

White board activity

- Find $\langle S_x \rangle$

- $\langle S_y \rangle$

- And $\langle S_z \rangle$

- For the general state $|\psi(t)\rangle \doteq e^{-i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i(\omega_0 t + \phi)} \sin \frac{\theta}{2} \end{pmatrix}$

Expectation Value of Spin Angular Momentum:

$$\begin{aligned}\langle S_z \rangle &= \left(+\frac{\hbar}{2} \right) P(+)+ \left(-\frac{\hbar}{2} \right) P(-) = \langle \psi(t) | S_z | \psi(t) \rangle \\ &= e^{i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} & e^{-i(\phi+\omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} e^{-i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i(\phi+\omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \\ &= \frac{\hbar}{2} \begin{pmatrix} \cos \frac{\theta}{2} & e^{-i(\phi+\omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} \\ -e^{i(\phi+\omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \\ &= \frac{\hbar}{2} \left[\cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} \right] = \frac{\hbar}{2} \cos \theta\end{aligned}$$

$$\begin{aligned}
\langle S_x \rangle &= \langle \psi(t) | S_x | \psi(t) \rangle \\
&= e^{i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} & e^{-i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} e^{-i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \\
&= \frac{\hbar}{2} \begin{pmatrix} \cos \frac{\theta}{2} & e^{-i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \begin{pmatrix} e^{i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \\ \cos \frac{\theta}{2} \end{pmatrix} \\
&= \frac{\hbar}{2} \cos \frac{\theta}{2} \sin \frac{\theta}{2} \left[e^{i(\phi + \omega_0 t)} + e^{-i(\phi + \omega_0 t)} \right] = \frac{\hbar}{2} \sin \theta \cos(\phi + \omega_0 t)
\end{aligned}$$

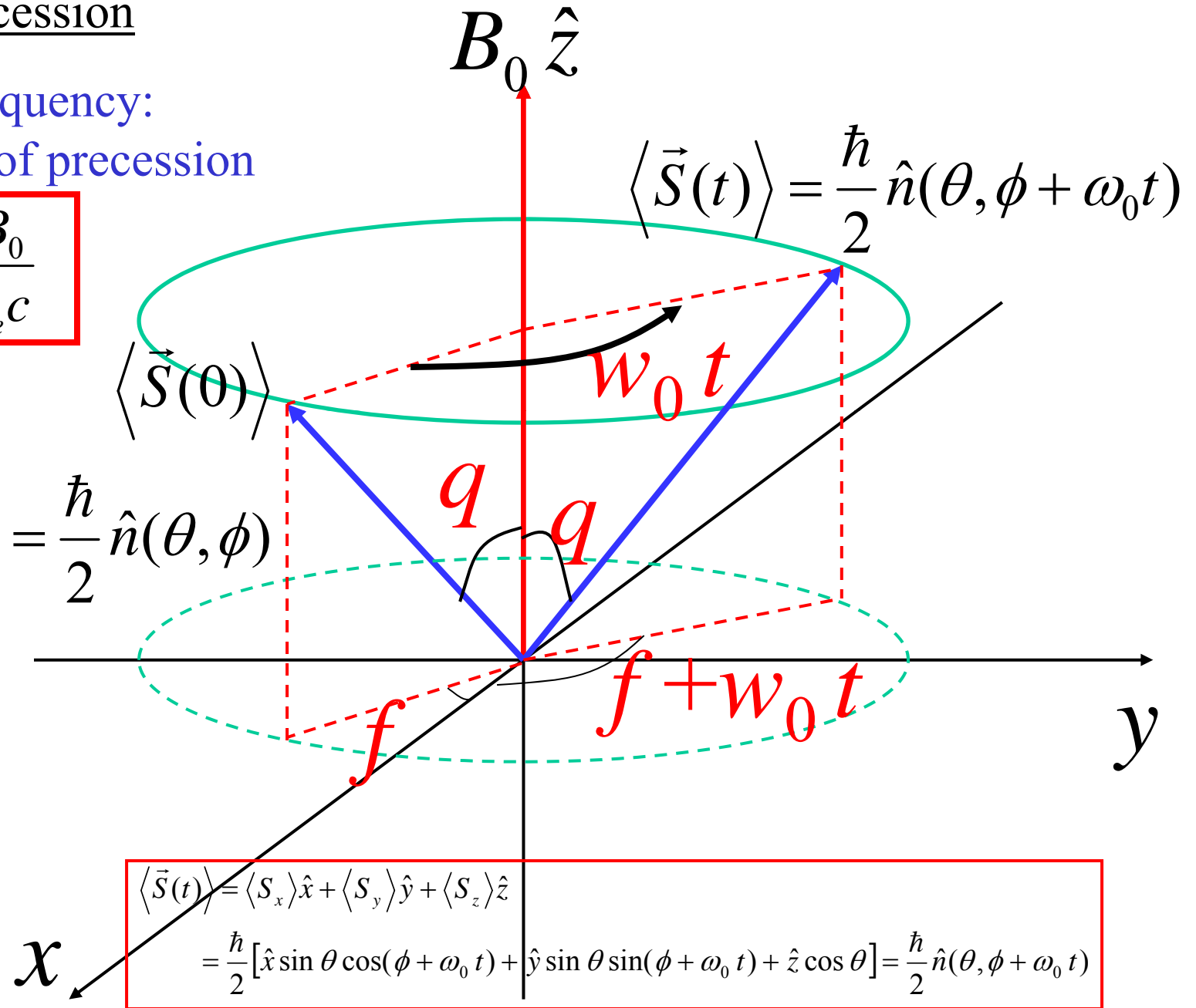
$$\begin{aligned}
\langle S_y \rangle &= \langle \psi(t) | S_y | \psi(t) \rangle \\
&= e^{i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} & e^{-i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} e^{-i\frac{\omega_0 t}{2}} \begin{pmatrix} \cos \frac{\theta}{2} \\ e^{i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \\
&= \frac{\hbar}{2} \begin{pmatrix} \cos \frac{\theta}{2} & e^{-i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \end{pmatrix} \begin{pmatrix} -ie^{i(\phi + \omega_0 t)} \sin \frac{\theta}{2} \\ i \cos \frac{\theta}{2} \end{pmatrix} \\
&= \frac{\hbar}{2} \cos \frac{\theta}{2} \sin \frac{\theta}{2} \left[-ie^{i(\phi + \omega_0 t)} + ie^{-i(\phi + \omega_0 t)} \right] = \frac{\hbar}{2} \sin \theta \sin(\phi + \omega_0 t)
\end{aligned}$$

$$\begin{aligned}
\langle \vec{S}(t) \rangle &= \langle S_x \rangle \hat{x} + \langle S_y \rangle \hat{y} + \langle S_z \rangle \hat{z} \\
&= \frac{\hbar}{2} \left[\hat{x} \sin \theta \cos(\phi + \omega_0 t) + \hat{y} \sin \theta \sin(\phi + \omega_0 t) + \hat{z} \cos \theta \right] = \frac{\hbar}{2} \hat{n}(\theta, \phi + \omega_0 t)
\end{aligned}$$

Spin Precession

Larmor frequency:
frequency of precession

$$\omega_0 = \frac{eB_0}{m_e c}$$



$$\begin{aligned}\langle \vec{S}(t) \rangle &= \langle S_x \rangle \hat{x} + \langle S_y \rangle \hat{y} + \langle S_z \rangle \hat{z} \\ &= \frac{\hbar}{2} [\hat{x} \sin \theta \cos(\phi + \omega_0 t) + \hat{y} \sin \theta \sin(\phi + \omega_0 t) + \hat{z} \cos \theta] = \frac{\hbar}{2} \hat{n}(\theta, \phi + \omega_0 t)\end{aligned}$$

What is $\langle S(t) \rangle$:

- if we start in a $|+\rangle_x$ state?
- If we start in a $|+\rangle_y$ state?
- If we start in a $|+\rangle$ state?

What does this mean?