

$$\vec{R}_{CM} \equiv \frac{m_1}{M} \vec{r}_1 + \frac{m_2}{M} \vec{r}_2 + \frac{m_3}{M} \vec{r}_3 + \dots = \sum_n \frac{m_n}{M} \vec{r}_n \quad \vec{L} = \vec{r} \times \vec{p}; \quad \vec{\tau} = \vec{r} \times \vec{F}$$

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{\ell^2}{2\mu r^2} + V(r) \quad \vec{f}(r) \hat{r} = \mu \frac{d^2 \vec{r}}{dt^2} = \mu(\ddot{r} - r\dot{\phi}^2) \hat{r} + \mu(r\ddot{\phi} + 2\dot{r}\dot{\phi}) \hat{\phi}$$

$$r(\phi) = \frac{\alpha}{1 + \epsilon \cos \phi}$$

$$\mathbf{r} = r \sin \theta \cos \phi \mathbf{i} + r \sin \theta \sin \phi \mathbf{j} + r \cos \theta \mathbf{k} \quad \hat{\theta} = \cos \theta \cos \phi \mathbf{i} + \cos \theta \sin \phi \mathbf{j} - \sin \theta \mathbf{k}$$

$$\hat{r} = \sin \theta \cos \phi \mathbf{i} + \sin \theta \sin \phi \mathbf{j} + \cos \theta \mathbf{k} \quad \hat{\phi} = -\sin \phi \mathbf{i} + \cos \phi \mathbf{j}$$

$$-\frac{\hbar^2}{2\mu} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right] \psi(r, \theta, \phi) + V(r) \psi(r, \theta, \phi) = E \psi(r, \theta, \phi)$$

$$\psi_{n\ell m}(r, \theta, \phi) = R_{n\ell}(r) \Theta_{\ell}^m(\theta) \Phi_m(\phi) = R_{n\ell}(r) Y_{\ell}^m(\theta, \phi)$$

$$\psi(r, \theta, \phi, t) = \sum_{n\ell m} c_{n\ell m} R_{n\ell}(r) Y_{\ell}^m(\theta, \phi) e^{-iE_n t/\hbar}$$

$$L_x \doteq i\hbar \left(\sin \phi \frac{\partial}{\partial \theta} + \cos \phi \cot \theta \frac{\partial}{\partial \phi} \right) \quad L_z \doteq -i\hbar \frac{\partial}{\partial \phi}$$

$$L_y \doteq i\hbar \left(-\cos \phi \frac{\partial}{\partial \theta} + \sin \phi \cot \theta \frac{\partial}{\partial \phi} \right) \quad L^2 \doteq -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right]$$

$$H_{ring} = \frac{L_z^2}{2I} \quad H_{sphere} = \frac{L^2}{2I} \quad \Phi_m(\phi) = \frac{1}{\sqrt{2\pi}} e^{im\phi}$$

ℓ	m	$Y_{\ell}^m(\theta, \phi)$
0	0	$Y_0^0 = \sqrt{\frac{1}{4\pi}}$
1	0	$Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta$
	± 1	$Y_1^{\pm 1} = \mp \sqrt{\frac{3}{8\pi}} \sin \theta e^{\pm i\phi}$
2	0	$Y_2^0 = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$
	± 1	$Y_2^{\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\phi}$
	± 2	$Y_2^{\pm 2} = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{\pm i2\phi}$
3	0	$Y_3^0 = \sqrt{\frac{7}{16\pi}} (5 \cos^3 \theta - 3 \cos \theta)$
	± 1	$Y_3^{\pm 1} = \mp \sqrt{\frac{21}{64\pi}} \sin \theta (5 \cos^2 \theta - 1) e^{\pm i\phi}$
	± 2	$Y_3^{\pm 2} = \sqrt{\frac{105}{32\pi}} \sin^2 \theta \cos \theta e^{\pm i2\phi}$
	± 3	$Y_3^{\pm 3} = \sqrt{\frac{35}{64\pi}} \sin^3 \theta e^{\pm i3\phi}$

$$E_n = -\frac{1}{n^2} \frac{Z^2 e^4 m_e}{2(4\pi\epsilon_0 \hbar)^2} = -\frac{1}{n^2} \frac{1}{2} \alpha^2 m_e c^2; \quad n=1,2,3\dots$$

$$V(r) = -\frac{Ze^2}{4\pi\epsilon_0 r} \quad a_0 = \frac{4\pi\epsilon_0 \hbar^2}{m_e e^2} \quad \alpha = \frac{e^2}{4\pi\epsilon_0 \hbar c}$$

$$\begin{aligned} \psi_{100}(r, \theta, \phi) &= \frac{1}{\sqrt{\pi}} \left(\frac{Z}{a_0} \right)^{3/2} e^{-Zr/a_0} \\ \psi_{200}(r, \theta, \phi) &= \frac{1}{\sqrt{\pi}} \left(\frac{Z}{2a_0} \right)^{3/2} \left[1 - \frac{Zr}{2a_0} \right] e^{-Zr/2a_0} \\ \psi_{210}(r, \theta, \phi) &= \frac{1}{2\sqrt{\pi}} \left(\frac{Z}{2a_0} \right)^{3/2} \frac{Zr}{a_0} e^{-Zr/2a_0} \cos\theta \\ \psi_{21,\pm 1}(r, \theta, \phi) &= \mp \frac{1}{2\sqrt{2\pi}} \left(\frac{Z}{2a_0} \right)^{3/2} \frac{Zr}{a_0} e^{-Zr/2a_0} \sin\theta e^{\pm i\phi} \\ \psi_{300}(r, \theta, \phi) &= \frac{1}{\sqrt{\pi}} \left(\frac{Z}{3a_0} \right)^{3/2} \left[1 - \frac{2Zr}{3a_0} + \frac{2}{27} \left(\frac{Zr}{a_0} \right)^2 \right] e^{-Zr/3a_0} \\ \psi_{310}(r, \theta, \phi) &= \frac{2\sqrt{2}}{3\sqrt{3\pi}} \left(\frac{Z}{3a_0} \right)^{3/2} \frac{Zr}{a_0} \left(1 - \frac{Zr}{6a_0} \right) e^{-Zr/3a_0} \cos\theta \\ \psi_{31,\pm 1}(r, \theta, \phi) &= \mp \frac{2}{3\sqrt{3\pi}} \left(\frac{Z}{3a_0} \right)^{3/2} \frac{Zr}{a_0} \left(1 - \frac{Zr}{6a_0} \right) e^{-Zr/3a_0} \sin\theta e^{\pm i\phi} \\ \psi_{320}(r, \theta, \phi) &= \frac{1}{27\sqrt{2\pi}} \left(\frac{Z}{3a_0} \right)^{3/2} \left(\frac{Zr}{a_0} \right)^2 e^{-Zr/3a_0} (3\cos^2\theta - 1) \\ \psi_{32,\pm 1}(r, \theta, \phi) &= \mp \frac{\sqrt{3}}{27\sqrt{\pi}} \left(\frac{Z}{3a_0} \right)^{3/2} \left(\frac{Zr}{a_0} \right)^2 e^{-Zr/3a_0} \sin\theta \cos\theta e^{\pm i\phi} \\ \psi_{32,\pm 2}(r, \theta, \phi) &= \frac{\sqrt{3}}{54\sqrt{\pi}} \left(\frac{Z}{3a_0} \right)^{3/2} \left(\frac{Zr}{a_0} \right)^2 e^{-Zr/3a_0} \sin^2\theta e^{\pm i2\phi} \end{aligned}$$

$$\int x e^{-x} dx = -x e^{-x} - e^{-x}$$

$$\int_0^\infty x^n e^{-ax} dx = \frac{n!}{a^{n+1}}$$

$$\int x^2 e^{-x} dx = -x^2 e^{-x} - 2x e^{-x} - 2e^{-x}$$

$$\int x^3 e^{-x} dx = -x^3 e^{-x} - 3x^2 e^{-x} - 6x e^{-x} - 6e^{-x}$$

$$\int x^4 e^{-x} dx = -x^4 e^{-x} - 4x^3 e^{-x} - 12x^2 e^{-x} - 24x e^{-x} - 24e^{-x}$$

$$\int \cos^4 x dx = \frac{3}{8}x + \frac{1}{4}\sin 2x + \frac{1}{32}\sin 4x$$