

ANGULAR MOMENTUM

Orbital angular momentum defined

$$\hat{\mathbf{L}} = \hat{\mathbf{r}} \times \hat{\mathbf{p}} \doteq -i\hbar \hat{\mathbf{r}} \times \nabla$$

$$\hat{L}_x = \hat{y}\hat{p}_z - \hat{z}\hat{p}_y \doteq -i\hbar \left[y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right]$$

$$\hat{L}_y = \hat{z}\hat{p}_x - \hat{x}\hat{p}_z \doteq -i\hbar \left[z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right]$$

$$\hat{L}_z = \hat{x}\hat{p}_y - \hat{y}\hat{p}_x \doteq -i\hbar \left[x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right]$$

$$\hat{L}^2 = \hat{L}_x^2 + \hat{L}_y^2 + \hat{L}_z^2$$

$$\hat{L}_x \doteq i\hbar \left[\sin\phi \frac{\partial}{\partial\theta} + \cot\theta \cos\phi \frac{\partial}{\partial\phi} \right]$$

$$\hat{L}_y \doteq i\hbar \left[-\cos\phi \frac{\partial}{\partial\theta} + \cot\theta \sin\phi \frac{\partial}{\partial\phi} \right]$$

$$\hat{L}_z \doteq -i\hbar \frac{\partial}{\partial\phi}$$

$$\hat{L}^2 \doteq -\hbar^2 \left[\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right]$$

Commutator relations for general angular momentum

$$[\hat{J}_x, \hat{J}_y] = i\hbar \hat{J}_z$$

$$[\hat{J}_y, \hat{J}_z] = i\hbar \hat{J}_x$$

$$[\hat{J}_z, \hat{J}_x] = i\hbar \hat{J}_y$$

$$[\hat{J}_x, \hat{J}^2] = [\hat{J}_y, \hat{J}^2] = [\hat{J}_z, \hat{J}^2] = 0$$

Ladder operators ...

$$\hat{J}_{\pm} = \hat{J}_x \pm i\hat{J}_y$$

$$\hat{J}_+ = \hat{J}_-^\dagger$$

$$\hat{L}_{\pm} \doteq \pm\hbar e^{\pm i\phi} \left[\frac{\partial}{\partial\theta} \pm i \cot\theta \frac{\partial}{\partial\phi} \right]$$

... and their commutation relations

$$[\hat{J}_+, \hat{J}_-] = 2\hbar \hat{J}_z$$

$$[\hat{J}_z, \hat{J}_{\pm}] = \pm\hbar \hat{J}_{\pm}$$

$$[\hat{J}^2, \hat{J}_{\pm}] = 0$$

Other relationships

$$\text{If } \hat{\mathbf{J}} = \hat{\mathbf{L}} + \hat{\mathbf{S}}, \text{ then } \hat{J}^2 = \hat{L}^2 + \hat{S}^2 + 2\hat{\mathbf{L}} \cdot \hat{\mathbf{S}}, \text{ and } \hat{J}^2 = \hat{L}^2 + \hat{S}^2 + \hat{L}_+ \hat{S}_- + \hat{L}_- \hat{S}_+ + 2\hat{L}_z \hat{S}_z$$

$$\hat{J}^2 = \hat{J}_{\mp} \hat{J}_{\pm} + \hat{J}_z^2 \pm \hbar \hat{J}_z$$

$$\hat{J}^2 |jm_j\rangle = j(j+1)\hbar^2 |jm_j\rangle$$

$$\hat{J}_z |jm_j\rangle = m_j \hbar |jm_j\rangle$$

$$m_j = -j, -j+1, \dots, j-1, j$$

$$\hat{J}_{\pm} |jm_j\rangle = \hbar [j(j+1) - m_j(m_j \pm 1)]^{1/2} |j, m_j \pm 1\rangle$$

$$\hat{L}^2 |\ell m_{\ell}\rangle = \ell(\ell+1)\hbar^2 |\ell m_{\ell}\rangle \quad \ell = 0, 1, 2, \dots$$

$$\hat{L}_z |\ell m_{\ell}\rangle = m_{\ell} \hbar |\ell m_{\ell}\rangle$$

$$m_{\ell} = -\ell, -\ell+1, \dots, \ell-1, \ell$$

$$\hat{S}^2 |sm_s\rangle = s(s+1)\hbar^2 |sm_s\rangle$$

$$\hat{S}_z |sm_s\rangle = m_s \hbar |sm_s\rangle$$

$$m_s = -s, -s+1, \dots, s-1, s$$