

$$\rho = \frac{m}{V} \quad P = \frac{F}{A} \quad P = P_0 + \rho gh \quad B = \rho Vg \quad Av = \text{constant}$$

$$P + \frac{1}{2}\rho v^2 + \rho gy = \text{constant} \quad y(x,t) = A \sin(kx - \omega t) \quad k = \frac{2\pi}{\lambda}$$

$$\omega = \frac{2\pi}{T} = 2\pi f \quad v = \frac{\omega}{k} = \frac{\lambda}{T} = \lambda f \quad v = \sqrt{\frac{T}{\mu}} \quad v = \sqrt{\frac{B}{\rho}}$$

$$f' = f \frac{v \pm v_o}{v \mp v_s} \quad f_b = |f_1 - f_2|$$

$$\lambda_n = \frac{2L}{n} \quad f_n = \frac{v}{\lambda_n} = n \frac{v}{2L}, \quad n = 1, 2, 3, \dots \quad f_n = \frac{v}{\lambda_n} = n \frac{v}{4L}, \quad n = 1, 3, 5, \dots$$

$$T_C = T - 273.15 \quad T_F = \frac{9}{5}T_C + 32^\circ F \quad \Delta L = \alpha L_i \Delta T \quad \Delta V = \beta V_i \Delta T$$

$$PV = nRT \quad Q = C\Delta T \quad Q = mc\Delta T \quad Q = mL$$

$$W = \int_{V_i}^{V_f} PdV \quad \Delta E_{\text{int}} = Q - W$$

$$Q = nC_V \Delta T \quad Q = nC_P \Delta T \quad \Delta E_{\text{int}} = nC_V \Delta T$$

$$C_P - C_V = R \quad PV^\gamma = \text{constant} \quad \gamma = \frac{C_P}{C_V}$$

$$e = \frac{W}{Q_h} = 1 - \frac{Q_c}{Q_h} \quad e_C = 1 - \frac{T_c}{T_h}$$

$$COP = \frac{Q_c}{W} \quad COP_C = \frac{T_c}{T_h - T_c} \quad \Delta S = \int_i^f \frac{dQ_r}{T} \quad \Delta S \geq 0$$

$$F_e = k_e \frac{|q_1||q_2|}{r^2} \quad \vec{\mathbf{E}} = \frac{\vec{\mathbf{F}}_e}{q_0} \quad \vec{\mathbf{E}} = k_e \frac{q}{r^2} \hat{\mathbf{r}} \quad \vec{\mathbf{E}} = k_e \sum_{i=1}^n \frac{q_i}{r_i^2} \hat{\mathbf{r}}_i = k_e \int \frac{dq}{r^2} \hat{\mathbf{r}}$$

$$\vec{\mathbf{F}}_e = q \vec{\mathbf{E}} \quad \Delta V = \frac{\Delta U}{q_0} \quad \Delta V = V_B - V_A = - \int_A^B \vec{\mathbf{E}} \bullet d\vec{s} \quad V = k_e \frac{q}{r}$$

$$V = k_e \sum_{i=1}^n \frac{q_i}{r_i} = k_e \int \frac{dq}{r}$$

$$U = k_e \frac{q_1 q_2}{r} \quad C = \frac{Q}{\Delta V} \quad E_x = - \frac{\partial V}{\partial x} \quad E_y = - \frac{\partial V}{\partial y} \quad E_z = - \frac{\partial V}{\partial z}$$

$$C_{\text{eq}} = C_1 + C_2 + C_3 + \dots \quad \frac{1}{C_{\text{eq}}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots$$

$$U = \frac{Q^2}{2C} = \frac{1}{2}C(\Delta V)^2 \quad C = \kappa C_0$$

$$I = \frac{dQ}{dt} \quad R = \frac{\ell}{\sigma A} = \frac{\Delta V}{I} \quad \rho = \frac{1}{\sigma} \quad \mathcal{P} = I\Delta V$$

$$\mathcal{P} = I^2 R = \frac{(\Delta V)^2}{R} \quad R_{\text{eq}} = R_1 + R_2 + R_3 + \dots \quad \frac{1}{R_{\text{eq}}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots$$

$$q = C\mathcal{E}(1 - e^{-t/RC}) \quad I = \frac{\mathcal{E}}{R} e^{-t/RC} \quad q = Qe^{-t/RC} \quad I = -\frac{Q}{RC} e^{-t/RC}$$