

FINALEXAM TOPICS/SECTIONS

II 2.2 - 2.6

III 3.1 - 3.8

VI 6.1 - 6.6

CHAPTER II 1st order ODE

Separable

Homogeneous

Exact

Modeling { population
tank
Cooling, Gravity/Drain

Existence & Uniqueness

Classification

Chapter III 2nd order ODE's

C.C.

E.E.

Homogeneous / Non-homogeneous

Existence & Uniqueness
(Wronskian)

MVC

Variation of Parameters

Reduction of order

Mechanical Vibrations
Electrical

Chapter VI

Laplace

Inverse

Impulse functions

Step functions

{ Convolution

{ Integral Equations

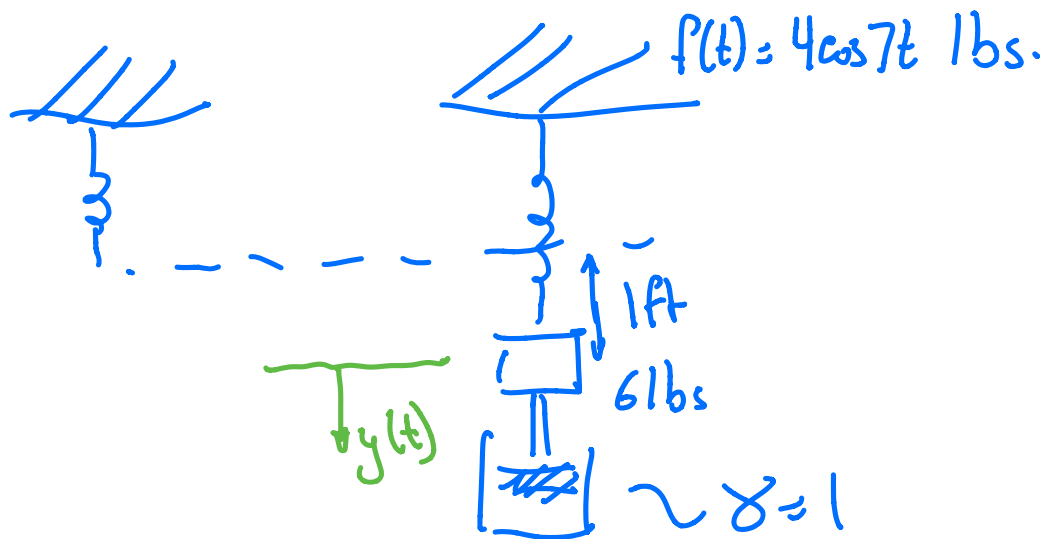
IVP

Forced/Damped Oscillator:

Damped $\gamma = 1$ Spring mass system with mass 6 lbs.

The mass travels 1 ft when the spring is loaded.

The mass is suddenly set in motion at $t=0$ by an external force of $4 \cos 7t$ lb. Determine $y(t)$. The mass starts at $y(0) = -\frac{1}{2}$ ft & $y'(0) = 0$



① Find spring constant:

$$mg = k \ell$$

$$6 \text{ lb} = k \cdot 1 \text{ ft} \quad k = 6 \text{ lb/ft}$$

$$m y'' = -\gamma y' - k y + f(t)$$

$$y'' + \frac{\gamma}{m} y' + \frac{k}{m} y = \frac{f(t)}{m}$$

$$m \text{ (slugs)} = \frac{6 \text{ lb}}{32 \text{ ft/s}^2} = m$$

$$y'' + \frac{1}{m} y' + \omega^2 y = F(t) \quad \text{ODE}$$

$$\omega^2 \equiv \frac{k}{m} = \frac{6}{6/32} = 32$$

$$\text{let } \delta = \frac{1}{m} \text{ is the damping} = \frac{32}{6}$$

$$F(t) = \frac{1}{m} 4 \cos 7t = \frac{64}{3} \cos 7t = \beta \cos 7t$$

$$\text{I.C. } y(0) = -\frac{1}{2} \quad y'(0) = 0 :$$

General solution:

$$y(t) = y_H(t) + y_p(t)$$

$$y_H'' + \delta y_H' + \omega^2 y_H = 0$$

$$y_H = e^{\alpha t}$$

$$\alpha^2 + \delta \alpha + \omega^2 = 0$$

$$c_1 e^{i\omega_d t} + c_2 e^{-i\omega_d t} \quad \alpha_{1,2} = -\frac{\delta}{2} \pm \frac{1}{2} \sqrt{\delta^2 - 4\omega^2}$$

$$= -\frac{\delta}{2} \pm i\omega_d \quad \omega_d = \frac{1}{2} \sqrt{4\omega^2 - \delta^2}$$

$$y_H = (c_1 \cos \omega_d t + c_2 \sin \omega_d t) e^{-\frac{\delta}{2} t}$$

$$y_p'' + \delta y_p' + \omega^2 y_p = \beta \cos(7t)$$

$$\text{let } y_p = A \cos(7t) + B \sin(7t)$$

$$y_p' = -7A \sin(7t) + B7 \cos(7t)$$

$$y_p'' = -7^2 A \cos(7t) - 7^2 B \sin(7t)$$

$$y_p'' = -7^2 y_p$$

$$-7^2 y_p + \delta [-7A \sin 7t + B7 \cos 7t] + \omega^2 y_p = \beta \cos(7t)$$

$$(\omega^2 - 7^2) y_p + \delta 7 [-A \sin 7t + B \cos 7t] = \beta \cos(7t)$$

Match $\cos(7t)$:

$$(\omega^2 - 7^2) A + \delta 7 B = \beta$$

$$(\omega^2 - 7^2) B - \delta 7 A = 0$$

Transient Portion
(dies off as $t \rightarrow \infty$)

$$y = (c_1 \cos \omega_0 t + c_2 \sin \omega_0 t) e^{-\frac{\delta}{2} t} + A \cos 7t + B \sin 7t$$

Apply I.C.

$$y(0) = c_1 + A = -\frac{1}{2} \Rightarrow c_1 = -A - \frac{1}{2}$$

$y'(0)$ determines c_2 .

Consider

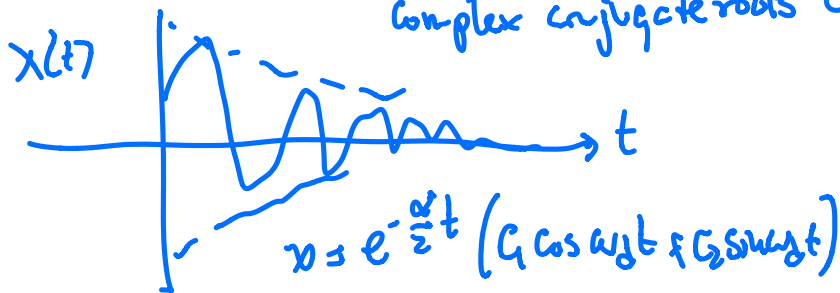
$$x'' + \alpha x' + \omega^2 x = 0$$

$$x = c_1 e^{q_1 t} + c_2 e^{q_2 t}$$

$$\theta_{1,2} = -\frac{\alpha}{2} \pm \frac{1}{2} \sqrt{\alpha^2 - 4\omega^2}$$

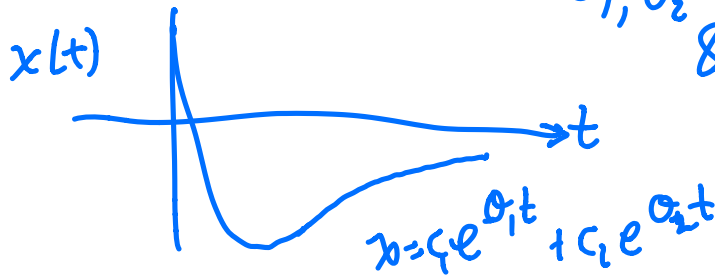
if $4\omega^2 > \alpha^2$ underdamped

complex conjugate roots θ_1, θ_2



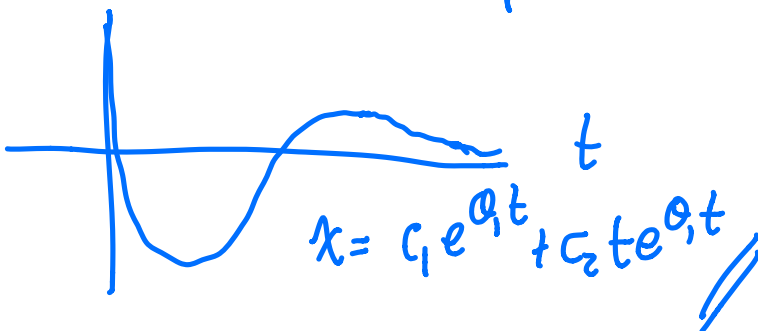
if $4\omega^2 < \alpha^2$ overdamped

θ_1, θ_2 are real & unequal



if $4\omega^2 = \alpha^2$ critically damped

real & equal



E.E. $\alpha x^2 y'' + \beta x y' + \gamma y = 0$ $m^2 - m + \frac{\beta}{\alpha} m + \frac{\gamma}{\alpha} = 0$
 $y = x^m$ $m^2 + \left(\frac{\beta-\alpha}{\alpha}\right)m + \frac{\gamma}{\alpha} = 0$
 $\alpha(m-1)m + \beta m + \gamma = 0$ roots $m_{1,2} = -\frac{1}{2\alpha}(\beta-\alpha) \pm \frac{1}{2\alpha}\sqrt{(\beta-\alpha)^2 - 4\alpha\gamma}$

if roots are c.c.

$$y = [C_1 \cos(\omega_d \ln x) + C_2 \sin(\omega_d \ln x)] x^{-c}$$

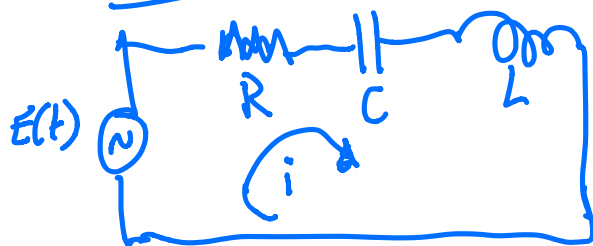
if roots are distinct & unequal

$$y = C_1 x^{m_1} + C_2 x^{m_2}$$

if roots are equal

$$y = C_1 x^m + C_2 \ln x x^m$$

Electrical Circuit (LRC)



$$E(t) = iR + \frac{Q}{C} + L \frac{di}{dt}$$

$$E(t) = \frac{dQ}{dt} R + \frac{Q}{C} + L \frac{d^2Q}{dt^2}$$

$$i = \frac{dQ}{dt}$$

$$i = \frac{dQ}{dt}$$

$$E''(t) = \frac{di}{dt} R + \frac{1}{C} i + L \frac{d^2 i}{dt^2}$$

I.C. $Q(0)$; $Q'(0) = i(0)$ are given.

Laplace Transform:

$$\mathcal{L}(\sin \omega t) = \mathcal{L}\left(\frac{e^{i\omega t} - e^{-i\omega t}}{2i}\right)$$

$$\frac{1}{2i} \mathcal{L}(e^{i\omega t}) - \frac{1}{2i} \mathcal{L}(e^{-i\omega t})$$

$$\mathcal{L}(f(t)) = \int_0^{\infty} e^{-st} f(t) dt$$

$$\mathcal{L}(e^{i\omega t}) = \int_0^{\infty} e^{-st} e^{i\omega t} dt$$

$$= \int_0^{\infty} e^{-(s-i\omega)t} dt = \frac{1}{-(s-i\omega)} e^{-(s-i\omega)t} \Big|_0^{\infty}$$

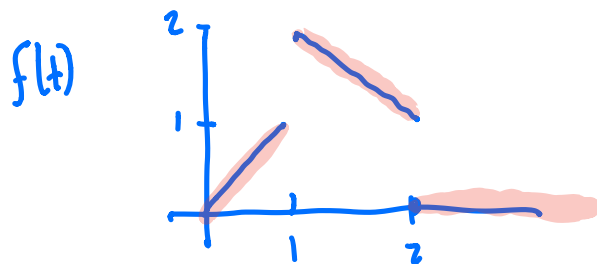
$$= \frac{1}{(s-i\omega)}$$

$$\mathcal{L}(\sin \omega t) = \frac{1}{2i} \left[\frac{1}{s-i\omega} - \frac{1}{s+i\omega} \right]$$

$$= \frac{1}{2i} \frac{s+i\omega - s+i\omega}{s^2+\omega^2} = \frac{1}{2i} \frac{2i\omega}{s^2+\omega^2} = \frac{\omega}{s^2+\omega^2}$$

Find $\mathcal{L}(f(t))$

$$f(t) = \begin{cases} t & 0 \leq t < 1 \\ 3-t & 1 \leq t < 2 \\ 0 & t \geq 2 \end{cases}$$



$$f(t) = [\mu_0(t) - \mu_1(t)]t + [\mu_1(t) - \mu_2(t)](3-t)$$

$$= \mu_0(t)t - \mu_1(t)t + \dots$$

$$= \mu_0(t)t - \mu_1(t)(t-1) - \mu_1(t) + 3\mu_1(t) - 3\mu_2(t) - \mu_1(t)t + \mu_2(t)t$$

$$\mu_0(t)t - \mu_1(t)(t-1) - \mu_1(t) + 3\mu_1(t) - 3\mu_2(t) - \mu_1(t)(t-1) - \mu_1(t) + \mu_2(t)(t-2) + 2\mu_2(t)$$

Convolution Theorem

$$\int_0^t f(t-\tau)g(\tau)d\tau = \mathcal{L}^{-1}(F(s)G(s))$$

Integral Equation

Find solution of $\varphi(t)$

$$\mathcal{L}\left\{ \varphi(t) + \int_0^t (t-\tau)\varphi(\tau)d\tau = 1 \right\}$$

$$\text{let } \Phi(s) = \mathcal{L}(\varphi)$$

$$F(s) = \mathcal{L}(t) = \frac{2}{s^2}$$

$$\Phi(s) + F(s)\Phi(s) = \frac{1}{s}$$

$$\Phi(s) \left[1 + \frac{2}{s^2} \right] = \frac{1}{s}$$

$$\Phi(s) = \frac{1}{s} \cdot \frac{1}{1 + 2/s^2} = \frac{1}{s} \cdot \frac{s^2}{s^2 + 2}$$

$$\mathcal{L}^{-1}(\Phi(s)) = \varphi(t)$$