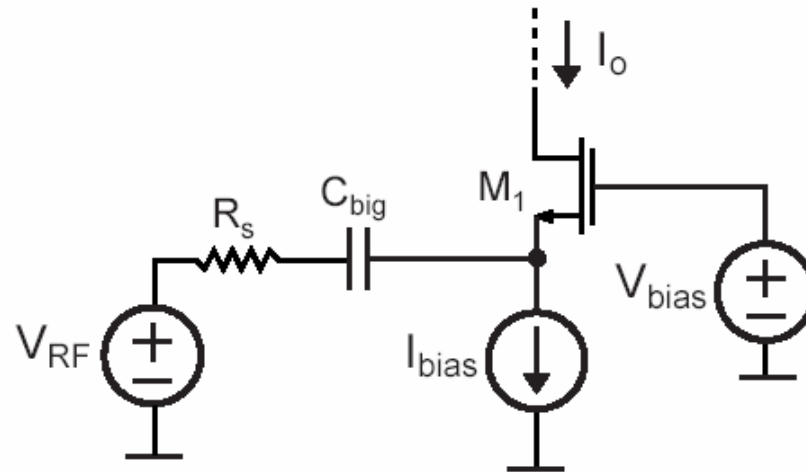
For  $\omega_T L_s \gg R_s$ , highly linearly transconductance, only depends  $L_s$



Note that:  $Q_{in} = \frac{1}{\omega C_{gs} (R_s + \frac{g_m}{C_{gs}} L_s)} = \frac{\omega_T L_s}{R_s + \frac{g_m}{C_{gs}} L_s}$

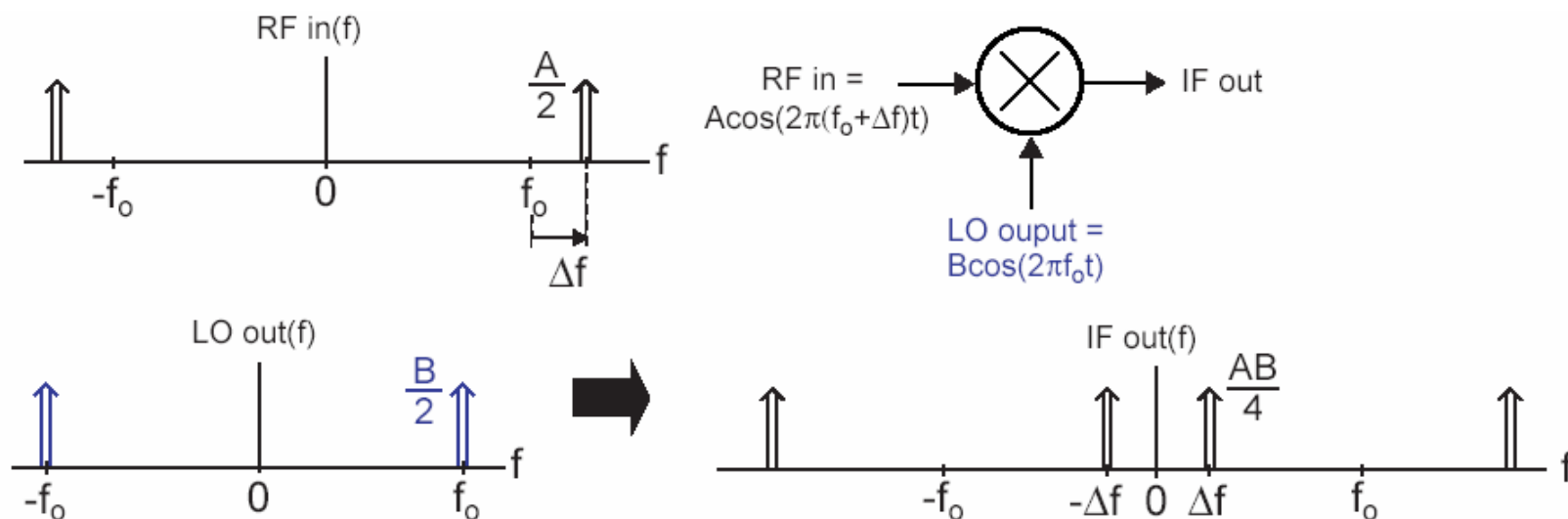


# Common-Gate Transconductance Stage in Mixer



- Apply RF signal to a common gate amplifier
- Transconductance value set by inverse of series combination of  $R_s$  and  $1/g_m$  of transistor
  - Amplifier is effectively degenerated to achieve higher linearity
- $I_{bias}$  can be set for large current density through device to achieve higher linearity (velocity saturation)

# Mixer Multiplication Factor



- Defined as voltage ratio of desired IF value to RF input
- Example: for an ideal mixer with RF input =  $A\sin(2\pi(f_0 + \Delta f)t)$  and sine wave LO signal =  $B\cos(2\pi f_0 t)$

$$IF\ out(t) = \frac{AB}{2} \left( \cos(2\pi(\Delta f)t) + \cos(2\pi(2f_0 + \Delta f)t) \right)$$

$$\Rightarrow \text{Voltage Conversion Gain} = \frac{AB/2}{A} = \frac{B}{2}$$

# Mixer Voltage Conversion Gain

- If the *sinusoidal* LO swing is sufficiently large to completely switch the current, we can approximate the LO by a square wave
- Consider only the fundamental term in LO

$$\begin{aligned}i_{out} &= i_{RF} \cos(\omega_{RF} t) \cdot \frac{4}{p} \cos(\omega_{LO} t) \\ &= \frac{1}{2} \left\{ \frac{4}{p} i_{RF} \cos[(\omega_{RF} - \omega_{LO})t] + \frac{4}{p} i_{RF} \cos[(\omega_{RF} + \omega_{LO})t] \right\}\end{aligned}$$

- After the low-pass filter,

$$\begin{aligned}i_{out} &= \frac{2}{p} i_{RF} \cos[(\omega_{RF} - \omega_{LO})t] \\ &= \frac{2}{p} g_{m\_eff} v_{RF} \cos[(\omega_{RF} - \omega_{LO})t]\end{aligned}$$

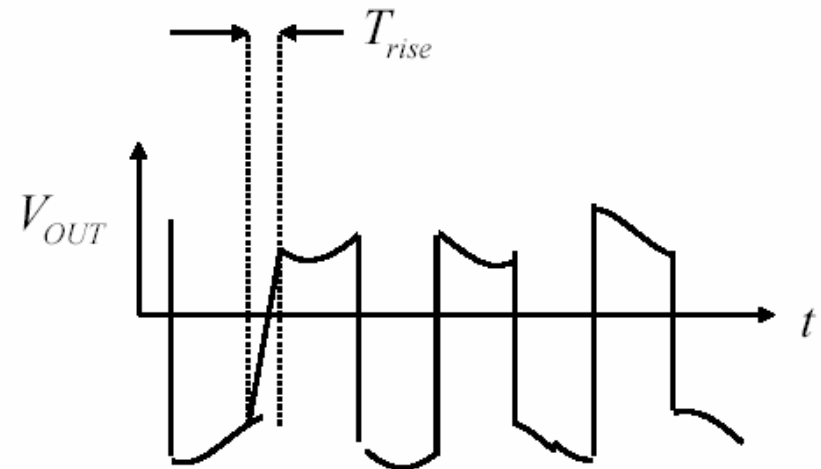
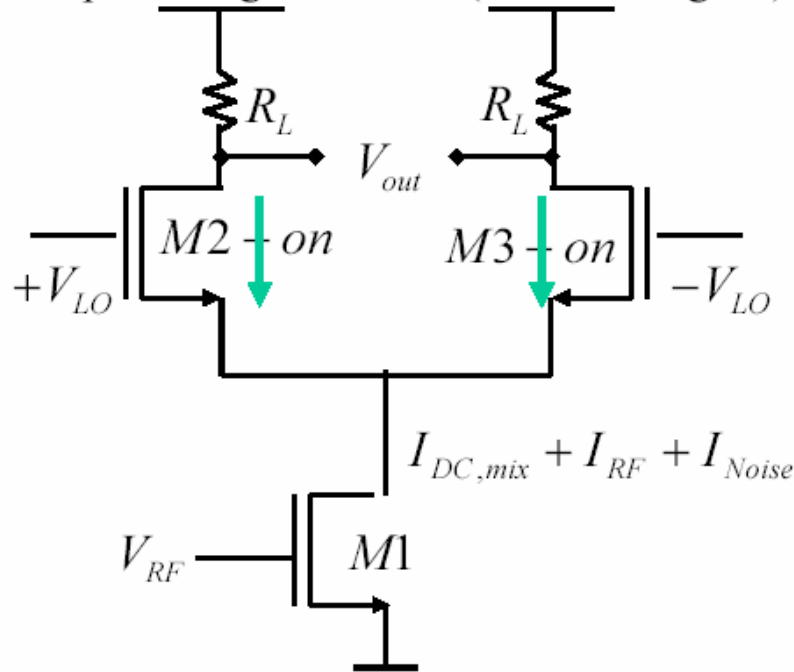
$$\text{P Gain} = i_{out} R_{out} = \frac{2}{p} g_{m\_eff} R_{out}$$

# Mixer Noise Analysis

- ❑ **Three contributors to mixer noise**
  - **Transconductance stage**
  - **Switching pairs**
  - **Load resistance**

# Design Consideration for Minimizing Mixer NF

- Optimizing the mixer (for noise figure):

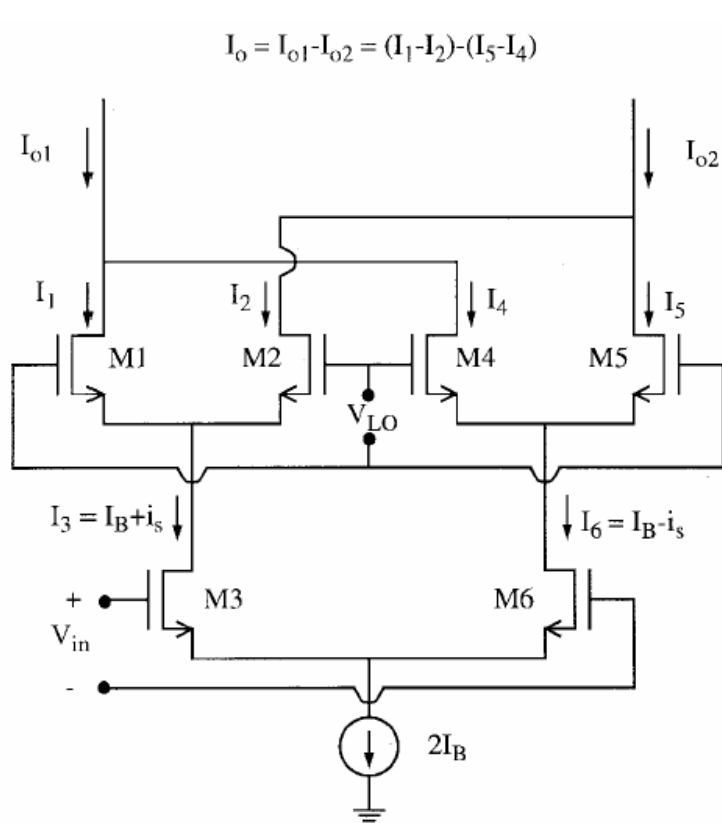


$$g_m \propto \sqrt{W} \dots \text{fixed} - I_{DC}$$

$$\omega_T \propto \frac{1}{\sqrt{W}} \dots \text{fixed} - I_{DC}$$

- Design the transducer for minimum noise figure
- Noise from M2 and M3 can be minimized through fast switching of M2 & M3 by
  - making LO amplitude large to ensure complete ( $> 90\%$ ) current commuting
  - making M2 and M3 as small as possible (i.e. increasing  $f_T$  of M2 and M3)

# NF Expression for Double-Balanced Mixer [1]



$(NF)_{SSB}$

$$= \frac{\alpha}{c^2} + \frac{2(\gamma_3 + r_{g3}g_{m3})g_{m3}\alpha + 4\gamma_1\overline{G} + 4r_{g1}\overline{G}^2 + \frac{1}{R_L}}{c^2g_{m3}^2R_s} \quad (44)$$

where

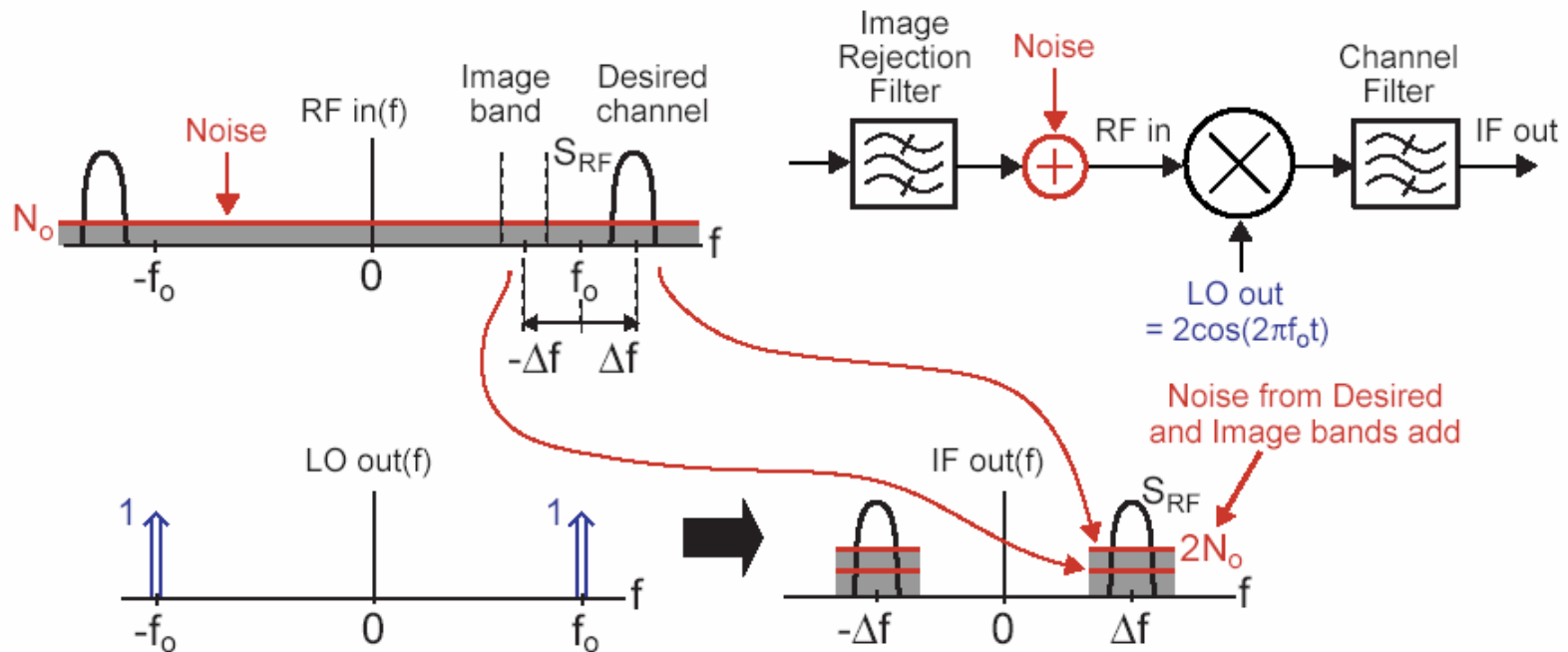
$$c \cong \frac{2}{\pi} \left( \frac{\sin(\pi\Delta f_{LO})}{\pi\Delta f_{LO}} \right) \quad (18)$$

$$\alpha \cong 1 - \frac{4}{3}(\Delta f_{LO}) \quad (25)$$

$$\overline{G} = \frac{1}{\pi V_o} \int_{-V_x}^{V_x} \left( \frac{dI_{o1}}{dV_{LO}} \right) dV_{LO} = \frac{2I_B}{\pi V_o} \quad (33)$$

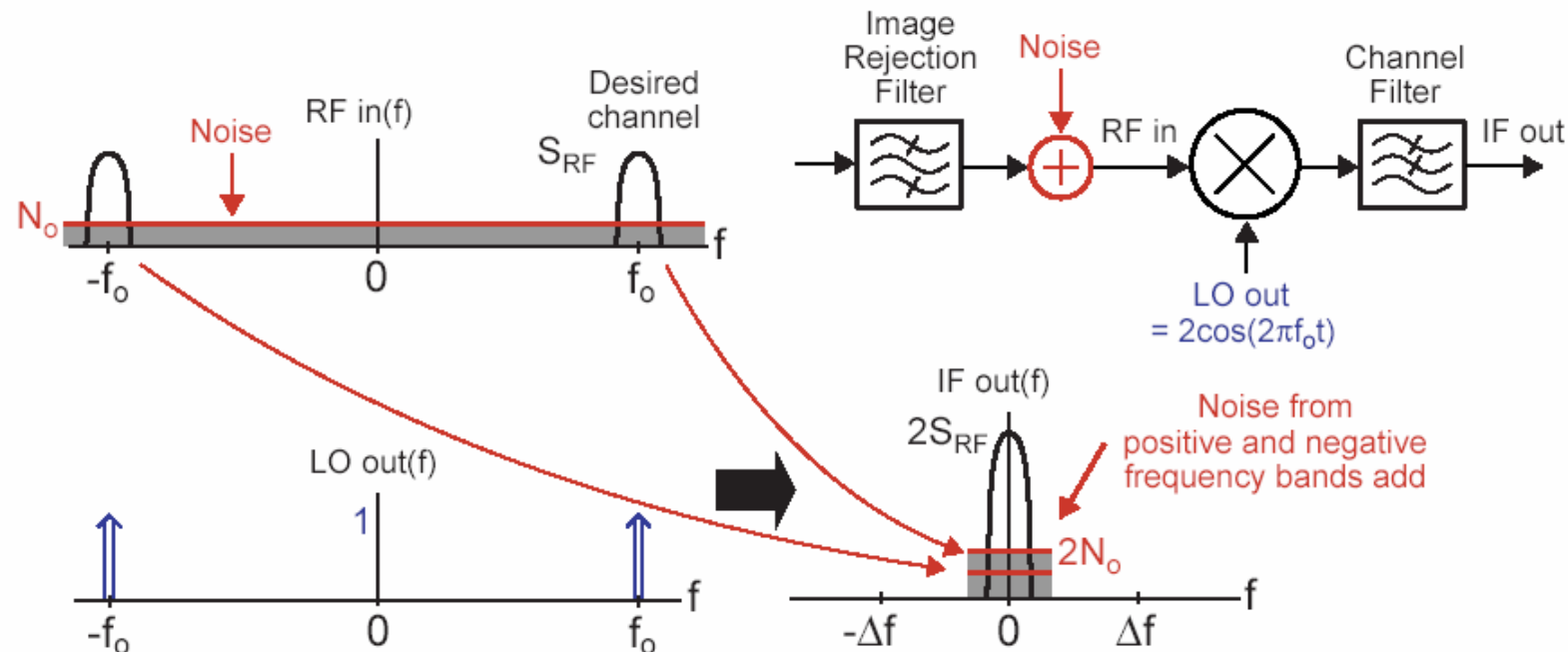
$$\overline{G}^2 \approx 16 \left( \frac{\ln(\sqrt{2} + 1)}{\sqrt{2}} - \frac{1}{3} \right) \cdot \frac{K_1^{1/2} I_B^{3/2}}{\lambda T_{LO}} = 4.64 \cdot \frac{K_1^{1/2} I_B^{3/2}}{\lambda T_{LO}} \quad (40)$$

# Mixer NF for Single-Sideband Systems



- **Issue – broadband noise from mixer or front end filter will be located in both image and desired bands**
  - Noise from both image and desired bands will combine in desired channel at IF output
    - Channel filter cannot remove this
  - **Mixers are inherently noisy!**

# Mixer NF Double Sideband Systems

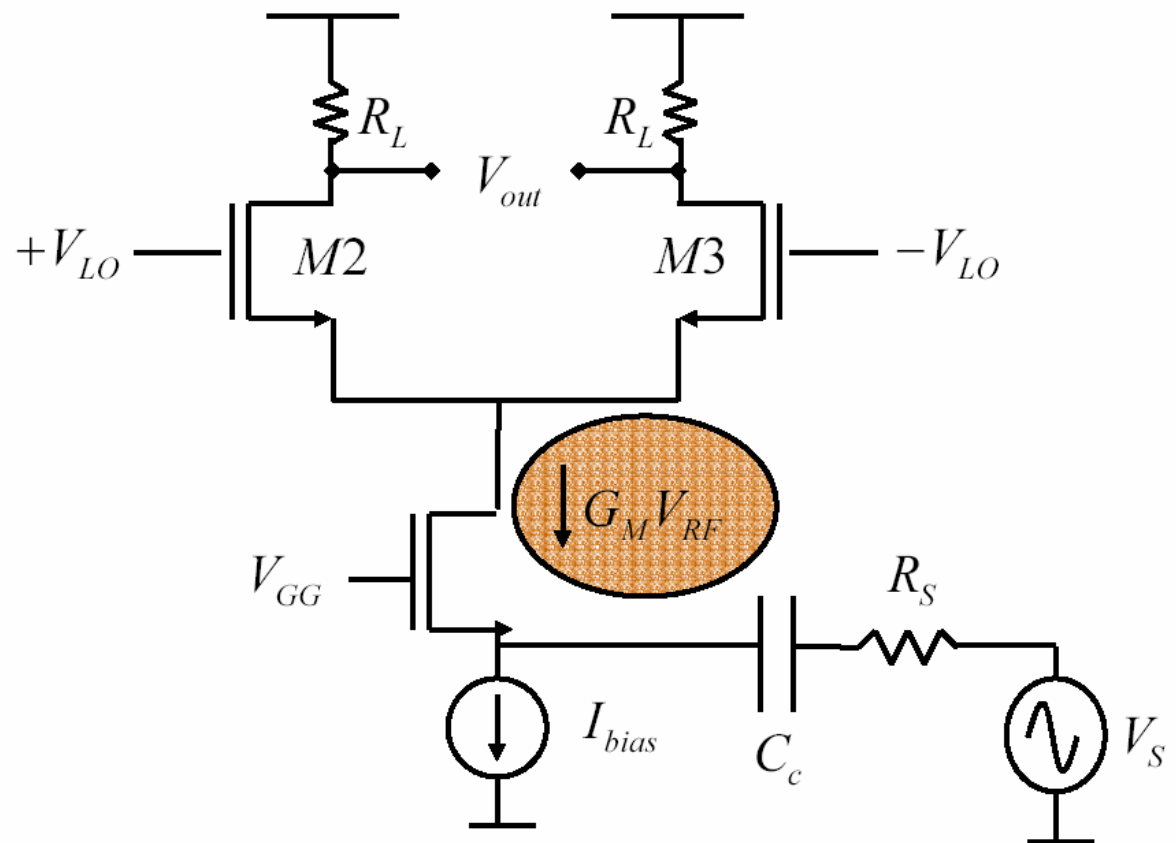


- For zero IF, there is no image band
  - Noise from positive and negative frequencies combine, but the signals do as well
- DSB noise figure is 3 dB lower than SSB noise figure
  - DSB noise figure often quoted since it sounds better
- For either case, Noise Figure computed through simulation





# Design Consideration for Mixer Linearity



- Using the common gate or common base stage as the transducer improves the linearity of the mixer. Unfortunately the approach reduces the gain and increases the noise figure of the mixer.

# Measured IIP3 for a 0.8-mm SB Mixer [2]

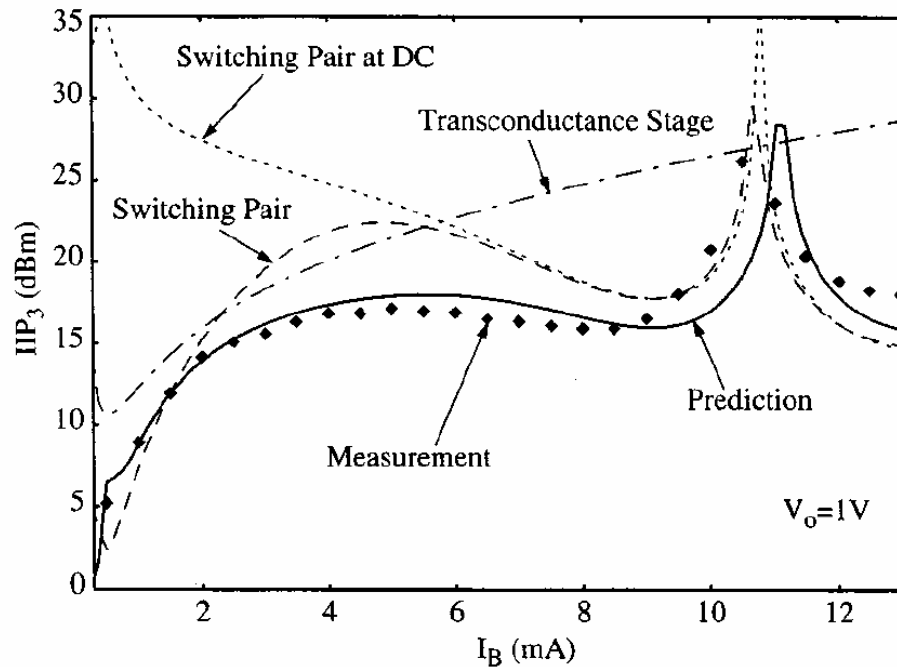


Fig. 20. Intermodulation measurements versus bias current for a fixed LO amplitude  $V_o = 1$  V.

- ❑ At high bias current, the switching pair nonlinearity dominates
- ❑ At low bias current, the transconductance stage nonlinearity dominates
  - For short channel devices, the transconductance stage nonlinearity dominates
  - IIP<sub>3</sub> is proportional to  $(V_{RF\_DC} - V_{th})$

# Measured IIP3 for a 0.8-mm SB Mixer [2]

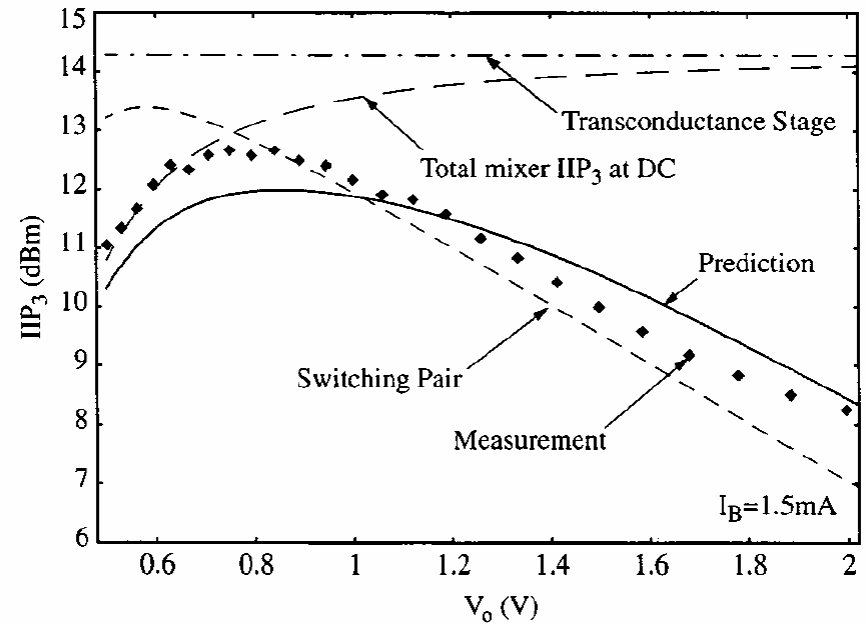
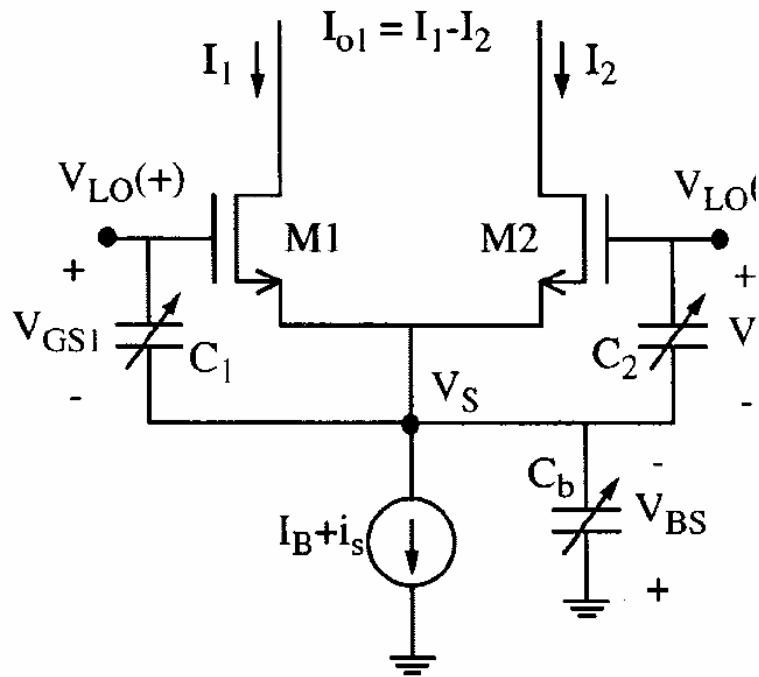
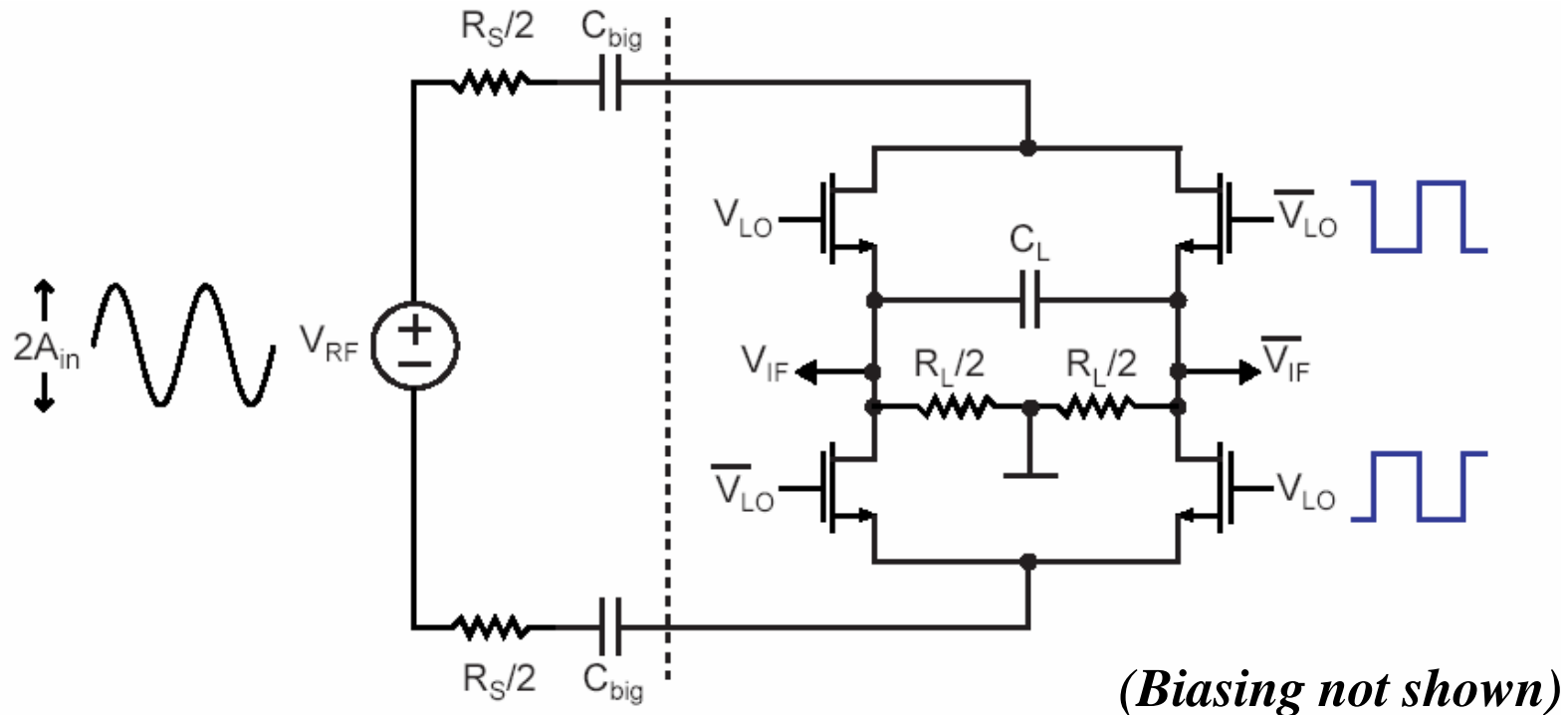


Fig. 21. Intermodulation measurements versus LO amplitude for a fixed bias current  $I_B = 1.5$  mA.

- ❑ At high frequencies, excessively large LO amplitude degrades IIP3 due to parasitic capacitive coupling which is nonlinear
- ❑ For low-voltage design ( $< 2V$ ), this is usually not a big concern

# Passive Mixers



- ❑ Very high linearity (assuming the current are completely commuted)
  - 20–30 dBm of IIP3 achievable
- ❑ High noise figure (noise due to the the switching devices)
  - 20–30 dB of NF
- ❑ Voltage conversion loss



## References

1. M. T. Terrovitis and R. G. Meyer, “Noise in Current-Commuting CMOS Mixers” *IEEE Journal of Solid-State Circuits*, Vol. 34, No. 6, June 1999.
2. M. T. Terrovitis and R. G. Meyer, “Intermodulation Distortion in Current-Commutating CMOS Mixers,” *IEEE Journal of Solid-State Circuits*, Vol. 35, No. 10, October 2000.
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4. Prof. L. Larson, UC San Diego  
ECE 265A and 265B lecture notes