

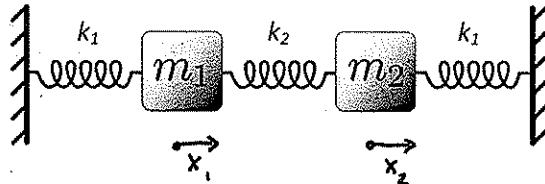
PHY 427 Worksheet Activity #1 – Differential Equations for Coupled Systems

Figures below depict five different systems of particles. For each system, write down differential equations of motion by inspection. Assume that the masses experience only a small perturbation in their position.

System 1:

$$m_1 \ddot{x}_1 = -k_1 x_1 + k_2 (x_2 - x_1)$$

$$m_2 \ddot{x}_2 = -k_1 x_2 + k_2 (x_1 - x_2)$$

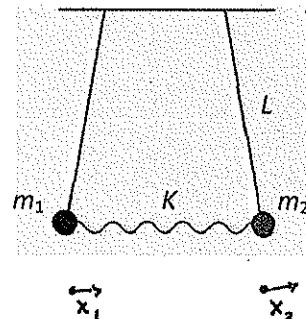


Trick: if the system is symmetric swapping $x_1 \leftrightarrow x_2$ must give you the second equation

System 2:

$$m_1 \ddot{x}_1 = -\frac{mg}{l} x_1 - K x_1 + K x_2 = -\frac{mg}{l} x_1 - K(x_1 - x_2)$$

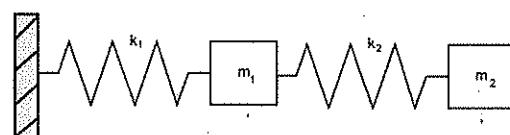
$$m_2 \ddot{x}_2 = -\frac{mg}{l} x_2 - K x_2 + K x_1 = -\frac{mg}{l} x_2 - K(x_2 - x_1)$$



System 3:

$$m_1 \ddot{x}_1 = -K_1 x_1 + K_2 (x_2 - x_1)$$

$$m_2 \ddot{x}_2 = -K_2 x_2 + K_1 x_1 = -K_2 (x_2 - x_1)$$



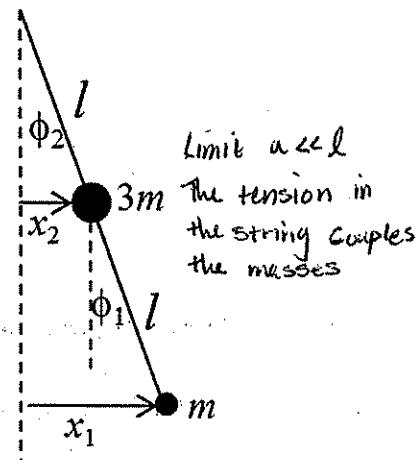
Recall one pendulum is $m\ddot{x} = \frac{mg}{l}x$

System 4:

$$m\ddot{x}_1 = \frac{mg}{l}(x_2 - x_1)$$

$$3m\ddot{x}_2 = \frac{mg}{l}(x_1 - x_2) - \frac{4mg}{l}x_2$$

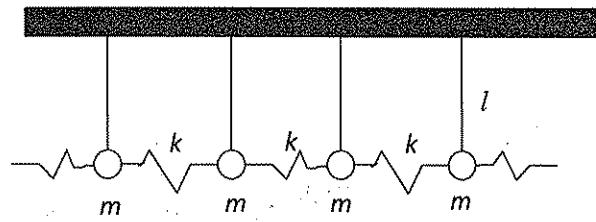
restoring tension in
1st length of string
is $\sim 4mg$



System 5:

$$m\ddot{x}_n = -\frac{mg}{l}x_n - K(x_n - x_{n-1}) + \dots$$

$$m\ddot{x}_{n+1} = \rightarrow \text{exercise for you} \leftarrow$$



System 6:

$$m\ddot{x}_1 = -K(x_1 - x_2) + K(x_3 - x_1)$$

$$m\ddot{x}_2 = +K(x_1 - x_2) - K(x_2 - x_3)$$

$$m\ddot{x}_3 = +K(x_2 - x_3) - K(x_3 - x_1)$$

