

# ***Least-Square Data Fitting***

data fitting = art worth serious study (not here)

seen: interpolate within a table

now: least-squares, “best” fit to data (search, matrices)

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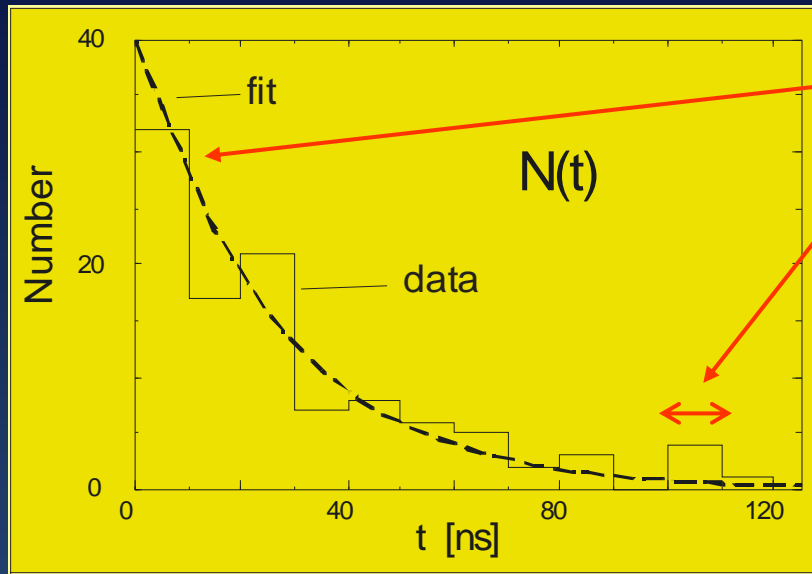
**Computational Physics for Undergraduates**

**BS Degree Program: Oregon State University**

***“Engaging People in Cyber Infrastructure”***

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# Problem: Fitting Exponential Decay

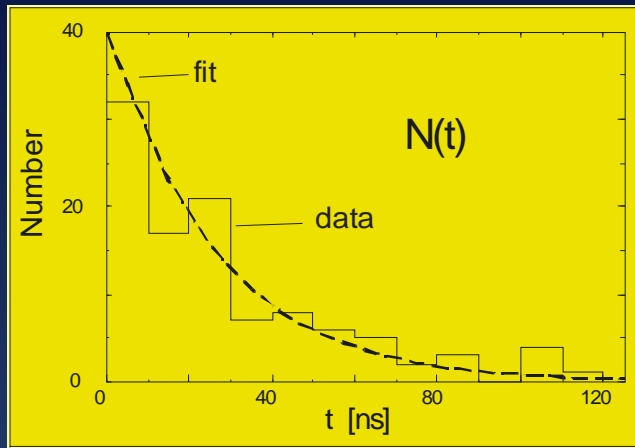


- Number =  $\Delta N$  = # of  $\pi$  meson decays
- Time in  $\Delta t = 10$  ns "bins"
- Curve = theoretical fit (your problem)
  - deduce  $\pi$  meson lifetime  $\tau$
  - tabulated  $\tau = 2.6 \cdot 10^{-8}$  s

- Theory: spontaneous decay (stochastic)
- Model: Exponential decay ( $\Delta t \rightarrow 0$ )

$$\frac{dN(t)}{dt} = \frac{dN(0)}{dt} e^{-t/\tau} \quad (1)$$

# Method: Least-Squares Fitting 1



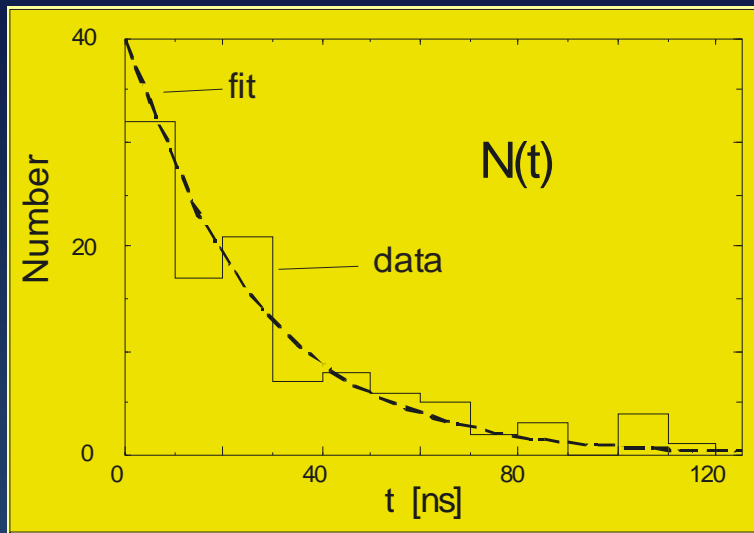
- Meaning "good" fit to data?
- Statistics = big subject (see refs)
- Three points to remember
  1. if errors, theory not pass through all
  2. if theory wrong, "best" fit terrible
  3. most best fits via search

**Theory**

$$\frac{dN(t)}{dt} = \frac{dN(0)}{dt} e^{-t/\tau} \quad (1)$$

- $y = g(x)$  describes data
- $g(x) = g(x, a_1, a_2, \dots, a_M) = g(x, \vec{a})$ 
  - $a_1, a_2, \dots, a_M$  = parameters, part of theory
  - $a_1$  = lifetime  $\tau$ ,  $a_2$  = initial rate  $dN(0)/dt$

# Least-Squares Fitting 2



$$\frac{dN(t)}{dt} = \frac{dN(0)}{dt} e^{-t/\tau} \quad (1)$$

1.  $y = g(x, a_1, a_2, \dots, a_M)$  = Eq.(1) describes data
2. Given:  $N_D$  data values
3.  $(x_i, y_i \pm \sigma_i)$ ,  $i = 1, N_D = \#$  data points
4.  $y_i$  = independent variable:  $t$
5.  $x_i$  = dependent variable:  $\Delta N(t)$
6.  $\pm \sigma_i$  = uncertainty ("error") in  $y_i$

# $\chi^2$ = Measure of Goodness (the “square”)

$$\chi^2 \stackrel{\text{def}}{=} \sum_{i=1}^{N_D} \left[ \frac{y_i - g(x_i, \vec{a})}{\sigma_i} \right]^2 \quad (2)$$

- $\chi^2$  = summed squares deviations of data from  $g(x)$
- $\Rightarrow$  smaller  $\chi^2 \Rightarrow$  better fit
- $1/\sigma_i^2$  = weighting  $\Rightarrow$  large errors contribute least
- Least-squares = “best” fit
- “Fit” = adjust  $\mathbf{a}_i \Rightarrow$  minimum  $\chi^2$  (the “least”)
- Determine parameters in theory
- $\chi^2 \cong N_D - M_P = \#$  degrees freedom, good
- Good fit: misses  $\sim 1/3$  points
- $\chi^2 = 0 \Rightarrow$  theory passes thru all data points

# Equations for Best Fit

$$\chi^2 \stackrel{\text{def}}{=} \sum_{i=1}^{N_D} \left[ \frac{y_i - g(x_i, \vec{a})}{\sigma_i} \right]^2 \quad (1)$$

Solve for  $a_m$  that make  $\chi^2$  a minimum:

$$\frac{\partial \chi^2}{\partial a_m} = 0 \quad (m = 1, M_P) \quad (2)$$

$$\Rightarrow \sum_{i=1}^{N_D} \frac{[y_i - g(x_i)]}{\sigma_i^2} \frac{\partial g(x_i)}{\partial a_m} = 0 \quad (3)$$

- $\Rightarrow M_P$  simultaneous equations (nonlinear) in  $\mathbf{a}_m$
- Work them out for each case
- Solution: trial-and-error search in  $M_P$  dimensions
- Need check:  $\chi^2 = \text{minimum}$ , global minimum
- Different starting values  $\Rightarrow \Delta \text{ min}$

**Means**

# E.G. Linear Least-Square Fit

$$g(x; \vec{a}) = a_1 + a_2 x \quad (4)$$

- Fitted function  $g(x, \vec{a})$  linear in parameter  $\mathbf{a}_i$
- Here straight line too!
- Simple (analytic) solution ("Linear regression")
- $M_P = 2$  parameters: slope  $\mathbf{a}_2$ ,  $\mathbf{y}$  intercept  $\mathbf{a}_1$
- *N.B.* still  $N_D \geq M_P = 2$  of data points to fit
  - Unique solution: More data than unknowns
- Straight line (4)  $\Rightarrow$  2 derivatives for min  $\chi^2$ :

$$\frac{\partial g(x_i)}{\partial a_1} = 1, \quad \frac{\partial g(x_i)}{\partial a_2} = x_i \quad (5)$$

- Solve  $\chi^2$  minimization equations, ...

# E.G. Linear Least-Square Fit

$$g(x; \vec{a}) = a_1 + a_2 x \quad (6)$$

Solve  $\chi^2$  minimization equations (algebra):

$$a_1 = \frac{S_{xx} S_y - S_x S_{xy}}{\Delta}, \quad a_2 = \frac{S S_{xy} - S_x S_y}{\Delta} \quad (7)$$

$$S = \sum_{i=1}^{N_D} \frac{1}{\sigma_i^2}, \quad S_x = \sum_{i=1}^{N_D} \frac{x_i}{\sigma_i^2}, \quad (8)$$

$$S_{xy} = \sum_{i=1}^{N_D} \frac{x_i y_i}{\sigma_i^2}, \quad \Delta = S S_{xx} - S_x^2 \quad (9)$$

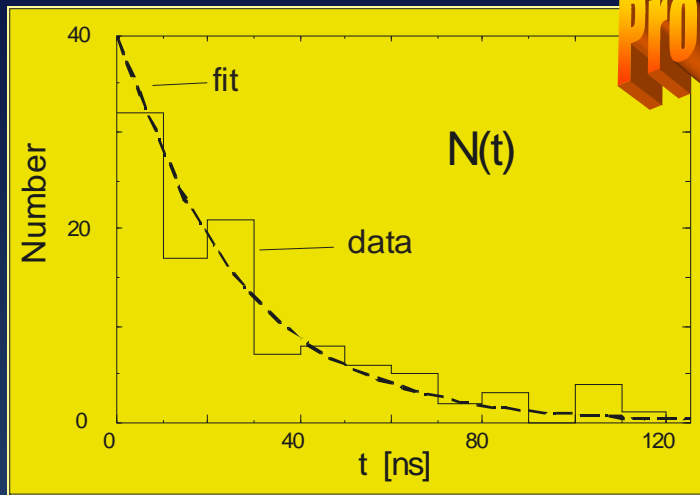
Variance = uncertainty in parameters

$$\sigma_{a_1}^2 = \frac{S_{xx}}{\Delta}, \quad \sigma_{a_2}^2 = \frac{S}{\Delta} \quad (10)$$



**Good Time for a Break**

# Assessment: Fit to Exponential Decay



1. Fit exponential decay law to data in Fig
2. Find best values for  $dN/dt(0)$  and  $\tau$
3. Judge how good the fit is

1. Construct table  $(\Delta N_i, \Delta t_i)$  from figure
2. Estimate error  $\sigma_i$  by "eye" or  $\sqrt{N_i}$
3. Fit the semilog plot

$$(1) \quad \frac{dN(t)}{dt} = \frac{dN(0)}{dt} e^{-t/\tau}$$

$$\ln \left| \frac{\Delta N(t)}{\Delta t} \right| \simeq -\frac{1}{\tau} \Delta t + \ln \left| \frac{\Delta N_0}{\Delta t} \right| \quad (2)$$

$$y = ax + b \quad (3)$$

4. Plot best fit with data and compare

## Extension: Linear Quadratic Fit

$$g(x) = a_1 + a_2x + a_3x^2 \quad (1)$$

- Recall: *linear* fit  $\Rightarrow$  linear in parameters  $a_i$  not straight line!
- Nonlinear:  $\mathbf{g}(\mathbf{x}) = (a_1 + a_2\mathbf{x}) e^{a\mathbf{x}}$
- Parabola:  $\min \chi^2 \Rightarrow 3$  simultaneous equations

$$\sum_{i=1}^{N_D} \frac{[y_i - g(x_i)]}{\sigma_i^2} \frac{\partial g(x_i)}{\partial a_1} = 0, \quad \frac{\partial g}{\partial a_1} = 1, \quad (2)$$

$$\sum_{i=1}^{N_D} \frac{[y_i - g(x_i)]}{\sigma_i^2} \frac{\partial g(x_i)}{\partial a_2} = 0, \quad \frac{\partial g}{\partial a_2} = x, \quad (3)$$

$$\sum_{i=1}^{N_D} \frac{[y_i - g(x_i)]}{\sigma_i^2} \frac{\partial g(x_i)}{\partial a_3} = 0, \quad \frac{\partial g}{\partial a_3} = x^2. \quad (4)$$

# Solution: Linear Quadratic Fit

$$g(x) = a_1 + a_2x + a_3x^2 \quad (1)$$

3 eqs, 3 unknowns

$$S a_1 + S_x a_2 + S_{xx} a_3 = S_y, \quad (2)$$

$$S_x a_1 + S_{xx} a_2 + S_{xxx} a_3 = S_{xy}, \quad (3)$$

$$S_{xx} a_1 + S_{xxx} a_2 + S_{xxxx} a_3 = S_{xxy} \quad (4)$$

$$e.g. \quad S_{xy} = \sum_{i=1}^{N_D} \frac{x_i y_i}{\sigma_i^2} \quad (5)$$

JamaFit.java

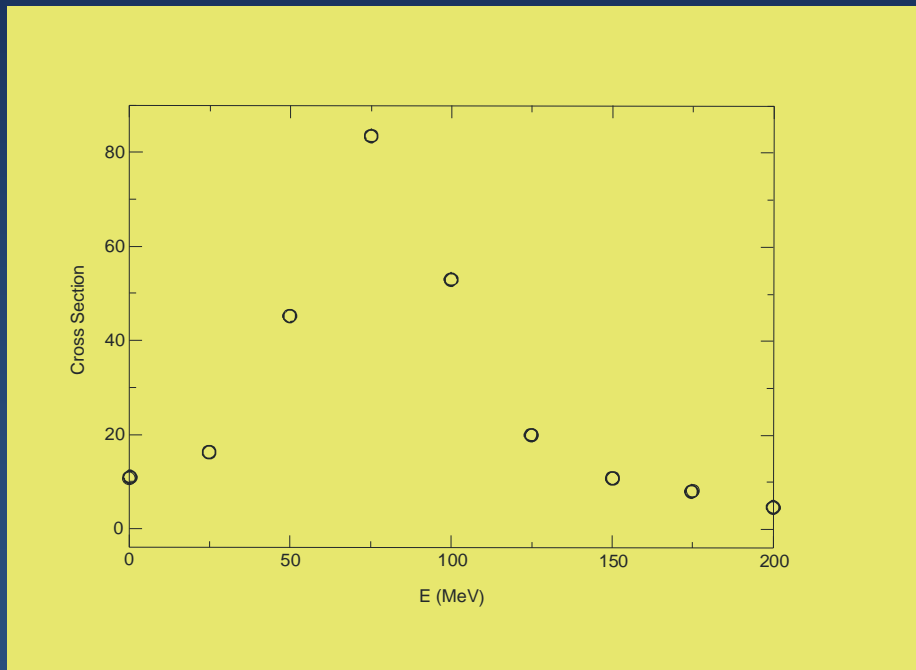
$$[\alpha] \vec{a} = \vec{\beta} \quad (6)$$

$$[\alpha] = \begin{bmatrix} S & S_x & S_{xx} \\ S_x & S_{xx} & S_{xxx} \\ S_{xx} & S_{xxx} & S_{xxxx} \end{bmatrix} \quad (7)$$

$$\vec{a} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}, \quad \vec{\beta} = \begin{bmatrix} S_y \\ S_{xy} \\ S_{xxy} \end{bmatrix} \quad (8)$$

# Nonlinear Fit to Cross Section (challenge)

$i$	1	2	3	4	5	6	7	8	9
$E_i$	0	25	50	75	100	125	150	175	200
$f(E_i)$	10.6	16.0	45.0	83.5	52.8	19.9	10.8	8.25	4.70
$+-\sigma_i$	9.34	17.9	41.5	85.5	51.5	21.5	10.8	6.29	4.14



$$f(E) = \frac{f_r}{(E - E_r)^2 + \Gamma^2/4}$$

- 3 parameters (OK)
- Non linear in  $E$  (hard)
- Newton-Raphson Search