

SIMILARITY TRANSFORMATIONS

Thm: let A, B be $n \times n$ matrices. They are **similar** if they have the same characteristic polynomial.

For A the characteristic polynomial is $\det(A - \lambda I) = p(\lambda) = 0$

If A, B are similar then the decomposition

$$V^{-1}AV = B$$

is possible, where V is an invertible matrix

$V^{-1}AV$ is the similarity transformation.

Pf:
$$\begin{aligned} B - \lambda I &= V^{-1}AV - \lambda I \\ &= V^{-1}AV - \lambda V^{-1}V \end{aligned}$$

$$B - \lambda I = V^{-1} (A - \lambda I) V$$

$$\det(B - \lambda I) = \det[V^{-1} (A - \lambda I) V]$$

$$\det(B - \lambda I) = \det(V^{-1}) \det(A - \lambda I) \det V$$

$$\text{but } \det(V^{-1}) \det(V) = 1$$

$$\therefore \det(B - \lambda I) = \det(A - \lambda I) //$$

$\det(A - \lambda I) = \det(B - \lambda I)$ does not necessarily
imply that the e-values of A and B
are the same //

DIAGONALIZATION of a Square matrix
is an application of similarity transformations

$$\text{Factor } A = V \Lambda V^{-1} \quad (\S)$$

Λ is a diagonal matrix

$$A = V \Lambda V^{-1}$$

Λ $n \times n$ matrix

$$\Lambda = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

λ_i are the eigenvalues of A ,

V is composed of column corresponding to e'vectors of A .

Not every $n \times n$ matrix can be diagonalized:

If n LI eigenvectors cannot be found then A does not have a diagonalization.

$$\Lambda = \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{bmatrix} \text{ for an } n \times n \text{ matrix}$$

λ_i can be complex

If (†) is possible we say A is diagonalizable

The V is clearly made up of the e'vectors of A .

ex) $A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix}$ Find $A = V\Lambda V^{-1}$
or $AV = V\Lambda$

1. Find e'values of A

$$p(\lambda) = (\lambda - 1)(\lambda + 2)^2 = 0$$

$$\lambda_1 = 1, \lambda_2 = -2, \lambda_3 = -2$$

2. Find e'vectors of A

$$\begin{aligned}\lambda_1 = 1 \quad (1-1)x_1 + 3x_2 + 3x_3 &= 0 \\ -3x_1 - 4x_2 - 3x_3 &= 0 \\ 3x_1 + 3x_2 + 0x_3 &= 0\end{aligned}$$

$$v_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$\begin{aligned}\lambda_2 = 2 \quad (1-2)x_1 + 3x_2 + 3x_3 &= 0 \\ -3x_1 - 3x_2 - 3x_3 &= 0 \\ 3x_1 + 3x_2 + 0x_3 &= 0\end{aligned}$$

$$v_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \quad v_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

v_1, v_2, v_3 are LI

$$\text{for } V = \begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix} = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

check that $AV = VA$



LINEAR DIFFERENCE EQUATIONS

Assume we have a sequence y_k $k=0,1,2,\dots$

Propose an operator E^n (displacement)

$$E^0 y_k = y_k$$

$$E^1 y_k = y_1, y_2, \dots, y_{k+1}, \dots$$

$$E^n E^m y_k = E^n [y_{k+m}] = y_{k+m+n}$$

etc

A linear difference equation (a recurrence equation)

$$P(E) y_k = z_k \quad k=0,1,2,\dots$$

$P(E)$ is a polynomial of displacement operators, commonly with constant

coefficient: $P(E) = a_n E^n + a_{n-1} E^{n-1} \dots + a_0 E^0$

$z_k = 0$ (homogeneous linear difference equation)

$z_k \neq 0$ (known) non-homogeneous problem,

ex) $P(E) = 6E^3 - 2E^2 + E^0$, $z_k = 0$ then

$P(E) y_k = 0$, a homogeneous equation:

$$(6E^3 - 2E^2 + E^0) y_k = 0$$

$$6y_{k+3} - 2y_{k+2} + y_k = 0 \quad k = 0, 1, 2, \dots$$

$$y_{k+3} = \frac{1}{3} y_{k+2} - \frac{1}{6} y_k$$

need 3 starting values, say y_0, y_1, y_2

An application of diagonalization to
solving $\underline{x}_{k+1} = A \underline{x}_k$

A is a matrix of constants

$$\underline{x}_k = A \underline{x}_{k-1}$$

General solution to $P(\epsilon) y_k = z_k$

is $y_k = y_k^H + y_k^P$

where $P(\epsilon) y_k^H = 0$

yields the homogeneous part

$$P(\epsilon) y_k^P = z_k$$

Solve the homogeneous problem:

$$P(\epsilon) y_k = 0$$

A good guess $y_k = r^k$ for some r .

ex) $(\epsilon^3 - 2\epsilon^2 - 5\epsilon + 6) y_k = 0$

(*) $y_{k+3} - 2y_{k+2} - 5y_{k+1} + 6y_k = 0$

Assume $y_k = r^k$

(this guess works when roots are not repeated)

if it is a solution, it satisfies (*):

$$r^{k+3} - 2r^{k+2} - 5r^{k+1} + 6r^k = 0$$

$$r^k [r^3 - 2r^2 - 5r + 6] = 0$$

$r=0$ is always a solution, but want nontrivial solution

$$r^3 - 2r^2 - 5r + 6 = 0$$

$$(r-1)(r+2)(r-3) = 0 \quad \text{characteristic eq.}$$

3 roots: 1, -2, 3

$$v_1 = 1^k \quad v_2 = (-2)^k \quad v_3 = 3^k$$

$$\therefore y_k = a 1^k + b (-2)^k + c 3^k \quad k=0,1,\dots$$

a, b, c are constants.

To find a, b, c , given y_k for 3 different k 's.

In this example the roots are distinct & real.

Suppose roots are complex (conjugate pairs) $r_1 = \alpha + i\beta$ $r_2 = \alpha - i\beta$

Suppose also r_3 is real

$$y_k = A r_3^k + B \alpha^k \cos(\beta k) + C \alpha^k \sin(\beta k)$$

is the assumed form of the solution...

For repeated roots, use "reduction of order"

Suppose r_1 is repeated

r_1^k is solution associated with this root.

$$r_2 = u(k) r_1^k$$

r_2 has to satisfy the difference equation.
this yields a difference equation for $u(k)$.

Reducing A Difference Equation to FIRST ORDER (NORMAL FORM)

Take $y_{k+3} - 2y_{k+2} - 5y_{k+1} + 6y_k = 0$

$$\text{let } \underline{x}_k = \begin{bmatrix} y_k \\ y_{k+1} \\ y_{k+2} \end{bmatrix}$$

(*)

$$y_{k+3} = 2y_{k+2} + 5y_{k+1} - 6y_k$$

$$\underline{x}_{k+1} = \begin{bmatrix} y_{k+1} \\ y_{k+2} \\ y_{k+3} \end{bmatrix} = \begin{bmatrix} 0 & y_{k+1} & 0 \\ 0 & 0 & y_{k+2} \\ \underbrace{-6y_k \quad 5y_{k+1} \quad 2y_{k+2}}_{\text{using (*)}} \end{bmatrix}$$

$$(\exists) \quad \underline{x}_{k+1} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & 5 & 2 \end{bmatrix} \underline{x}_k = \underline{A} \underline{x}_k$$

Need to be able to solve $(\exists)$. The general solution

$$\underline{x}_k = C y_k$$

$$C = \begin{bmatrix} 0 & 1 & & & \\ & \ddots & \ddots & & \\ & & 0 & & \\ & & & \ddots & \\ & & & & 0 & \\ -a_n & -a_{n-1} & \dots & & & -a_1 \end{bmatrix}$$

i.e.

$$y_{k+n} + a_1 y_{k+n-1} + a_2 y_{k+n-2} \dots a_{n-1} y_{k+1} + a_n y_k = 0$$

One can solve $(\exists)$ numerically. Sometimes one can find closed form solutions.

We're considering using **DIAGONALIZATION**

$$\underline{x}_{k-1} = A \underline{x}_{k-2}$$

$$\underline{x}_{k+1} = A(\underline{x}_k) = A(A(\underline{x}_{k-2})) \dots$$

So generally $\boxed{\underline{x}_m = A^m \underline{x}_0}$

Suppose $A = V \Lambda V^{-1}$ is possible

$$\boxed{\underline{x}_m = V \Lambda^m V^{-1}}$$

$$\Lambda^m = \begin{bmatrix} \lambda_1^m & & \\ & \lambda_2^m & \\ & & \ddots \\ & & & \lambda_n^m \end{bmatrix}$$

ex) $A = \begin{bmatrix} 6 & -1 \\ 2 & 3 \end{bmatrix} \quad V = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \quad V^{-1} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$

$$\Lambda = \begin{bmatrix} 5 & 0 \\ 0 & 4 \end{bmatrix}$$

$$\text{Find } A^2 = (V \Lambda V^{-1}) \underbrace{(V \Lambda V^{-1})}_{I}$$

$$= V \Lambda^2 V^{-1}$$

$$A^3 = V \Lambda^3 V^{-1}$$

$$A^m = V \Lambda^m V^{-1}$$

$$= \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 5^m & 0 \\ 0 & 4^m \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 2 \cdot 5^m - 4^m & -5^m + 4^m \\ 2 \cdot 5^m - 2 \cdot 4^m & -5^m + 2 \cdot 4^m \end{bmatrix}$$