

Inverse of a Partitioned Matrix:

There is no general methodology for partitioned matrices. Here, we get the flavor of how exploiting partitioning might be a good idea.

Take the special case

$$A = \begin{bmatrix} A_{11} & A_{12} \\ \emptyset & A_{22} \end{bmatrix} \quad A_{22} \in \mathbb{R}^{q \times q}, \quad A_{11} \in \mathbb{R}^{p \times p}$$

Goal: find A^{-1} (assume A^{-1} exists):

Using row echelon operations, find a matrix B s.t.

$$\begin{bmatrix} A_{11} & A_{12} \\ \emptyset & A_{22} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} I_p & \emptyset \\ \emptyset & I_q \end{bmatrix}$$

Perform matrix multiplication:

$$\textcircled{2} \quad \left\{ \begin{array}{l} A_{11}B_{11} + A_{12}B_{21} = I_p \quad (\dagger) \\ A_{22}B_{21} = \emptyset \Rightarrow B_{21} = \emptyset \text{ since } A_{22} \neq \emptyset. \end{array} \right.$$

$$\textcircled{1} \quad \left\{ \begin{array}{l} A_{11}B_{12} + A_{12}B_{22} = \emptyset \quad (\ddagger) \\ A_{22}B_{22} = I_q \Rightarrow B_{22} = A_{22}^{-1} \in \mathbb{R}^{q \times q} \end{array} \right.$$

That $B_{12} = \Delta_{12}^{-1}$ does not tell us what B_{22} is. We still will have to solve for it.

Use (4) in ①

$$\Delta_{11} B_{12} + \Delta_{12} B_{22} = \phi$$

$$\text{or } \Delta_{11} B_{12} = -\Delta_{12} B_{22} = -\Delta_{12} \Delta_{22}^{-1}$$

hence
$$B_{12} = -\Delta_{11}^{-1} \Delta_{12} \Delta_{22}^{-1}$$

Again, we need to find Δ_{11}^{-1} as well.

$$\therefore \Delta^{-1} = \begin{bmatrix} \Delta_{11} & \Delta_{12} \\ 0 & \Delta_{22} \end{bmatrix}^{-1} = \begin{bmatrix} \Delta_{11}^{-1} & -\Delta_{11}^{-1} \Delta_{12} \Delta_{22}^{-1} \\ 0 & \Delta_{22}^{-1} \end{bmatrix}$$

What's gained? by direct means computing Δ^{-1} is $O(N^3)$
where $N = p+q$. Computing Δ_{11}^{-1} is $O(p^3)$ and $\Delta_{22}^{-1} = O(q^3)$.

Much cheaper. Compare $O((p+q)^3)$ to $O(p^3) + O(q^3)$.

We have not talked about numerical stability, but one can gain numerical stability (in some cases).

MATRIX FACTORIZATION

There are all kinds of factorizations:

LU, Cholesky, QR, SVD, ILU, etc

LU factorization

As we'll see,

Can be related to matrix multiplication

by matrices that effect row reduction:

Elementary Matrices : (simple) matrices

that effect row operations on another matrix

Elementary Matrix

$$\text{ex)} \quad A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad \& \quad E_1 = \begin{bmatrix} 1 & 0 \\ -4 & 1 \end{bmatrix}$$

$$E_1 A = \begin{bmatrix} 1 & 0 \\ -4 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ -4c + c & -4b + d \end{bmatrix}$$

So E_1 applied to A did the following:

added : $-4(\text{row } 1)$ to row 2

left unchanged: row 1 = row 1



So the many row operations, applied to some matrix A , can be written as the LEFT product $E_p E_{p-1} E_{p-2} \dots E_2 E_1 A$

[If $FE = I \Rightarrow F$ is the "reverse" of E .]
 Not every elementary matrix has an inverse.
 However, the product of these could:

An example of find A^{-1} , here $A \in \mathbb{R}^{n \times n}$

If $(E_p E_{p-1} \dots E_1) A = I_n$

then $E_p E_{p-1} \dots E_1 = A^{-1}$ (if it exists)

LU Factorization

In matlab

`lu(A)` gives the LU factorization of the matrix

$A \in \mathbb{R}^{n \times n}$

$$A = \begin{bmatrix} 1 & 1 & 0 \\ x & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$L \in \mathbb{R}^{n \times n}$

$$\begin{bmatrix} x & x & x \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$U \in \mathbb{R}^{n \times n}$

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \in \mathbb{R}^{n \times n}$$

Why is this a good idea?

ex) $\text{(*) } Ax = b$, b is known. Want to solve for unknown x . Here $A \in \mathbb{R}^{n \times n}$. Then

$$x = A^{-1}b, \text{ as we know.}$$

Use LU factorization

let $A = L U$
replace into $(*)$

$$LUx = b$$

$$L(Ux) = b \Rightarrow \begin{cases} Lz = b & (\text{*}) \\ Ux = z & (\$) \end{cases}$$

$$\text{(*)} \quad \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

Easily find \underline{x} ($O(n)$ ops)

use it in \underline{b} :

$$\begin{pmatrix} \underline{A} & \underline{X} \\ \underline{0} & \end{pmatrix} \begin{pmatrix} \underline{x}_1 \\ \vdots \\ \underline{x}_n \end{pmatrix} = \begin{pmatrix} \underline{z}_1 \\ \vdots \\ \underline{z}_n \end{pmatrix}$$

to solve for \underline{x} is $O(n)$ ops.

So, once we have done the LU factorization
(which generally takes $O(N^2)$ operations), then
we can solve problems of the form

$$\underbrace{\underline{A}}_n \underline{x}_n = \underline{b}_n$$

$$n=1, 2, \dots$$

Here \underline{A} is known, and \underline{b}_n is known.
You factor $\underline{A} = \underline{L}\underline{U}$ once, then solving
for each \underline{x}_n is cheap. //