

Ladder operators  
Spherical harmonics

Last time:  $\vec{L}^2 |l, m\rangle = \hbar^2 l(l+1) |l, m\rangle$

$l \geq 0$   $L_z |l, m\rangle = \hbar m |l, m\rangle$

$Y_l^m(\theta, \varphi) = \langle \vec{n} | l, m \rangle$   $m = 0, \pm 1, \pm 2, \dots$

Introduce ladder operators  $L_{\pm} = L_x \pm iL_y$

From HW #1  $\Rightarrow L_{\mp} L_{\pm} = \vec{L}^2 - L_z^2 \mp \hbar L_z$

$\Downarrow$   
 $\langle l, m | \vec{L}^2 - L_z^2 \mp \hbar L_z | l, m \rangle = \hbar^2 l(l+1) - \hbar^2 m^2 \mp \hbar^2 m = \hbar^2 (l(l+1) - m(m \pm 1)) = \hbar^2 (l \mp m)(l \pm m + 1)$

From another side,

$L_{\pm}^{\dagger} = L_{\mp}$

$\langle l, m | L_{\mp} L_{\pm} | l, m \rangle = \langle l, m | L_{\pm}^{\dagger} L_{\pm} | l, m \rangle =$

$= \| L_{\pm} | l, m \rangle \|^2 \geq 0 \Rightarrow \underline{(l \mp m)(l \pm m + 1) \geq 0}$

show  $\Rightarrow$

$-l \leq m \leq l$  |  $\leftarrow$  prove this to yourself!!

$$\text{When } m=l \Rightarrow \|L_+ |l, l\rangle\| = 0$$

$$\Downarrow \\ \underline{L_+ |l, l\rangle = 0}$$

$$\text{Similarly, } \underline{L_- |l, -l\rangle = 0}$$

$$\text{Since } [\vec{L}^2, L_i] = 0 \Rightarrow [\vec{L}^2, L_{\pm}] = 0 \Rightarrow$$

$$\Rightarrow \vec{L}^2 L_{\pm} |l, m\rangle = L_{\pm} \vec{L}^2 |l, m\rangle = \hbar^2 l(l+1) |l, m\rangle$$

$$\cdot \underline{L_{\pm} |l, m\rangle} \Rightarrow \vec{L}^2 |\psi\rangle = \hbar^2 l(l+1) |\psi\rangle$$

$\Downarrow$   
So,  $L_{\pm}$  operators acting on a state do not change  $l$   
What about  $m$ ?  $\Rightarrow$

$$L_z L_{\pm} |l, m\rangle = ?$$

$$\text{From HW \#1} \Rightarrow [L_z, L_{\pm}] = \pm \hbar L_{\pm} \Rightarrow$$

$$L_z L_{\pm} |l, m\rangle = L_{\pm} L_z |l, m\rangle \pm \hbar L_{\pm} |l, m\rangle = \hbar m L_{\pm} |l, m\rangle \pm \hbar L_{\pm} |l, m\rangle$$

$$\textcircled{=} \hbar (m \pm 1) \underbrace{L_{\pm} |l, m\rangle}_{|\psi\rangle} \Rightarrow L_z |\psi\rangle = \hbar (m \pm 1) |\psi\rangle \quad (5)$$

$L_{\pm}$  change the state  $\Leftarrow$   
from  $|l, m\rangle$  to  $|l, m \pm 1\rangle$

$$|\psi\rangle = \underset{\substack{\uparrow \\ \text{const}}}{c_{\pm}} |l, m \pm 1\rangle$$

From page 1  $\Rightarrow \|L_{\mp} |l, m\rangle\|^2 = \hbar^2 (l \pm m)$

$$(l \mp m + 1) = |c_{\mp}|^2 \Rightarrow$$

$$L_{\pm} |l, m\rangle = \hbar \sqrt{(l \mp m)(l \pm m + 1)} |l, m \pm 1\rangle$$

$\Uparrow$  project on  $|\vec{n}\rangle$  :

$$L_{\pm} Y_e^m(\theta, \varphi) = \hbar \sqrt{(l \mp m)(l \pm m + 1)} Y_e^{m \pm 1}(\theta, \varphi)$$

Morning coffee exercise (Sakurai, p. 200) <sup>red edition</sup> :

$$L_+ = -i\hbar e^{i\varphi} \left[ i \frac{\partial}{\partial \theta} - \cot \theta \frac{\partial}{\partial \varphi} \right] \leftarrow \text{show!}$$

Then,  $L_+ |l, l\rangle = 0 \Leftrightarrow L_+ Y_e^l(\theta, \varphi) = 0 =$

differential equation  $\rightarrow$  can solve for  $Y_e^l$

show that  $Y_l^l(\theta, \varphi) = C_l e^{il\varphi} \sin^l \theta$  (Sakurai 3.6.34) (4)

Apply  $L_- |l, l\rangle \Rightarrow |l, m-1\rangle$

show that  $\Leftarrow Y_l^{m-1}(\theta, \varphi)$

$$Y_l^m(\theta, \varphi) = \frac{(-1)^l}{2^l l!} \sqrt{\frac{2l+1}{4\pi} \frac{(l+m)!}{(l-m)!}} e^{im\varphi} \frac{1}{\sin^m \theta}$$

$P_l^m(\cos\theta)$   
 associated Legendre polynomials.  
 and  $Y_l^m(\theta, \varphi) = (-1)^m [Y_l^{-m}(\theta, \varphi)]^*$

$$\frac{d^{l-m}}{d(\cos\theta)^{l-m}} (\sin\theta)^{2l} \quad \text{at } m > 0$$

Summary: a state  $|l, m\rangle$  is an eigenstate of  $L^2$  and  $L_z$ , where  $l \geq 0$  and  $|m| \leq l$

Still need to figure out

why  $\lambda = \hbar^2 l(l+1)$   
 from dimensionality?

integer  $\Rightarrow l$  is integer

Lectures # 1 and 2

Consider an arbitrary eigenstate of  $\vec{J}^2$  and  $J_z$  (2)

$|j, m_j\rangle$

not necessarily  $\Rightarrow$  generalised angular momentum  
 orbital angular momentum  $\uparrow$  angular momentum

Apply  $J_z J_+ |j, m_j\rangle = (J_+ J_z + \hbar J_+) |j, m_j\rangle =$   
 $= J_+ \hbar m_j |j, m_j\rangle + \hbar J_+ |j, m_j\rangle =$   
 $= \hbar (m_j + 1) J_+ |j, m_j\rangle$

Also,  $J_z^2 J_+ |j, m_j\rangle = J_+ J_z^2 |j, m_j\rangle =$   
 $= \hbar^2 j(j+1) J_+ |j, m_j\rangle$

let's say this is  $\lambda$

$C_+ |j, m_j + 1\rangle$

say, we don't know that

Consider  $\langle j, m_j | J_z^2 - J_z^2 |j, m_j\rangle = \lambda = j(j+1)$

$= \langle j, m_j | J_x^2 + J_y^2 |j, m_j\rangle \geq 0 \Rightarrow \lambda - m_j^2 \geq 0$

then, there is  $\Leftarrow \lambda \geq m_j^2$   
 some  $m_j^{\max}$  for which

$J_+ |j, m_j^{\max}\rangle = 0$

Since  $J_- J_+ = J^2 - J_z^2 - \hbar J_z \Rightarrow$

$$J_- (J_+ |j, m_j^{\max}\rangle) = 0 \Rightarrow$$

$$(\vec{J}^2 - J_z^2 - \hbar J_z) |j, m_j^{\max}\rangle = 0 \Rightarrow$$

$$\hbar^2 (\lambda - m_j^{\max} - m_j^{\max}) |j, m_j^{\max}\rangle = 0$$

$$\Downarrow$$

$$\lambda = m_j^{\max} (m_j^{\max} + 1)$$

Similarly,  $J_- |j, m_j^{\min}\rangle = 0 \Rightarrow$

$$J_+ (J_- |j, m_j^{\min}\rangle) = 0 \Rightarrow$$

$$(\vec{J}^2 - J_z^2 + \hbar J_z) |j, m_j^{\min}\rangle = 0 \Rightarrow$$

$$\hbar^2 (\lambda - m_j^{\min} + m_j^{\min}) |j, m_j^{\min}\rangle = 0 \Rightarrow$$

$$\lambda = m_j^{\min} (m_j^{\min} - 1)$$

Since  $m_j^{\max} (m_j^{\max} + 1) = m_j^{\min} (m_j^{\min} - 1) \Rightarrow$

$$\underline{m_j^{\max} = -m_j^{\min}}$$

To get from  $|j, m_j^{\max}\rangle$  to  $|j, m_j^{\min}\rangle$  by

$\psi^* \psi = J_- \Rightarrow$  takes  $2m_j \Rightarrow K$  steps  $\uparrow$   $(+)$

Then,  $\lambda = m_j^{\max} (m_j^{\max} + 1) = \frac{K}{2} (\frac{K}{2} + 1)$

$0, 1, 2, \dots$

Note that  $m_j^{\max} = \frac{K}{2} = 0, \frac{1}{2}, 1, \dots$

$j = m_j^{\max} \leftarrow$  can be integer or half-integer

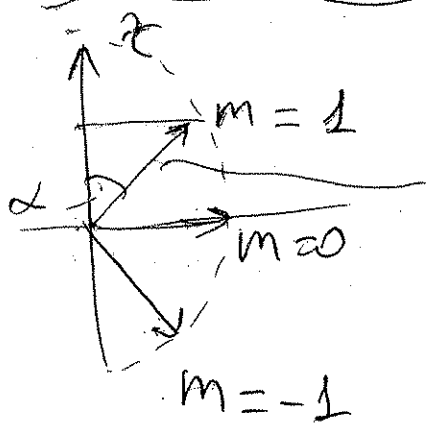
If  $j \equiv l \Rightarrow m_l$  is integer  $\Rightarrow l$  is integer

$\uparrow$  orbital angular momentum  $\lambda = l(l+1)$

If  $j \equiv s \Rightarrow m_s$  can be half-integer

$\uparrow$  spin angular momentum (e.g. for  $s = \frac{1}{2}$  particles  $m_s = \pm \frac{1}{2}$ )

### Geometrical interpretation of $|l, m\rangle$



Example:  $l=1, m=-1, 0, 1$

$|\vec{L}| = \hbar \sqrt{l(l+1)}$

note:  $|L_z| < |\vec{L}| \Rightarrow$

$\uparrow$   
 $m^2 < l(l+1)$

So there is a minimum angle between  $\vec{L}$  and z-axis  $\Rightarrow \cos \alpha = \frac{L_z}{|\vec{L}|} = \frac{M_{max}}{\sqrt{l(l+1)}} = \frac{l}{\sqrt{l(l+1)}}$

$$\vec{L} \text{ and } z\text{-axis} \Rightarrow \cos \alpha = \frac{L_z}{|\vec{L}|} = \frac{M_{max}}{\sqrt{l(l+1)}} = \frac{l}{\sqrt{l(l+1)}}$$

$$\downarrow = \frac{l}{\sqrt{l(l+1)}}$$

This is a consequence of the uncertainty principle

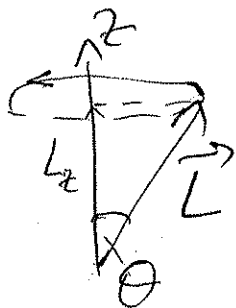
if  $\vec{L}$  were parallel to z-axis  $\Rightarrow$

$$L_x = L_y = 0, L_z = \pm \hbar l \Rightarrow \text{we would}$$

know all three components of  $\vec{L}$  simultaneously

Which is impossible, since  $[L_i, L_j] \neq 0!$  ( $i \neq j$ )

Instead, if we know  $L^2$  and  $L_z \Rightarrow$  we can't know  $L_x$  and  $L_y$  with absolute precision  $\Rightarrow$  geometrical interpretation is that  $\vec{L}$  precesses around z-axis at a constant angle  $\theta$ , which keeps  $L_z$  constant, but has  $L_x, L_y$  oscillating  $\Rightarrow \langle L_x \rangle = \langle L_y \rangle = 0$ , but  $\langle L_x^2 \rangle = \langle L_y^2 \rangle \neq 0!$



show this in HW #3 (Sawai 3.16)