# Eigenvalue Computations: The Power and Lanczos Methods

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#### Introduction

This paper looks at two methods for finding the eigenvalues of a matrix. The first section examines the behavior of symmetric and nonsymmetric matrices under the power method. Differences in the convergence rates of these two classes of matrices are presented and explained. The second section focuses on the extreme eigenvalues computed by the Lanczos algorithm. In particular, the paper examines error bounds and approximations for the symmetric and unsymmetric Lanczos methods.

#### I. The Power Method

The power method is known as a simple iterative process for finding the dominant eigenvalue of a matrix. The method proceeds as follows: Let  $x_0$  be an arbitrary initial vector, and let  $A \in \mathbb{R}^{n \times n}$  have eigenvalues  $\lambda_1, \lambda_2, \ldots, \lambda_n$  such that  $|\lambda_1| \leq |\lambda_2| \leq \cdots < |\lambda_n|$ . Construct the sequence  $x_{k+1} = Ax_k$  for  $k = 0, 1, 2, \ldots$  Assuming the dominant eigenvalue  $\lambda_n$  exists, this sequence converges to a multiple of the associated eigenvector. The method is easily explained by expanding  $x_0$  in terms of the eigenvectors of A. Suppose the eigenvectors  $v_1, v_2, \ldots, v_n$  of the matrix are linearly independent; that is, A is non-defective. Then  $x_0$  can be written as

$$x_{0} = \alpha_{1}v_{1} + \dots + \alpha_{n}v_{n}$$
Thus, 
$$x_{k} = A^{k}x_{0} = \alpha_{1}\lambda_{1}^{k}v_{1} + \dots + \alpha_{n}\lambda_{n}^{k}v_{n}$$

$$= \lambda_{n}^{k}\left[\alpha_{1}\left(\frac{\lambda_{1}}{\lambda_{n}}\right)^{k}v_{1} + \dots + \alpha_{n-1}\left(\frac{\lambda_{n-1}}{\lambda_{n}}\right)^{k}v_{n-1} + \alpha_{n}v_{n}\right]$$

$$\to \alpha_{n}\lambda_{n}^{k}v_{n} \text{ as } k \to \infty$$

$$(1)$$

When using the power method, the  $x_k$ 's are usually scaled at each step to prevent underflow or overflow from the  $\lambda_n^k$  term. Also, an approximation to the dominant eigenvalue can be computed at each step from the Rayleigh quotient:

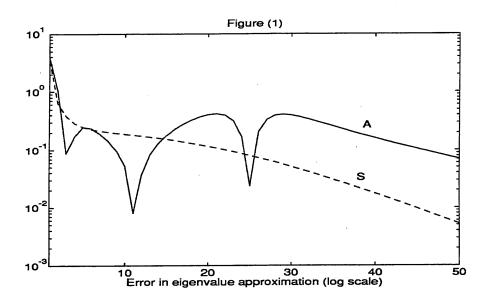
$$\mu_k = \frac{x_k^T A x_k}{x_k^T x_k} \tag{2}$$

<sup>&</sup>lt;sup>1</sup>Even if A is defective, the power method can still yield the dominant eigenvector if it has multiplicity one.

As  $x_k$  approaches the dominant eigenvector, the Rayleigh quotient  $\mu_k$  will be an increasingly better estimate of the dominant eigenvalue. Equation (1) suggests that the speed of convergence of the power method is determined by the ratio  $\frac{\lambda_{n-1}}{\lambda_n}$ . Many of the linear algebra textbooks discuss this point no further. However, there is more to the convergence of the power method than the ratio  $\frac{\lambda_{n-1}}{\lambda_n}$ . Figure (1) plots the power method's error for two matrices, A and S, that have exactly the same set of eigenvalues. Regarding this graph, one can see that a couple of unexpected things occur. Not only does S converge much faster than A, but the eigenvalue estimations of A appear to jump up and down initially whereas the convergence of S is very smooth. The differences in convergence occur because S is a symmetric matrix. The comparison of the behavior of symmetric versus nonsymmetric matrices under the power method will be the focus of this section.

The tridiagonal matrices with the same eigenvalues from Figure (1) are found below. These matrices have exactly the same set of eigenvalues since S is just a similarity transformation of A, i.e.  $A = D^{-1}SD$ , where D is the diagonal matrix with diagonal components  $(2^0, 2^1, ..., 2^9)$ .

$$A_{10\times 10} = \begin{bmatrix} 2 & -2 & 0 \\ \frac{-1}{2} & 2 & \ddots \\ & \ddots & \ddots & -2 \\ 0 & & \frac{-1}{2} & 2 \end{bmatrix} \quad S_{10\times 10} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & \ddots & \\ & \ddots & \ddots & -1 \\ 0 & & -1 & 2 \end{bmatrix}$$



This figure plots the error in the power method's eigenvalue approximation for 50 iterations applied to A and S.

A good heuristic explanation of A's initial oscillation can be given in terms of an orthogonal expansion of the  $x_k$ 's. Since S is symmetric, an orthogonal set of eigenvectors exists.

We can write  $x_0$  as a linear combination of these eigenvectors:

$$x_0 = lpha_1 v_1 + \dots + lpha_{10} v_{10} = V lpha, \quad lpha = \left[ egin{array}{c} lpha_1 \ dots \ lpha_{10} \end{array} 
ight]$$

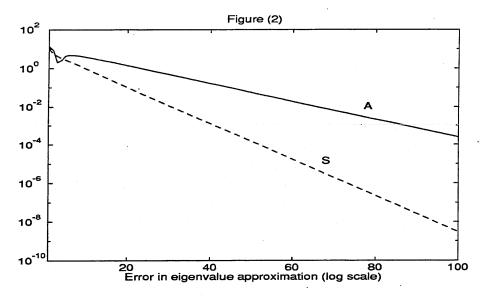
Since V is an orthogonal matrix, it is length preserving, and  $||x_0|| = ||\alpha||$ . The coefficients  $\alpha_i$  are on the same scale as the components of  $x_0$ . On the other hand, the unsymmetric matrix A has eigenvectors that are not orthogonal. Let  $x_0 = \beta_1 \omega_1 + \cdots + \beta_{10} \omega_{10}$ , where  $\omega_i$  is an eigenvector of A. These coefficients  $\beta_i$  can be rather large, making  $||\beta|| \gg ||x_0||$ . For instance, let  $x_0 \in \mathbb{R}^{10}$  be the vector  $\frac{1}{\sqrt{10}}(1,\ldots,1)^T$ . Then by writing  $x_0$  as an expansion of each set of eigenvectors, we find that  $||\alpha|| = ||x_0|| = 1$ , but  $||\beta|| \approx 69.5$ . When  $\beta$  has such large positive or negative components for successive  $x_k$ 's, we see the Rayleigh quotient oscillate as in Figure (1). Only when  $x_k$  is close enough to the dominant eigenvector does the norm of  $\beta$  approximate the norm of  $x_k$  and the convergence curve becomes smooth. This is easiest to see if we normalize all the eigenvectors and  $x_k$ 's to be of unit length. Then as  $x_k$  approaches  $\omega_{10}$ ,  $\beta_{10}$  approaches 1 but all the other coefficients go to zero. Thus,  $||\beta|| \approx ||x_k|| = 1$ .

Figure (2) illustrates the difference in convergence rates for another pair of  $10 \times 10$  matrices sharing the same eigenvalues:

$$A_{1} = \begin{bmatrix} -5 & 2 & & & & 0 \\ \frac{1}{2} & -7 & 3 & & & & \\ & \frac{1}{3} & -9 & 4 & & & \\ & & \frac{1}{4} & -11 & \ddots & & \\ & & & \ddots & \ddots & 10 \\ 0 & & & & \frac{1}{10} & -23 \end{bmatrix} \quad S_{1} = \begin{bmatrix} -5 & 1 & & & & 0 \\ 1 & -7 & 1 & & & & \\ & 1 & -9 & 1 & & & \\ & & & 1 & -11 & \ddots & \\ & & & \ddots & \ddots & 1 \\ 0 & & & 1 & -23 \end{bmatrix}$$

The difference can be explained by properties of the Rayleigh quotient (equation (2)) applied to symmetric matrices. Calculating Rayleigh quotients for a symmetric matrix has the effect of squaring the error in the initial vector  $x_k$ . That is, suppose  $x_k = v_n + e$ , where  $||e|| = \epsilon$  and  $v_n$  is an eigenvector of A. Then  $\mu_k = \lambda_n + O(\epsilon^2)$ . A proof may be found in Stewart [5]. Thus, while the eigenvalues for A converge linearly at the same rate as the eigenvectors of both matrices, the eigenvalues of S converge twice as fast. While this is still extremely slow, the difference is worth noting.

The properties discussed are not unique to the two matrix pairs A and S given here. Other examples of symmetric and nonsymmetric matrices sharing the same eigenvalues can easily be constructed on mathematical software. For example, on Matlab, let A = rand(n), and find the eigensystem of A by [V,E] = eig(A), where the columns of V are eigenvectors and the diagonal elements of E are the eigenvalues. The command E = orth(V) gives an orthogonal basis for the eigenvectors, and  $E = \text{conv}(E) + \text{command}(E) + \text{command}(E) + \text{convergence}(E) + \text{convergence$ 



This figure plots the error in the eigenvalue approximation for 100 iterations of the power method applied to matrices A and S.

#### II. Lanczos

The Lanczos method for finding eigenvalues of a symmetric matrix is typically applied to large, sparse matrices when a few of the extreme eigenvalues are desired. Given a symmetric matrix  $A \in \mathbb{R}^{n \times n}$ , the method computes a sequence of tridiagonal matrices  $T_j$  whose largest and smallest eigenvalues are usually close approximations of the extreme eigenvalues of A. The transformations are made with orthonormal,  $n \times j$  matrices  $Q_j$  such that  $Q_j^T A Q_j = T_j$   $(T_n \equiv T)$ . Thus, when j = n, A and T have exactly the same set of eigenvalues since this is just a similarity transformation. The transformation is useful because the eigenspace of T is much easier to compute than that of A. This method was developed by Cornelius Lanczos in 1950 as a complete algorithm for tridiagonalization. In actual use, round-off errors cause the method to break down as the orthogonality of the columns of Q is lost. However, the practicality of the Lanczos algorithm is that the extreme eigenvalues of A are closely approximated when j is much less than n. This section will focus on the error bounds and approximations of the eigenvalues of the  $T_j$ 's.

The Lanczos method (Golub and Van Loan [2])

Let  $A \in \mathbb{R}^{n \times n}$  be symmetric. We want to find an orthogonal matrix Q such that

$$Q^{T}AQ = T = \begin{bmatrix} \alpha_{1} & \beta_{1} & & & 0\\ \beta_{1} & \alpha_{2} & \beta_{2} & & & \\ & \beta_{2} & \alpha_{3} & \ddots & & \\ & & \ddots & \ddots & \beta_{n-1} \\ 0 & & & \beta_{n-1} & \alpha_{n} \end{bmatrix}$$
(3)

To show how this can be done, we first represent Q by its columns:  $Q = [q_1 \ q_2 \dots q_n]$ . Since AQ = QT, we can set the  $j^{th}$  column of AQ equal to the  $j^{th}$  column of QT. Thus,

$$Aq_{j} = \beta_{j-1}q_{j-1} + \alpha_{j}q_{j} + \beta_{j}q_{j+1} \quad (\beta_{0}q_{0} \equiv 0) \quad j = 1: n-1$$
(4)

Since the columns of Q are mutually orthogonal, multiplying equation (4) by  $q_j^T$  yields  $\alpha_j = q_j^T A q_j$ . Let  $r_j = (A - \alpha_j I) q_j - \beta_{j-1} q_{j-1}$ . Then  $q_{j+1} = r_j / \beta_j$ , where  $\beta_j = \pm ||r_j||_2$ . If  $r_j = 0$  the algorithm terminates prematurely. We have thus written explicit formulas for the  $\alpha_j$  and  $\beta_j$ . This method may be programmed into Matlab as follows:

```
Matrix = input('Matrix = ?');
q(:,1) = zeros(size(Matrix,1),1);
q(:,2) = input('initial vector = ?');
j = 0;
u(1) = 1;
r(:,1) = q(:,2);
np = size(Matrix,1);
for j = 2:(np+1)
d(j) = q(:,j)^*Matrix^*q(:,j);
r(:,j) = (Matrix - d(j)*eye(np))*q(:,j) - u(j-1)*q(:,j-1);
\mathbf{u}(\mathbf{j}) = \mathbf{norm}(\mathbf{r}(:,\mathbf{j}));
q(:,j+1) = r(:,j)/u(j);
end;
Tridiag = zeros(np,np);
for j = 1:size(Matrix,1)-1
Tridiag(j,j) = d(j+1);
Tridiag(j+1,j) = u(j+1);
Tridiag(j,j+1) = u(j+1);
end
Tridiag(j+1,j+1) = d(j+2);
```

A Lanczos algorithm for unsymmetric matrices exists but is not very practical. Given  $A \in \mathbb{R}^{n \times n}$ , one can find an invertible (but not necessarily orthogonal) matrix X such that

$$X^{-1}AX = T = \begin{bmatrix} \alpha_1 & \gamma_1 & & 0 \\ \beta_1 & \alpha_2 & \gamma_2 & & & \\ & \beta_2 & \alpha_3 & \ddots & & \\ & & \ddots & \ddots & \gamma_{n-1} \\ 0 & & \beta_{n-1} & \alpha_n \end{bmatrix}$$
 (5)

Just like the symmetric case, the extreme eigenvlaues of A are located fairly quickly by a small submatrix of T. As pointed out in Golub and Van Loan [2], the tridiagonalization of a nonsymmetric matrix is a very unstable process. The unsymmetric Lanczos method is almost never used in practice, although some recent research has attempted to improve

this algorithm, such as Parlett, Taylor and Liu's "look-ahead Lanczos algorithm" [3]. The Madab program for this algorithm is as follows:

```
Matrix = input('Matrix = ?');
x(:,2) = input('initial vector x = ?');
y(:,2) = x(:,2);
x(:,2) = x(:,2)/norm(x(:,2));
y(:,2) = y(:,2)/norm(y(:,2));
N = size(Matrix,1);
x(:,1)=zeros(N,1); y(:,1)=x(:,1);
c(1) = 0; b(1) = 0;
for j = 2:N
a(j) = y(:,j)^*Matrix^*x(:,j);
r(:,j) = (Matrix - a(j)*eye(N))*x(:,j) - c(j-1)*x(:,j-1);
b(j) = norm(r(:,j));
x(:,j+1) = r(:,j)/b(j);
p(:,j) = (Matrix - a(j)*eye(N))*y(:,j) - b(j-1)*y(:,j-1);
c(j) = x(:,j+1)*p(:,j);
y(:,j+1) = p(:,j)/c(j);
a(N+1) = y(:,N+1)^*Matrix^*x(:,N+1);
Tridiag = zeros(N,N);
for j = 1:N-1
Tridiag(j,j) = a(j+1);
Tridiag(j+1,j) = b(j+1);
Tridiag(j,j+1) = c(j+1);
end
Tridiag(N,N) = a(N+1);
```

Note: This program does <u>not</u> work for complex matrices.

It has been mentioned that the sequence  $T_j$  tends to locate the extreme eigenvalues of A very quickly. The Kaniel-Page theorem gives a lower bound for the largest and smallest eigenvalues of  $T_j$  in terms of the eigenvalues of A.

## Kaniel-Paige Theorem. (Golub and Van Loan [2])

Let A be an  $n \times n$  symmetric matrix with eigenvalues  $\lambda_1 \leq \ldots \leq \lambda_n$  and corresponding orthonormal eigenvectors  $v_1, \ldots, v_n$ . Let  $\theta_1 \leq \ldots \leq \theta_j$  be the eigenvalues of the matrix  $T_j$  obtained after j steps of the Lanczos method. Then

$$\lambda_n \ge \theta_j \ge \lambda_n - \frac{(\lambda_n - \lambda_1) \tan(\phi_n)^2}{(c_{j-1}(1 + 2\rho_n))^2} \tag{6}$$

where  $\cos(\phi_n) = |q_1^T v_n|$ ,  $\rho_n = (\lambda_n - \lambda_{n-1})/(\lambda_{n-1} - \lambda_1)$ , and  $c_{j-1}(x)$  is the Chebyshev polynomial of degree j-1. Similarly,

$$\lambda_1 \le \theta_1 \le \lambda_1 + \frac{(\lambda_n - \lambda_1)\tan(\phi_1)^2}{(c_{j-1}(1+2\rho_1))^2}$$
 (7)

where  $\cos(\phi_1) = |q_1^T v_1|$  and  $\rho_1 = (\lambda_2 - \lambda_1)/(\lambda_n - \lambda_2)$ .

### Proof. (Golub and Van Loan [2])

From the minimax theorem of eigenvalues, we have

$$\theta_j = \max_{y \neq 0} \frac{y^T T_j y}{y^T y} = \max_{y \neq 0} \frac{y^T (Q_j^T A Q_j) y}{y^T y} = \max_{y \neq 0} \frac{(Q_j y)^T A (Q_j y)}{(Q_j y)^T (Q_j y)}$$

Let  $w = Q_j y$ . Then  $w \in \text{span}\{q_1, q_2, \dots, q_j\}$ . One can show by induction that  $w \in \text{span}\{q_1, Aq_1, \dots, A^{j-1}q_1\}$ , providing that the Lanczos process does not break down. This implies that  $w = p(A)q_1$  for  $p \in P^{j-1}$ , where  $P^{j-1}$  is the set of polynomials of degree j-1. Then  $w = Vp(\Lambda)V^Tq_1$  since  $A = V\Lambda V^T$  by the spectral theorem.

Thus,  $\theta_j = \max_{w \in K(A, q_1, j)} \frac{w^T A w}{w^T w}$  where K is the Krylov subspace  $\equiv \text{span}\{q_1, A q_1, \dots, A^{j-1} q_1\}.$ 

Since  $\lambda_n$  is the maximum of  $\frac{w^T A w}{w^T w}$  over all nonzero w, it follows that  $\lambda_n \geq \theta_j$ . Now let  $d = V^T q_1$  where d is just the vector of coefficients if we expand  $q_1$  as a linear combination of A's eigenvectors. Then

$$\theta_{j} = \max_{p \in P^{j-1}} \frac{q_{1}^{T} V p(\Lambda)^{T} \Lambda p(\Lambda) V^{T} q_{1}}{q_{1}^{T} V p(\Lambda)^{T} p(\Lambda) V^{T} q_{1}} = \max_{p \in P^{j-1}} \frac{d^{T} p(\Lambda)^{T} \Lambda p(\Lambda) d}{d^{T} p(\Lambda)^{2} d}$$

$$= \max_{p \in P^{j-1}} \frac{\sum_{i=1}^{n} d_{i}^{2} p(\lambda_{i})^{2} \lambda_{i}}{\sum_{i=1}^{n} d_{i}^{2} p(\lambda_{i})^{2}}$$

$$\geq \max_{p \in P^{j-1}} \lambda_{n} - \frac{(\lambda_{n} - \lambda_{1}) \sum_{i=1}^{n-1} d_{i}^{2} p(\lambda_{i})^{2}}{d^{2} p(\lambda_{n})^{2} + \sum_{n=1}^{n-1} d_{i}^{2} p(\lambda_{i})^{2}}$$
(8)

Note that this bound holds for any specific polynomial p(x) we choose. We can make a tight bound by choosing our polynomial p(x) that is large at  $\lambda_n$  and relatively small for the non-dominant eigenvalues. Let

$$p(x) = c_{j-1}(-1 + 2\frac{x - \lambda_1}{\lambda_{n-1} - \lambda_1})$$

where  $c_{j-1}$  is the Chebyshev polynomial defined by  $c_j(x) = \cos(j\cos^{-1}x)$ . For  $x \in [-1,1]$ ,  $|c_j(x)| \le 1$ ; but the Chebyshev polynomial grows very rapidly outside this interval. Thus,  $|p(\lambda_i)| \le 1$  for i = 1 : n - 1, while

$$p(\lambda_n) = c_{j-1}(1+2\rho_n), \rho_n = \frac{\lambda_n - \lambda_{n-1}}{\lambda_{n-1} - \lambda_1}.$$

Since ||d|| = 1,

$$1 - d_n^2 = \sum_{i=1}^{n-1} d_i^2 \ge \sum_{i=1}^{n-1} d_i^2 p(\lambda_i)^2.$$
Thus,  $\theta_j \ge \lambda_n - \frac{(\lambda_n - \lambda_1)(1 - d_n^2)}{d_n^2 c_{j-1} (1 + 2\rho_n)^2}$ 

To obtain the final bound of the Kaniel-Paige theorem, note that  $\tan(\phi_n)^2 = (1 - d_n^2)/d_n^2$ .

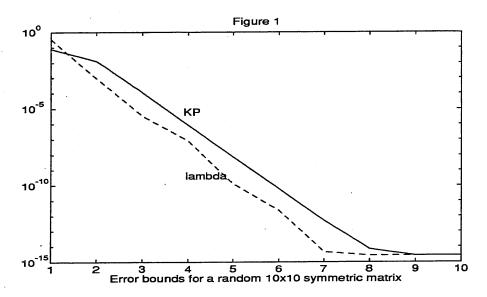


Figure (1) graphs the proximity of the theorem's upper and lower bounds to the dominant eigenvalue for successive  $T_j$ 's. One can see that for random matrices, the upper bound,  $\lambda_n$ , is actually a closer approximation of  $\theta_j$  than the lower bound (denoted KP).

The proof suggests an interesting result that occurs when there is a multiplicity of the eigenvalues. If A has k distinct eigenvalues where k < n, then the extreme eigenvalues  $\theta_1$  and  $\theta_k$  of the matrix  $T_k$  generated by Lanczos will be exactly equal to  $\lambda_1$  and  $\lambda_n$ . To see why this is true, look at equation (8). The polynomial p(x) in this case has degree k-1. Since

$$\lambda_n \ge \theta_k \ge \frac{\sum_{i=1}^n d_i^2 p(\lambda_i)^2 \lambda_i}{\sum_{i=1}^n d_i^2 p(\lambda_i)^2} \text{ for any } p \in P^{k-1},$$

we can choose our polynomial p(x) to have roots at  $\lambda_1, \ldots, \lambda_{k-1}$ . Then  $\lambda_n \geq \theta_k \geq \lambda_n$ , so  $\theta_k = \lambda_n$ . One can show  $\theta_1 = \lambda_1$  in the same manner.

Very little has been written about the unsymmetric Lanczos method. The author is unaware of any error bounds or approximations for the eigenvalues of T comparable to the Kaniel-Paige theorem for the symmetric case. In 1987, Cybenko [1] published an explicit formula for the characteristic polynomials of the  $T_j$ 's in terms of the eigenspace of A. This formula applies to all nondefective matrices A.

Cybenko's Theorem. Let  $\lambda_i$ ,  $u_i$ ,  $v_i$  be the eigenvalues, right eigenvectors, and left eigenvectors of A respectively. Let x and y be arbitrary vectors, and assume A is nondefective. The characteristic polynomial  $c_j(\lambda)$  of the  $j^{th}$  approximating matrix obtained in the Lanczos process satisfies

$$c_j(\lambda) = \sigma \sum_{I \in \Delta n_j} \gamma_{i_1} \gamma_{i_2} \cdots \gamma_{i_j} V^2(\lambda_{i_1}, \lambda_{i_2}, \dots, \lambda_{i_j}) \times (\lambda - \lambda_{i_1})(\lambda - \lambda_{i_2}) \cdots (\lambda - \lambda_{i_j})$$

where  $\sigma$  is a constant and V is the Vandermonde determinant. The factors  $\gamma_j$  are

$$\gamma_j = (y^* u_j)(v_j^* x)$$

See Cybenko [1] for the proof.

Cybenko's theorem sheds more light on the case of the multiple eigenvalues. If A has k distinct eigenvalues, then not only are the extreme eigenvalues of  $T_k$  exact, but <u>all</u> of the eigenvalues are exact.

**Proof.** The characteristic polynomial of  $T_k$  can be written as a sum of terms of the form

$$\gamma_{i_1}\gamma_{i_2}\cdots\gamma_{i_j}V^2(\lambda_{i_1},\lambda_{i_2},\ldots,\lambda_{i_j})\times(\lambda-\lambda_{i_1})(\lambda-\lambda_{i_2})\cdots(\lambda-\lambda_{i_j})$$

If  $\lambda_{i_q} = \lambda_{i_r}$  for some q, r then the Vandermonde determinant of this term will be zero since its matrix will contain two identical rows. The only terms left contain all k distinct eigenvalues as roots.  $\Box$ 

Therefore, if we have a  $1000 \times 1000$  matrix with just two distinct eigenvalues, one can just construct the  $2 \times 2$  matrix  $T_2$  to get both of them exactly. While matrices like this rarely occur in applications, the result is an interesting one.

The problem at hand is to find error bounds or approximations for the eigenvalues of the matrices  $T_j$ . Cybenko's formula turns the problem into a search for the roots of polynomials. A well-known technique for finding such roots is Newton's method. The remainder of this paper will examine the application of one iteration of Newton's method to the characteristic polynomial  $p_j(x)$  of  $T_j$  in order to approximate the eigenvalues of  $T_j$ .

Recall that Newton's method works as follows: given a function f(x) and an initial guess  $x_0$ , then  $x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$  will be a closer approximation to the nearest root than  $x_0$ . Applying this first iteration to Cybenko's formula yields

$$x_{1} = x_{0} - \frac{\sum_{I \in \Delta n_{j}} \gamma_{i_{1}} \cdots \gamma_{i_{j}} V^{2}(\lambda_{i_{1}}, \dots, \lambda_{i_{j}}) \times (x_{0} - \lambda_{i_{1}}) \cdots (x_{0} - \lambda_{i_{j}})}{\sum_{I \in \Delta n_{j}} [\gamma_{i_{1}} \cdots \gamma_{i_{j}} V^{2}(\lambda_{i_{1}}, \dots, \lambda_{i_{j}}) \sum_{I_{p} \in \Delta n(j-1)} (x_{0} - \lambda_{i_{p_{1}}}) \cdots (x_{0} - \lambda_{i_{p_{j-1}}})]}$$
(10)

For the symmetric case, we can create an upper bound for  $T_j$ 's largest eigenvalues  $\theta_j$  by letting  $x_0 = \lambda_n$ . We know this is an upper bound since the characteristic polynomial p(x) will have all real roots, so the concavity of p does not change for  $x \geq \theta_j$ , and we know  $\lambda_n \geq \theta_j$  from the Kaniel-Paige theorem. Thus  $x_1$  will be located between  $\lambda_n$  and  $\theta_j$ . Figure

(2) shows that this bound is a much tighter one than the Kaniel-Paige bounds. In the unsymmetric case, the Newton formula yields just an approximation and not necessarily a bound since some of the eigenvalues may be complex. From Figure (3) one can see that this approximation is also fairly tight. These graphs indicate that the Newton estimate seems to have a lot of potential.

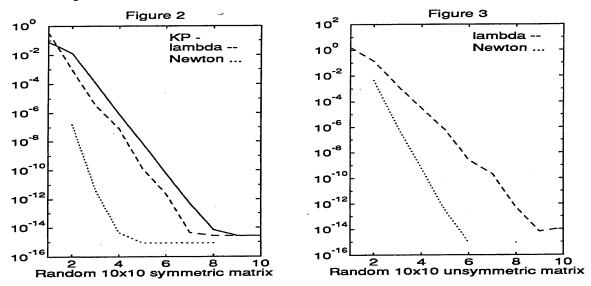


Figure (2) and Figure (3) plot the closeness of the bounds to the actual dominant eigenvalues of the  $T_j$ 's for j=1:10.

To be practical at all, this formula must be simplified so that it does not require prior knowledge of the entire eigenspace. Plugging in  $\lambda_n$  for  $x_0$  causes many of the terms to cancel, but unfortunately this does not provide a simpler expression of equation (10). Some knowledge of the distribution of the eigenvalues can help this simplification.

Consider random matrices whose entries are uniformly distributed between 0 and 1. Such matrices can be generated on Matlab by the command  $\mathbf{A} = \mathrm{rand}(\mathbf{n})$ . A symmetric matrix can be generated from a random matrix A by  $\mathbf{S} = (\mathbf{A} + \mathbf{A^T})/2$ . These matrices have a dominant eigenvalue at approximately  $\frac{n}{2}$ , and the rest are located within a circle of radius  $\sqrt{\frac{n}{6}}$  about the origin (Silverstein [4]). To make things simpler, suppose the initial vector x has equal components in the direction of all the eigenvectors. Then we can cancel the  $\gamma_i$ 's from equation (10). Actually, the choice of a random initial vector should have little impact on the speed of convergence of Lanczos. Regard Figure (4), which plots the convergence of the Lanczos eigenvalues to  $\lambda_n$  for a random initial vector and for one with equal components in the directions of the eigenvectors. The equal components vector gives a bad initial estimate<sup>2</sup> of trace(A)/n, but the convergence rates appear to be roughly the same. Since terms containing  $\lambda_n$  cancel, our Newton formula contains  $\binom{n-1}{i}$  terms in the

 $<sup>2</sup>x^TAx = trace(A)/n$  in the symmetric case, where  $x = \frac{1}{\sqrt{n}}V[1, ..., 1]^T$ . Obviously this guess is not even close to the dominant eigenvalue.

numerator containing j products of the form  $\lambda_n - \lambda_i$ . To maintain the upper bound, we can underestimate the difference by substituting  $(\lambda_n - \sqrt{\frac{n}{6}})^j$ . The denominator consists of  $\binom{n}{j}$  terms containing j-1 products of the form  $\lambda_n - \lambda_i$ . We can overestimate by using  $(\lambda_n + \sqrt{\frac{n}{6}})^{j-1}$ . The Vandermonde determinants contain  $\binom{j}{2}$  products of the form  $\lambda_i - \lambda_j$ . In the numerator these products do not include  $\lambda_n$ , although some in the denominator do. For this fraction, we can initially try  $\frac{\sqrt{\frac{n}{6}}}{\lambda_n + \sqrt{\frac{n}{6}}}$ . Our Newton approximation then becomes

$$x_{1} = \lambda_{n} - \frac{\binom{n-1}{j}}{\binom{n}{j}} \left(\frac{\sqrt{\frac{n}{6}}}{\lambda_{n} + \sqrt{\frac{n}{6}}}\right)^{2\binom{j}{2}} \frac{(\lambda_{n} - \sqrt{\frac{n}{6}})^{j}}{(\lambda_{n} + \sqrt{\frac{n}{6}})^{j-1}}$$

$$= \lambda_{n} - \frac{n-j}{n} \left(\frac{\sqrt{\frac{n}{6}}}{\lambda_{n} + \sqrt{\frac{n}{6}}}\right)^{2\binom{j}{2}} \frac{(\lambda_{n} - \sqrt{\frac{n}{6}})^{j}}{(\lambda_{n} + \sqrt{\frac{n}{6}})^{j-1}}$$
(11)

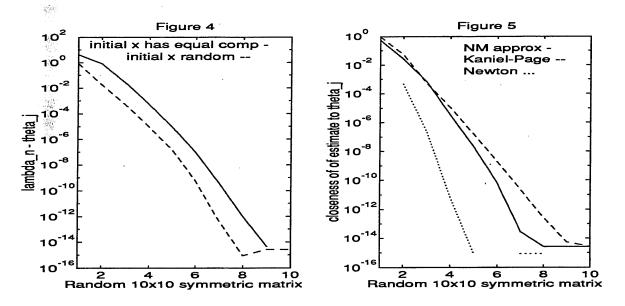


Figure (4) plots the convergence rate  $\lambda_n - \theta_j$  for j = 1:10 for two starting vectors – one with equal components in the directions of all the eigenvectors and one random. Figure (5) plots the closeness of three different bounds to the dominant eigenvalues of the  $T_j$ 's.

The exponent of  $2\binom{j}{2}$  causes this fraction to approach zero very quickly, just as the Lanczos method locks in on the dominant eigenvalue very quickly. For large n, experimentation

seems to show that this formula is still an upper bound for  $\theta_j$  except for  $T_2$ . We can correct this by leaving out the term  $\frac{(\lambda_n - \sqrt{\frac{n}{6}})^j}{(\lambda_n + \sqrt{\frac{n}{6}})^{j-1}}$ , although we lose some initial tightness in doing so. Figure (5) plots the tightness of this approximation versus the Kaniel-Paige bound and the original Newton formula. Much of the tightness from the original Newton's method (before simplification) has been lost already by the estimations, so better estimates of the eigenvalue differences, particularly in the Vandermonde terms, should be an improvement.

Although our formula requires prior knowledge of the dominant eigenvalue, remember that the Kaniel-Paige bound uses three eigenvalues. These formulas can be used to predict the location of  $\theta_j$  given  $\lambda_n$ . This may seem strange since the whole purpose of the Lanczos method is to find the  $\theta_j$ 's to approximate  $\lambda_n$ . Our Newton estimate is best used to give a better understanding of the Lanczos convergence and a general expectation of the accuracy of Lanczos.

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