

ex) find $y = \cos x = f(x)$.

For this case, $\delta y \approx -\sin x \delta x$. Hence

$$\left| \frac{\delta y}{y} \right| \approx k \left| \frac{\delta x}{x} \right| \quad k = \frac{x f'(x)}{f} = -x \tan x$$

$$\therefore \left| \frac{\delta y}{y} \right| = |x| |\tan x| \left| \frac{\delta x}{x} \right| = |x| \left| \frac{\delta x}{x} \right|$$

take $x \sim \frac{\pi}{2}$ for example. We see that $f(x)$ is highly sensitive to perturbations in x . //

CONDITION NUMBER OF MATRIX-VECTOR MULTIPLICATION

Take: $x \xrightarrow{A} y$ i.e. $y = Ax$
 $A \in \mathbb{C}^{m \times n}$

$$\begin{aligned} \kappa_2 &= \sup_{\delta x} \left(\frac{\|A(x + \delta x) - Ax\| \|x\|}{\|Ax\| \|\delta x\|} \right) \\ &= \sup_{\delta x} \frac{\|A \delta x\| \|x\|}{\|\delta x\| \|Ax\|} \end{aligned}$$

$$\therefore k = \|A\| \frac{\|x\|}{\|Ax\|}$$

If A is square & nonsingular

$$\frac{\|x\|}{\|Ax\|} \leq \|A^{-1}\|$$

$$\therefore k = \alpha \|A\| \|A^{-1}\|$$

$$\alpha = \frac{\|x\|}{\|Ax\|} / \|A^{-1}\| \sim 1$$

If $A \in \mathbb{C}^{m \times n}$ use

$$k = \alpha \|A\| \|A^{\dagger}\| //$$

Thm: Let $A \in \mathbb{C}^{m \times n}$ be nonsingular & $Ax = b$.

The problem of computing b , given x has

Condition number

$$k = \|A\| \frac{\|x\|}{\|b\|} \leq \|A\| \|A^{-1}\|$$

with respect to perturbations in x .

The problem of finding x , given b :

$$k = \|A^{-1}\| \frac{\|b\|}{\|x\|} \leq \|A\| \|A^{-1}\| //$$

CONDITION NUMBER OF
A MATRIX

$$k(A) \equiv \|A\| \|A^{-1}\|$$

if k is small ~ 1 "well-conditioned"
if k is very large "ill-conditioned"
(k can be ∞)

S'pose $\|\cdot\|_2$ then

$$\|A\|_2 = G_1$$

$$\|A^{-1}\| = \frac{1}{G_m}$$

$$\therefore k(A) = \frac{G_1}{G_m}$$

it "measures" the ellipticity of the hyperellipse. //

What happens when $A \rightarrow A + \delta A$?

How do we estimate the sensitivity

of outcomes to "errors" in A ?

let's fix b .

$$(A + \delta A)(x + \delta x) = b$$

$$Ax + \delta Ax + A\delta x + \delta A\delta x = b$$

$$\delta Ax + A\delta x + \underbrace{\delta A\delta x}_{\text{too small}} = 0$$

too small $\therefore$ remove

$$\therefore \delta Ax = -A\delta x$$

$$\delta x = -A^{-1}(\delta A)x$$

Bound δx :

$$\|\delta x\| \leq \|A^{-1}\| \|\delta A\| \|x\|$$

Want $\frac{\delta x}{x} / \frac{\delta A}{A}$:

$$\frac{\frac{\|\delta x\|}{\|x\|}}{\frac{\|\delta A\|}{\|A\|}} \leq \|A^{-1}\| \|\delta A\| = \kappa(A)$$

$\therefore \kappa(A)$ captures sensitivity to errors in A

//

FLOATING POINT NUMBERS

Lecture 13 Finite-Precision Computing

Finite Precision Machine (double precision binary machine)

max positive number $\sim 1.79 \cdot 10^{308}$

min positive number $\sim 2.23 \cdot 10^{-308}$

resolution (largest gap) $= 2^{-52} \sim 2.22 \cdot 10^{-16}$

representation (binary, octal, hex, decimal, etc)

the IEEE standard is binary (memory representation)

Floating Point Representation: means position of decimal (or binary point) "moves" (stored separately). The gaps between the numbers will scale in proportion to size of the numbers.

$fl(x)$ is the "floating point representation" of the number x

Representation: consists of 4 fields:

$\left\{ \begin{array}{l} \beta \text{ base} \\ t \text{ precision} \\ e \in [L, U] \text{ exponent} \\ \text{sign indicator} \end{array} \right. //$

$$x = \pm \left(\frac{d_1}{\beta} + \frac{d_2}{\beta^2} + \dots + \frac{d_t}{\beta^t} \right) \beta^e$$

$$= \pm \underbrace{0.d_1 d_2 \dots d_t}_{\text{Normalized notation}} \beta^e$$

Normalized notation

The normalized representation in decimal is 0. The normalized representation in binary is 1.

$$0 \leq d_i \leq \beta - 1 \quad i = 0, 1, \dots, t$$

$$e \in [1, U]$$

ex) Normalized representation

$$100 \text{ in } \beta = 10 \quad 0.1 \cdot 10^3$$

Hexadecimal

$$\beta = 16 \quad 0 \leq d_i \leq 15$$

$$d_i = 0, 1, 2, \dots, 9, A, B, C, D, E, F$$

$$\begin{aligned} (23A.D)_{16} &= 2 \cdot 16^2 + 3 \cdot 16^1 + 10 \cdot 16^0 + 13 \cdot 16^{-1} \\ &= 512 + 48 + 10 + 0.8125 = 570.8125 \end{aligned}$$

Binary $\beta = 2 \quad 0 \leq d_i \leq 1$

$$\text{ex) } (1101.0011)_2 = 10.11010011 \cdot 2^4$$

$$\begin{aligned} &= 1 \cdot 2^3 + 1 \cdot 2^2 + 0 \cdot 2^1 + 1 \cdot 2^0 + 0 \cdot 2^{-1} + 1 \cdot 2^{-2} + 1 \cdot 2^{-3} + 1 \cdot 2^{-4} \\ &= 13.1875 \end{aligned}$$

ex) Convert $\frac{2}{3}$ to binary:

$$\frac{2}{3} = (0.a_1a_2\dots)_2$$

$\times 2$

$$\frac{4}{3} = (a_1.a_2\dots)_2 \rightarrow a_1 = 1$$

subtract 1 from b.s.

$$\frac{4}{3} - 1 = \frac{1}{3} = (0.a_2\dots)_2$$

$\times 2$

$$\frac{2}{3} = (a_2.a_3\dots)_2 \quad a_2 = 0$$

$\times 2$

$$\frac{4}{3} = (a_3.a_4\dots)_2 \quad a_3 = 1$$

etc

$$\frac{2}{3} = (0.1010\dots)_2$$

IEEE 754-1985 Standard

	β	t	L	U	wordlength
HP (Half)	2	11	-14	15	16
SP (single)	2	24	-126	127	32
DP (double)	2	53	-1022	1023	64
QP (quad)	2	113	-16383	16384	128

Example SP 32 bit

sign	exponent	normalized mantissa
1 bit	8 bits	23 bits

↑ first entry is an implied 1

└────────────────┘
24 bit mantissa

UFL (underflow) β^L

OFL (overflow) $\beta^{UH} (1 - \beta^{-L})$

In binary $x = (-1)^s q \cdot 2^m$

$s=0$ positive $s=1$ negative

$q = (1.f)$

↑ implied (Normalized binary notation)

$m = e - U$

$m = e - 217$ (for 32-bit)
8-bit biased

Range $0 < e < 11111111 = 2^8 - 1 = 255$

The number 0 is reserved for ± 0

" " 255 " " " for NaN

$m = e - 127 \therefore m \in [-126, 127]$

The smallest positive # $2^{-126} \sim 1.2 \cdot 10^{-38}$

The largest positive # $(2-2^{-23}) \times 2^{127} \approx 3.4 \cdot 10^{38}$

The least significant bit 2^{-23}

$$\text{EPS} = \frac{1}{2} \beta^{1-t} \quad (\text{rounding})$$

Machine epsilon

$$\text{EPS}_{\text{sp}} = \frac{1}{2} 2^{-23} = 2^{-24} \approx 6 \cdot 10^{-8}$$

$$\text{EPS}_{\text{dp}} = \frac{1}{2} 2^{-53} \sim 1 \cdot 10^{-16}$$

The $\frac{1}{2}$ results from using rounding approximation scheme.