

$$v = \frac{dx}{dt}$$

$$a = \frac{dv}{dt}$$

$$x = x_0 + v_0 t + \frac{1}{2} a t^2$$

$$v = v_0 + at$$

$$v^2 = v_0^2 + 2a(x - x_0)$$

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\vec{v} = \frac{d\vec{r}}{dt}$$

$$\vec{a} = \frac{d\vec{v}}{dt}$$

$$\vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$\vec{v} = \vec{v}_0 + \vec{a} t$$

$$ax^2 + bx + c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\vec{a} \cdot \vec{b} = ab \cos \phi$$

$$\cos(90^\circ + \phi) = -\sin \phi$$

$$a_R = \frac{v^2}{r}$$

$$\sum \vec{F} = m\vec{a}$$

$$\vec{F}_{12} = -\vec{F}_{21}$$

$$\vec{F}_G = m\vec{g}$$

$$F_{fr} = \mu_k F_N$$

$$F_{fr} \leq \mu_s F_N$$

$$a_{\tan} = \frac{dv}{dt}$$

$$F = G \frac{m_1 m_2}{r^2}$$

$$\vec{F}_{12} = -G \frac{m_1 m_2}{r_{21}^2} \hat{r}_{21}$$

$$W = \vec{F} \cdot \vec{d} = \int \vec{F} \cdot d\vec{\ell}$$

$$F_S = -kx$$

$$W_s = \frac{1}{2} kx_i^2 - \frac{1}{2} kx_f^2$$

$$K = \frac{1}{2} mv^2$$

$$W_{net} = \frac{1}{2} mv_2^2 - \frac{1}{2} mv_1^2$$

$$U = mgy$$

$$U = \frac{1}{2} kx^2$$

$$\Delta U = U_2 - U_1 = -W = -\int_1^2 \vec{F} \cdot d\vec{\ell}$$

$$F(x) = -\frac{dU(x)}{dx}$$

$$E = K + U$$

$$K_2 + U_2 = K_1 + U_1$$

$$\Delta K + \Delta U = W_{NC}$$

$$U = -\frac{Gm_1 m_2}{r}$$

$$\mathcal{P} = \frac{dW}{dt} = \vec{F} \cdot \vec{v}$$

$$\vec{p} = m\vec{v}$$

$$\sum \vec{F} = \frac{d\vec{p}}{dt}$$

$$\Delta \vec{p} = \vec{p}_f - \vec{p}_i = \int_{t_i}^{t_f} \vec{F} dt = \vec{J}$$

$$\vec{p}_1 + \vec{p}_2 = \vec{p}'_1 + \vec{p}'_2$$

$$\frac{d\vec{P}}{dt} = \sum \vec{F}_{\text{ext}}$$

$$x_{\text{CM}} = \frac{1}{M} \sum_{i=1}^n m_i x_i = \frac{1}{M} \int x dm$$

$$M\vec{a}_{\text{CM}} = \sum \vec{F}_{\text{ext}}$$